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# VARIATIONAL METHODS AND LINEARIZATION TOOLS TOWARDS THE SPECTRAL ANALYSIS OF THE P-LAPLACIAN, ESPECIALLY FOR THE FREDHOLM ALTERNATIVE 

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These notes transcribe the plenary lecture at the conference and are written for advanced Ph. D. students

[^0]Abstract. We look for weak solutions $u \in W_{0}^{1, p}(\Omega)$ of the degenerate quasilinear Dirichlet boundary value problem

$$
\begin{equation*}
-\Delta_{p} u=\lambda|u|^{p-2} u+f(x) \quad \text { in } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{P}
\end{equation*}
$$

It is assumed that $1<p<\infty, p \neq 2, \Delta_{p} u \equiv \operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the $p$ Laplacian, $\Omega$ is a bounded domain in $\mathbb{R}^{N}, f \in L^{\infty}(\Omega)$ is a given function, and $\lambda$ stands for the (real) spectral parameter. Such weak solutions are precisely the critical points of the corresponding energy functional on $W_{0}^{1, p}(\Omega)$,

$$
\begin{equation*}
\mathcal{J}_{\lambda}(u) \stackrel{\text { def }}{=} \frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u \mathrm{~d} x, \quad u \in W_{0}^{1, p}(\Omega) . \tag{J}
\end{equation*}
$$

I.e., problem (P) is equivalent with $\mathcal{J}_{\lambda}^{\prime}(u)=0$ in $W^{-1, p^{\prime}}(\Omega)$. Here, $\mathcal{J}_{\lambda}^{\prime}(u)$ stands for the (first) Fréchet derivative of the functional $\mathcal{J}_{\lambda}$ on $W_{0}^{1, p}(\Omega)$ and $W^{-1, p^{\prime}}(\Omega)$ denotes the (strong) dual space of the Sobolev space $W_{0}^{1, p}(\Omega)$, $p^{\prime}=p /(p-1)$.

We will describe a global minimization method for this functional provided $\lambda<\lambda_{1}$, together with the (strict) convexity of the functional for $\lambda \leq 0$ and possible "nonconvexity" if $0<\lambda<\lambda_{1}$. As usual, $\lambda_{1}$ denotes the first (smallest) eigenvalue $\lambda_{1}$ of the positive $p$-Laplacian $-\Delta_{p}$. Strict convexity will force the uniqueness of a critical point (which is then the global minimizer for $\mathcal{J}_{\lambda}$ ), whereas "nonconvexity" will be shown by constructing a saddle point which is different from any local or global minimizer. These methods are well-known and can be found in many textbooks on Nonlinear Functional Analysis or Variational Calculus.

The problem becomes quite difficult if $\lambda=\lambda_{1}$ or $\lambda>\lambda_{1}$, even in space dimension one $(N=1)$. We will restrict ourselves to the case $\lambda=\lambda_{1}$, the Fredholm alternative for the p-Laplacian at the first eigenvalue. Even if the functional $\mathcal{J}_{\lambda_{1}}$ is no longer coercive on $W_{0}^{1, p}(\Omega)$, for $p>2$ we will show that it is bounded from below and does possess a global minimizer. For $1<p<2$ the functional $\mathcal{J}_{\lambda_{1}}$ is unbounded from below and one can find a pair of sub- and supersolutions to problem (P) by a variational method (a simplified minimax principle) performed in the orthogonal decomposition $W_{0}^{1, p}(\Omega)=\operatorname{lin}\left\{\varphi_{1}\right\} \oplus$ $W_{0}^{1, p}(\Omega)^{\top}$ induced by the inner product in $L^{2}(\Omega)$. First, the minimum is taken in $W_{0}^{1, p}(\Omega)^{\top}$, and then (possibly only local) maximum in $\operatorname{lin}\left\{\varphi_{1}\right\}$. The "sub-" and "supercritical" points thus obtained provide a pair of sub- and supersolutions to problem (P). Then a topological (Leray-Schauder) degree has to be employed to obtain a solution to problem (P) by a standard fixed point argument.

Finally, we will discuss the existence and multiplicity of a solution for problem (P) when $f$ "nearly" satisfies the orthogonality condition $\int_{\Omega} f \varphi_{1} \mathrm{~d} x=0$ and $\lambda<\lambda_{1}+\delta$ (with $\delta>0$ small enough). A crucial ingredient in our proofs are rather precise asymptotic estimates for possible "large" solutions to problem ( P ) obtained from the linearization of problem $(\mathrm{P})$ about the eigenfunction $\varphi_{1}$. These will be briefly discussed. Naturally, the (linear selfadjoint) Fredholm alternative for the linearization of problem (P) about $\varphi_{1}$ (with $\lambda=\lambda_{1}$ ) appears in the proofs.

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## 1. Introduction

In this lecture notes we will combine variational and topological methods to establish various results on existence (or nonexistence), uniqueness, and multiplicity of solutions corresponding to the Fredholm alternative for the nonlinear Dirichlet problem

$$
\begin{equation*}
-\Delta_{p} u=\lambda|u|^{p-2} u+f(x) \quad \text { in } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{1.1}
\end{equation*}
$$

with the $p$-Laplacian $\Delta_{p}$ defined by $\Delta_{p} u \stackrel{\text { def }}{=} \operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ for $p \in(1, \infty)$. Here, $\lambda \in \mathbb{R}$ is the spectral (control) parameter taking values near the first (smallest) eigenvalue $\lambda_{1}$ of $-\Delta_{p}$,

$$
\begin{equation*}
\lambda_{1}=\inf \left\{\int_{\Omega}|\nabla u|^{p} \mathrm{~d} x: u \in W_{0}^{1, p}(\Omega) \text { with } \int_{\Omega}|u|^{p} \mathrm{~d} x=1\right\} \tag{1.2}
\end{equation*}
$$

and $f \in L^{\infty}(\Omega)$ is a given function, $f \not \equiv 0$ in $\Omega$. Using a new variational method introduced in Takáč [32, 35] we will be able to show a number of results on the solvability of problem (1.1) under various conditions on $\lambda$ and $f$. We assume that $\Omega$ is a bounded domain in $\mathbb{R}^{N}(N \geq 1)$ with sufficiently smooth boundary $\partial \Omega ; C^{2}$ boundary will do. As far as conditions on $f$ are concerned, we will find it convenient to work with the orthogonal sum $L^{2}(\Omega)=\operatorname{lin}\left\{\varphi_{1}\right\} \oplus L^{2}(\Omega)^{\top}$, where

$$
\begin{equation*}
L^{2}(\Omega)^{\top} \stackrel{\text { def }}{=}\left\{f \in L^{2}(\Omega):\left\langle f, \varphi_{1}\right\rangle=0\right\}, \tag{1.3}
\end{equation*}
$$

$\left\langle f, \varphi_{1}\right\rangle \stackrel{\text { def }}{=} \int_{\Omega} f \varphi_{1} \mathrm{~d} x$, so that $f$ splits as $f=f^{\|} \cdot \varphi_{1}+f^{\top}$, where

$$
\begin{equation*}
f \stackrel{\| \text { def }}{=}\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{-2}\left\langle f, \varphi_{1}\right\rangle \quad \text { and }\left\langle f^{\top}, \varphi_{1}\right\rangle=0 \tag{1.4}
\end{equation*}
$$

Here, $\varphi_{1}$ denotes the eigenfunction associated with $\lambda_{1}$ which is a simple eigenvalue of $-\Delta_{p}$, by Anane [2, Théorème 1, p. 727] or Lindqvist [25, Theorem 1.3, p. 157].

We normalize $\varphi_{1}$ by $\varphi_{1}>0$ in $\Omega$ and $\left\|\varphi_{1}\right\|_{L^{p}(\Omega)}=1$. We have $\varphi_{1} \in L^{\infty}(\Omega)$ by Anane [3, Théorème A.1, p. 96]. More details about $\lambda_{1}$ and $\varphi_{1}$ will be presented in Section 5

We formulate our solvability conditions on $f$ in terms of $f^{\|}$and $f^{\top}$ where the ratio between $\left|f^{\|}\right|$and $\left\|f^{\top}\right\|_{L^{\infty}(\Omega)}$ plays a decisive role. For $\lambda$ near $\lambda_{1}$, say, $\left|\lambda-\lambda_{1}\right| \leq$ $\delta$, this ratio, combined with the signs of $\lambda-\lambda_{1}$ and $p-2$, determines the existence (or nonexistence) and multiplicity of weak solutions to problem (1.1) in $W_{0}^{1, p}(\Omega)$. It is not surprising that we look for solutions to 1.1) coming also in the form $u=u^{\|} \cdot \varphi_{1}+u^{\top}$ defined in (1.4). We will establish strong relations between $f^{\|}$ and $u^{\|}$, and $f^{\top}$ and $u^{\top}$, as well, for any $1<p<\infty$, in analogy with the case $p=2$ when these two relations are decoupled by the spectral decomposition of the (linear) Laplace operator $\Delta$ in $L^{2}(\Omega)$.

In accordance with 1.3 we write

$$
\begin{gathered}
L^{\infty}(\Omega)^{\top} \stackrel{\text { def }}{=}\left\{u \in L^{\infty}(\Omega):\left\langle u, \varphi_{1}\right\rangle=0\right\} \\
W_{0}^{1, p}(\Omega)^{\top} \stackrel{\text { def }}{=}\left\{u \in W_{0}^{1, p}(\Omega):\left\langle u, \varphi_{1}\right\rangle=0\right\}
\end{gathered}
$$

and take advantage of the orthogonal sums

$$
L^{\infty}(\Omega)=\operatorname{lin}\left\{\varphi_{1}\right\} \oplus L^{\infty}(\Omega)^{\top}, \quad W_{0}^{1, p}(\Omega)=\operatorname{lin}\left\{\varphi_{1}\right\} \oplus W_{0}^{1, p}(\Omega)^{\top}
$$

The main idea in our variational approach is to look for the unknowns $u^{\|}$and $u^{\top}$ separately; first for $u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$ and then for $u^{\|} \in \mathbb{R}$ (depending on $u^{\top}$ ). More precisely, we look for critical points of the energy functional

$$
\begin{equation*}
\mathcal{J}_{\lambda}(u)=\frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u \mathrm{~d} x, \quad u \in W_{0}^{1, p}(\Omega) \tag{1.5}
\end{equation*}
$$

corresponding to problem 1.1) as follows.
First, we fix $u^{\|}=\tau \in \mathbb{R}$ arbitrary and minimize the restricted energy functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ over the orthogonal complement $W_{0}^{1, p}(\Omega)^{\top}$, thus obtaining a global minimizer $u_{\tau}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$,

$$
j_{\lambda}(\tau) \stackrel{\text { def }}{=} \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u_{\tau}^{\top}\right) \leq \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right) \quad \text { for all } u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}
$$

This is possible provided the functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ is coercive on $W_{0}^{1, p}(\Omega)^{\top}$ which, indeed, is the case if $\lambda<\Lambda_{\infty}$. The number

$$
\begin{equation*}
\Lambda_{\infty} \stackrel{\text { def }}{=} \inf \left\{\int_{\Omega}|\nabla u|^{p} \mathrm{~d} x: u \in W_{0}^{1, p}(\Omega)^{\top} \text { with } \int_{\Omega}|u|^{p} \mathrm{~d} x=1\right\} \tag{1.6}
\end{equation*}
$$

satisfies $\Lambda_{\infty}>\lambda_{1}$, by the simplicity of eigenvalue $\lambda_{1}$. Using the uniform convexity of $W_{0}^{1, p}(\Omega)$, we will be able to show that $j_{\lambda}: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function.

Now we vary $\tau \in \mathbb{R}$ and look for local extrema (minima or maxima) of the function $j_{\lambda}(\tau)$ in order to determine possible critical points of the functional $\mathcal{J}_{\lambda}$ : $W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$. Clearly, if $\tau_{0}$ is a local minimizer for $j_{\lambda}$, then also $u_{0}=\tau_{0} \varphi_{1}+u_{\tau_{0}}^{\top}$ is a local minimizer for $\mathcal{J}_{\lambda}$ and hence a critical point of $\mathcal{J}_{\lambda}$. A more complicated situation occurs if $j_{\lambda}$ has a local maximum at $\tau_{0} \in \mathbb{R}$. In general, we even do not know if $j_{\lambda}$ is differentiable at $\tau_{0}$. However, we are still able to show that problem (1.1) possesses a pair of sub- and supersolutions,

$$
\underline{u}=\tau_{0} \varphi_{1}+\underline{u}^{\top} \quad \text { and } \quad \bar{u}=\tau_{0} \varphi_{1}+\bar{u}^{\top}
$$

respectively, such that

$$
\left.\begin{array}{cl}
-\Delta_{p} \underline{u}=\lambda|\underline{u}|^{p-2} \underline{u}+f(x)+\underline{\zeta} \cdot \varphi_{1} & \text { in } \Omega ; \\
\underline{u}=0 \quad \text { on } \partial \Omega, & \\
-\Delta_{p} \bar{u}=\lambda|\bar{u}|^{p-2} \bar{u}+f(x)+\bar{\zeta} \cdot \varphi_{1} & \text { in } \Omega ;  \tag{1.8}\\
\bar{u}=0 \quad \text { on } \partial \Omega, &
\end{array}\right\}
$$

for some $\underline{\zeta}, \bar{\zeta} \in \mathbb{R}$ satisfying $\underline{\zeta} \leq 0 \leq \bar{\zeta}$. Fortunately, another method ([6] Theorem 8.2, p. 44 $\overline{8}$ ] or [14, Lemma 2. $\overline{4}$, p. 191]), which combines the existence of such a pair of sub- and supersolutions with the topological (Leray-Schauder) degree, renders the existence of a (weak) solution $u=\tau \varphi_{1}+u^{\top}$ of problem (1.1) with $\tau$ "close enough" to $\tau_{0}$, relative to the magnitude of $\left|\tau_{0}\right|$. In this way we are able to distinguish the solution $u$ from those other local minima or maxima of $j_{\lambda}$ whose absolute value is of a different order of magnitude than $\left|\tau_{0}\right|$ (meaning either much smaller or much larger) or whose sign is opposite to $\operatorname{sgn} \tau_{0}$. If the sub- and supersolutions coincide, then $u_{0}=\underline{u}=\bar{u}$ is a critical point of $\mathcal{J}_{\lambda}$ and, moreover, it is an easy exercise to show that $j_{\lambda}$ is differentiable at $\tau_{0}$ with vanishing derivative. Employing this procedure we are able to obtain multiple solutions of the form $u=\tau \varphi_{1}+u^{\top}$ to problem (1.1) which can be distinguished either by the order of magnitude of $|\tau|$ or by the sign of parameter $\tau \in \mathbb{R}$.

The variational method sketched above is somewhat different from Rabinowitz' "Saddle Point Theorem" [30, Theorem 4.6, p. 24] applied to the functional $\mathcal{J}_{\lambda}$. We actually work with a "maximin" expression,

$$
\begin{equation*}
\max _{a<\tau<b} j_{\lambda}(\tau)=\max _{a<\tau<b} \min _{u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}} \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right) \tag{1.9}
\end{equation*}
$$

with $-\infty \leq a<b \leq \infty$ suitably chosen, and thus obtain a local maximizer $\tau_{0}$ of the function $j_{\lambda}: \mathbb{R} \rightarrow \mathbb{R}$ which, in turn, induces a sub- and a supersolution to problem (1.1). This method originates in an earlier work of the author [32, Sect. 7] for $p<2$ and $\lambda_{1}-\delta \leq \lambda \leq \lambda_{1}$. A number of results on the solvability (existence, or nonexistence, and multiplicity of solutions) of problem 1.1) have been obtained by other methods for any $1<p<\infty$ and $\left|\lambda-\lambda_{1}\right| \leq \delta$; see [7, 9, 28, 40, 41] with further significant progress being made recently in [10, 11, 12, 13, 14, 20, 22, 26, 27, 29, 32, 33, 34, 35]. We will follow the recent work [35] in order to prove (or at least explain) some of these results here employing our variational method. A result from [35, Theorem 2.7, p. 702] concerning the case $p>2$ and $\lambda_{1}<\lambda \leq \lambda_{1}+\delta$ is of special interest, for it features at least three (pairwise distinct) solutions of problem (1.1): two critical points of the functional $\mathcal{J}_{\lambda}$, which are probably not local minimizers, and a local minimizer "between" them. Occasionally, variational proofs provide generalizations of earlier results. For these reasons we feel that the method is worth of being further explored in order to derive existence and multiplicity results for 1.1 and related problems, with $f(x)$ replaced by a more general function $f(x, u)$, see suggestions in Section 12

We will see that problem (1.1) possesses multiple solutions in some cases provided $\left|\left\langle f, \varphi_{1}\right\rangle\right|>0$ is small enough relative to $\|f\|_{L^{\infty}(\Omega)}$ : at least two solutions if $\lambda=\lambda_{1}$, and at least three solutions if $\left|\lambda-\lambda_{1}\right|>0$ is small enough. We start from the basic case $\left\langle f, \varphi_{1}\right\rangle=0$ and $\lambda=\lambda_{1}$. Our variational method is stable enough for the energy functional $\mathcal{J}_{\lambda}$, so that we can slightly relax the orthogonality condition $\left\langle f, \varphi_{1}\right\rangle=0$ (relative to the size of $\|f\|_{L^{\infty}(\Omega)}$ ) and/or the condition $\lambda=\lambda_{1}$. Multiple solutions
to problem (1.1) with $N=1$, any $0<\lambda<\lambda_{1}$, and a suitable function $f$ have been constructed earlier in [19] (for $1<p<2$ ) and [28] (for $2<p<\infty$ ). Other cases, all with $\lambda$ near $\lambda_{1}$, have been treated more recently in [10, 11, 12, 13, 22, 33, 34].

These lecture notes are organized as follows. As a "warm-up" exercise, in the next section (Section 2) we give a (simple) variational proof of the Riesz representation theorem for continuous linear functionals on $L^{p}(\Omega)$ inspired by Adams and Fournier [1, Proof of Theorem 2.44, pp. 46-47]. In Section 3 we introduce some notations and basic hypotheses. The energy functional $\mathcal{J}_{\lambda}$ and (weak and strong) convergence of a minimizing sequence in $W_{0}^{1, p}(\Omega)$ are studied in Section 4. A few basic properties of the first eigenvalue of $-\Delta_{p}$ are stated in Section 5. In Section 6 we explore the convexity of the functional $\mathcal{J}_{\lambda}$, first for $\lambda \leq 0$ (on all of $W_{0}^{1, p}(\Omega)$, in $\$ 6.1$ and then also for $0<\lambda \leq \lambda_{1}$ and $f \geq 0$ (on the set of positive functions, in $\$ 6.2$, and its impact on the uniqueness of a solution to problem (1.1). In Section 7 we present a variational method which is based on minimization with constraint. Elementary analysis in Section 8 suggests how to obtain critical points for $\mathcal{J}_{\lambda}$. In Section 9 we apply the Leray-Schauder degree to a suitable fixed point mapping in order to establish the existence of a critical point for $\mathcal{J}_{\lambda}$ (which probably is not a local minimizer). Multiple (and "large") critical points of $\mathcal{J}_{\lambda}$ are discussed in Section 10. A collection of main results that can be obtained by the variational and topological methods presented in these notes is given in Section 11. Finally, Section 12 is devoted to a brief discussion of the general problem

$$
\begin{equation*}
-\Delta_{p} u=\lambda|u|^{p-2} u+f(x, u(x)) \quad \text { in } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{1.10}
\end{equation*}
$$

when the function $f(x, u)$ is allowed to depend also on the state variable $u \in \mathbb{R}$. The lecture notes conclude with two appendices: Appendix A with some auxiliary functional-analytic results from Takáč [32 and Appendix B which contains some (mostly highly nontrivial) results from Drábek et al. [13, Theorem 4.1, pp. 445-446] and Takáč 32, 33.

## 2. The Riesz representation theorem in $L^{p}(\Omega)$

A given (equivalent) norm $\|\cdot\|_{X}$ on a Banach space $X$ (and, hence, also $X$ itself endowed with this norm) is called uniformly convex if for every $\varepsilon>0$ there exists some $\delta \equiv \delta(\varepsilon)>0$ such that, for all $u, v \in X$, one has

$$
\|u\|_{X},\|v\|_{X} \leq 1 \quad \text { and } \quad\left\|\frac{u+v}{2}\right\|_{X}>1-\delta \quad \Longrightarrow \quad\|u-v\|_{X}<\varepsilon
$$

The uniform convexity of the standard norm on $L^{p}(\Omega)$ for $1<p<\infty$,

$$
\begin{equation*}
\|u\|_{L^{p}(\Omega)} \stackrel{\text { def }}{=}\left(\int_{\Omega}|u(x)|^{p} \mathrm{~d} x\right)^{1 / p}, \quad u \in L^{p}(\Omega) \tag{2.1}
\end{equation*}
$$

is a direct consequence of Clarkson's inequalities (see e.g. Adams and Fournier [1. Theorem 2.38, p. 44] for a proof):

Lemma 2.1 (Clarkson's inequalities). Let $1<p<\infty$ and $p^{\prime}=p /(p-1)$. For $u, v \in L^{p}(\Omega)$ (real or complex-valued, and vector-valued functions from $\left[L^{p}(\Omega)\right]^{N}$, as well) we have
(a) if $2 \leq p<\infty$ then

$$
\begin{align*}
& \left\|\frac{u+v}{2}\right\|_{L^{p}(\Omega)}^{p}+\left\|\frac{u-v}{2}\right\|_{L^{p}(\Omega)}^{p} \leq \frac{1}{2}\left(\|u\|_{L^{p}(\Omega)}^{p}+\|v\|_{L^{p}(\Omega)}^{p}\right)  \tag{2.2}\\
& \left\|\frac{u+v}{2}\right\|_{L^{p}(\Omega)}^{p^{\prime}}+\left\|\frac{u-v}{2}\right\|_{L^{p}(\Omega)}^{p^{\prime}} \geq\left[\frac{1}{2}\left(\|u\|_{L^{p}(\Omega)}^{p}+\|v\|_{L^{p}(\Omega)}^{p}\right)\right]^{p^{\prime}-1}
\end{align*}
$$

(b) if $1<p \leq 2$ then

$$
\begin{align*}
& \left\|\frac{u+v}{2}\right\|_{L^{p}(\Omega)}^{p^{\prime}}+\left\|\frac{u-v}{2}\right\|_{L^{p}(\Omega)}^{p^{\prime}} \leq\left[\frac{1}{2}\left(\|u\|_{L^{p}(\Omega)}^{p}+\|v\|_{L^{p}(\Omega)}^{p}\right)\right]^{p^{\prime}-1}  \tag{2.3}\\
& \left\|\frac{u+v}{2}\right\|_{L^{p}(\Omega)}^{p}+\left\|\frac{u-v}{2}\right\|_{L^{p}(\Omega)}^{p} \geq \frac{1}{2}\left(\|u\|_{L^{p}(\Omega)}^{p}+\|v\|_{L^{p}(\Omega)}^{p}\right)
\end{align*}
$$

Notice that if $p=p^{\prime}=2$, the inequalities above reduce to the parallelogram law in the Hilbert space $L^{2}(\Omega)$.

Clarkson's inequalities (2.2) (if $2 \leq p<\infty$ ) and (2.3) (if $1<p \leq 2$ ) can be used to give a simple variational proof of the Riesz representation theorem for continuous linear functionals on $L^{p}(\Omega)$; see e.g. the monograph by Adams and Fournier [1, Theorem 2.44, p. 47 ]. We are now ready to give a similar proof. Our approach is even more "variational" than the one presented in [1, Proof of Theorem 2.44, pp. $46-47]$. We apply a standard minimization procedure to the functional

$$
\begin{equation*}
\mathcal{E}(u) \equiv \mathcal{E}(u ; \ell)=\frac{1}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\Re \mathfrak{e} \ell(u), \quad u \in L^{p}(\Omega) \tag{2.4}
\end{equation*}
$$

where $\ell: L^{p}(\Omega) \rightarrow \mathbb{R}($ or $\mathbb{C})$ is a continuous linear functional defined on the real (or complex, respectively) Lebesgue space $L^{p}(\Omega), 1<p<\infty$, which is given. Hence, we will show that this functional has a global minimizer $\tilde{u}$ in $L^{p}(\Omega)$; see Lemma 2.2 below. Moreover, $\mathcal{E}$ being strictly convex, by Clarkson's inequalities, we can conclude that it possesses a unique critical point. This point will provide us with the desired representation function from the dual space $L^{p^{\prime}}(\Omega), p^{\prime}=p /(p-1)$.

In other words, we will apply Clarkson's inequalities (Lemma 2.1) to show
The Riesz representation theorem. Given a continuous linear functional $\ell$ on $L^{p}(\Omega)$, there exists a unique function $f \in L^{p^{\prime}}(\Omega)$ such that

$$
\begin{equation*}
\ell(u)=\int_{\Omega} u f \mathrm{~d} x \quad \text { holds for all } u \in L^{p}(\Omega) \tag{2.5}
\end{equation*}
$$

Clearly, the standard complexification procedure for the real Lebesgue space $L_{\mathbb{R}}^{p}(\Omega)$ (over the field $\mathbb{R}$ ) yields the complex Lebesgue space $L_{\mathbb{C}}^{p}(\Omega)$ (over the field $\mathbb{C})$, so that $L_{\mathbb{C}}^{p}(\Omega)=L_{\mathbb{R}}^{p}(\Omega) \oplus \mathrm{i} L_{\mathbb{R}}^{p}(\Omega)$ is a direct sum over the field $\mathbb{R}\left(\mathrm{i}^{2}=-1\right)$. As a consequence, both, the real and imaginary parts of the continuous linear functional $\ell$ are also continuous linear functionals on the direct sum $L_{\mathbb{R}}^{p}(\Omega) \oplus \mathrm{i} L_{\mathbb{R}}^{p}(\Omega)$. Hence, it suffices to verify the Riesz representation theorem for the real Lebesgue space $L^{p}(\Omega)=L_{\mathbb{R}}^{p}(\Omega)$ and $\ell: L_{\mathbb{R}}^{p}(\Omega) \rightarrow \mathbb{R}$. To this end, observe that if $f \in L^{p^{\prime}}(\Omega)$ satisfies (2.5) then $v=|f|^{p^{\prime}-2} f$ is a critical point of the functional

$$
\mathcal{E}(u)=\frac{1}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\ell(u), \quad u \in L^{p}(\Omega)
$$

Vice versa, if $v \in L^{p}(\Omega)$ is a critical point of $\mathcal{E}$ then $f=|v|^{p-2} v$ satisfies (2.5). Notice that the Fréchet derivative $\mathcal{E}^{\prime}(v): L^{p}(\Omega) \rightarrow \mathbb{R}$ of the functional $\mathcal{E}$ at a given
point $v \in L^{p}(\Omega)$ is given by the formula

$$
\mathcal{E}^{\prime}(v) u=\int_{\Omega} u|v|^{p-2} v \mathrm{~d} x-\ell(u), \quad u \in L^{p}(\Omega)
$$

It remains to establish the following lemma which is valid in both, the real and complex versions of the Lebesgue space $L^{p}(\Omega)$ (over the field $\mathbb{R}$ or $\mathbb{C}$ ), that is, also for the functional $\mathcal{E}$ defined in 2.4.
Lemma 2.2. The functional $\mathcal{E}: L^{p}(\Omega) \rightarrow \mathbb{R}$ defined in 2.4 is continuous, strictly convex, and coercive on $L^{p}(\Omega), 1<p<\infty$. Moreover, every minimizing sequence for $\mathcal{E}$ converges strongly in $L^{p}(\Omega)$ to the (unique) global minimizer $\tilde{u}$ of $\mathcal{E}$.

Proof. The continuity and coercivity of $\mathcal{E}$ are obvious. As mentioned above, $\mathcal{E}$ is strictly convex, by Clarkson's inequalities 2.2 (if $2 \leq p<\infty$ ) and 2.3) (if $1<p \leq 2$ ).

Set $\mu \stackrel{\text { def }}{=} \inf _{u \in L^{p}(\Omega)} \mathcal{E}(u)$ and consider any minimizing sequence $\left\{u_{n}\right\}_{n=1}^{\infty} \subset L^{p}(\Omega)$ for $\mathcal{E}$, i.e., $\mathcal{E}\left(u_{n}\right) \rightarrow \mu$ as $n \rightarrow \infty$. We wish to show that $u_{n} \rightarrow \tilde{u}$ strongly in $L^{p}(\Omega)$ as $n \rightarrow \infty$. Since the space $L^{p}(\Omega)$ is complete, this is equivalent to $\left\{u_{n}\right\}_{n=1}^{\infty}$ being a Cauchy sequence, i.e.,

$$
\begin{equation*}
\lim _{m, n \rightarrow \infty}\left\|u_{n}-u_{m}\right\|_{L^{p}(\Omega)} \rightarrow 0 \quad \text { as } m, n \rightarrow \infty \tag{2.6}
\end{equation*}
$$

The last claim follows from the facts that

$$
\begin{equation*}
\mathcal{E}\left(\frac{1}{2}\left(u_{n}+u_{m}\right)\right) \geq \mu \quad \text { and } \quad \ell\left(\frac{1}{2}\left(u_{n}+u_{m}\right)\right)=\frac{1}{2}\left(\ell\left(u_{n}\right)+\ell\left(u_{m}\right)\right) \tag{2.7}
\end{equation*}
$$

combined with Clarkson's inequalities (2.2) and (2.3) which force (2.6), thanks to $\mathcal{E}\left(u_{n}\right) \rightarrow \mu$ as $n \rightarrow \infty$.

To see this, for $p \geq 2$ one applies inequality directly to the functional $\mathcal{E}$ as follows:

$$
\begin{aligned}
\mu+\frac{1}{p}\left\|\frac{u_{n}-u_{m}}{2}\right\|_{L^{p}(\Omega)}^{p} & \leq \mathcal{E}\left(\frac{u_{n}+u_{m}}{2}\right)+\frac{1}{p}\left\|\frac{u_{n}-u_{m}}{2}\right\|_{L^{p}(\Omega)}^{p} \\
& \leq \frac{1}{2}\left(\mathcal{E}\left(u_{n}\right)+\mathcal{E}\left(u_{m}\right)\right)
\end{aligned}
$$

Using $\mathcal{E}\left(u_{n}\right) \rightarrow \mu$ as $n \rightarrow \infty$ we arrive at (2.6).
For $1<p<2$ the proof is less direct; this proof works for any $p \in(1, \infty)$. Since the functional $\mathcal{E}$ is coercive, the minimizing sequence $\left\{u_{n}\right\}_{n=1}^{\infty}$ must be bounded in $L^{p}(\Omega)$. Consequently, passing to a suitable subsequence if necessary, we may assume

$$
\left\|u_{n}\right\|_{L^{p}(\Omega)} \rightarrow \xi \in \mathbb{R}_{+} \quad \text { and } \quad \ell\left(u_{n}\right) \rightarrow \eta \in \mathbb{C} \quad \text { as } n \rightarrow \infty ;
$$

hence, $\frac{1}{p} \xi^{p}+\Re e \eta=\mu$. From Minkowski's inequality (convexity of a norm) and 2.7) we deduce

$$
\begin{aligned}
\mu & \leq \mathcal{E}\left(\frac{u_{n}+u_{m}}{2}\right)=\frac{1}{p}\left\|\frac{u_{n}+u_{m}}{2}\right\|_{L^{p}(\Omega)}^{p}-\Re \mathfrak{e} \ell\left(\frac{u_{n}+u_{m}}{2}\right) \\
& \leq \frac{1}{p}\left(\frac{\left\|u_{n}\right\|_{L^{p}(\Omega)}+\left\|u_{m}\right\|_{L^{p}(\Omega)}}{2}\right)^{p}-\frac{1}{2}\left(\Re \mathfrak{e} \ell\left(u_{n}\right)+\Re \mathfrak{e} \ell\left(u_{m}\right)\right) \\
& \leq \frac{1}{2}\left(\mathcal{E}\left(u_{n}\right)+\mathcal{E}\left(u_{m}\right)\right) .
\end{aligned}
$$

Using $\mathcal{E}\left(u_{n}\right) \rightarrow \mu$ as $n \rightarrow \infty$, we arrive at $\mathcal{E}\left(\frac{u_{n}+u_{m}}{2}\right) \rightarrow \mu$ as $m, n \rightarrow \infty$. Since also $\ell\left(\frac{u_{n}+u_{m}}{2}\right) \rightarrow \eta$ and $\frac{1}{p} \xi^{p}+\Re \mathfrak{e} \eta=\mu$, we conclude that $\left\|\frac{u_{n}+u_{m}}{2}\right\|_{L^{p}(\Omega)} \rightarrow \xi$
$(m, n \rightarrow \infty)$. Finally, we combine this convergence result and $\left\|u_{n}\right\|_{L^{p}(\Omega)} \rightarrow \xi$ $(n \rightarrow \infty)$ with Clarkson's inequalities 2.2 (if $2 \leq p<\infty$ ) and (2.3) (if $1<p \leq 2$ ) to obtain (2.6).

## 3. Notation and basic hypotheses

All Banach and Hilbert spaces used in these lecture notes are real. We work with the standard inner product in $L^{2}(\Omega)$ defined by $\langle u, v\rangle \stackrel{\text { def }}{=} \int_{\Omega} u v \mathrm{~d} x$ for $u, v \in L^{2}(\Omega)$. The orthogonal complement in $L^{2}(\Omega)$ of a set $\mathcal{M} \subset L^{2}(\Omega)$ is denoted by $\mathcal{M}^{\perp, L^{2}}$,

$$
\mathcal{M}^{\perp, L^{2}} \stackrel{\text { def }}{=}\left\{u \in L^{2}(\Omega):\langle u, v\rangle=0 \text { for all } v \in \mathcal{M}\right\}
$$

The inner product $\langle\cdot, \cdot\rangle$ in $L^{2}(\Omega)$ induces a duality between the Lebesgue spaces $L^{p}(\Omega)$ and $L^{p^{\prime}}(\Omega)$, where $1 \leq p<\infty$ and $1<p^{\prime} \leq \infty$ with $\frac{1}{p}+\frac{1}{p^{\prime}}=1$, and between the Sobolev space $W_{0}^{1, p}(\Omega)$ and its (strong) dual space $W^{-1, p^{\prime}}(\Omega)$, as well. We keep the same notation also for the duality between the Cartesian products $\left[L^{p}(\Omega)\right]^{N}$ and $\left[L^{p^{\prime}}(\Omega)\right]^{N}$. The closure, interior, and boundary of a set $S \subset \mathbb{R}^{N}$ are denoted by $\bar{S}, \operatorname{int}(S)$, and $\partial S$, respectively, and the characteristic function of $S$ by $\chi_{S}: \mathbb{R}^{N} \rightarrow\{0,1\}$. We write $|S|_{N} \stackrel{\text { def }}{=} \int_{\mathbb{R}^{N}} \chi_{S}(x) \mathrm{d} x$ if $S$ is also Lebesgue measurable.

We always assume the following hypothesis:
(H1) If $N \geq 2$ then $\Omega$ is a bounded domain in $\mathbb{R}^{N}$ whose boundary $\partial \Omega$ is a compact manifold of class $C^{1, \alpha}$ for some $\alpha \in(0,1)$, and $\Omega$ satisfies also the interior sphere condition at every point of $\partial \Omega$. If $N=1$ then $\Omega$ is a bounded open interval in $\mathbb{R}^{1}$.
For $N \geq 2$, H 1 is satisfied if $\Omega \subset \mathbb{R}^{N}$ is a bounded domain with $C^{2}$ boundary.

## 4. The energy functional

Recall that the energy functional defined in 1.5),

$$
\mathcal{J}_{\lambda}(u) \equiv \mathcal{J}_{\lambda}(u ; f)=\frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u \mathrm{~d} x
$$

for $u \in W_{0}^{1, p}(\Omega)$, corresponds to problem 1.1. This problem is equivalent to $\mathcal{J}_{\lambda}^{\prime}(u)=0$ in $W^{-1, p^{\prime}}(\Omega)$, where $\mathcal{J}_{\lambda}^{\prime}(u)$ denotes the (first) Fréchet derivative of the functional $\mathcal{J}_{\lambda}$ on $W_{0}^{1, p}(\Omega)$.

If $\lambda<\lambda_{1}$, the functional $\mathcal{J}_{\lambda}$ is coercive on $W_{0}^{1, p}(\Omega)$ which means that $\|u\|_{W_{0}^{1, p}(\Omega)}$ $\rightarrow \infty$ forces $\mathcal{J}_{\lambda}(u) \rightarrow+\infty$. Thus, the Sobolev space $W_{0}^{1, p}(\Omega)$ being reflexive, there exists a weakly convergent (minimizing) sequence $u_{n} \rightharpoonup u_{0}$ in $W_{0}^{1, p}(\Omega)$ as $n \rightarrow \infty$, such that

$$
\mathcal{J}_{\lambda}\left(u_{n}\right) \rightarrow \mathcal{J}_{\lambda}\left(u_{0}\right)=\inf _{u \in W_{0}^{1, p}(\Omega)} \mathcal{J}_{\lambda}(u)>-\infty \quad \text { as } n \rightarrow \infty
$$

Notice that this weak convergence implies only

$$
\liminf _{n \rightarrow \infty} \int_{\Omega}\left|\nabla u_{n}\right|^{p} \mathrm{~d} x \geq \int_{\Omega}\left|\nabla u_{0}\right|^{p} \mathrm{~d} x .
$$

Since the Sobolev embedding $W_{0}^{1, p}(\Omega) \hookrightarrow L^{p}(\Omega)$ is compact, by the Rellich--Kondrachov embedding theorem, we have also $u_{n} \rightarrow u_{0}$ strongly in $L^{p}(\Omega)$ as
$n \rightarrow \infty$. We combine these convergence results with the definition of the functional $\mathcal{J}_{\lambda}$ to conclude that we must have also

$$
\int_{\Omega}\left|\nabla u_{n}\right|^{p} \mathrm{~d} x \longrightarrow \int_{\Omega}\left|\nabla u_{0}\right|^{p} \mathrm{~d} x \quad \text { as } n \rightarrow \infty
$$

But this and the weak convergence $u_{n} \rightharpoonup u_{0}$ in $W_{0}^{1, p}(\Omega)$ force the strong convergence

$$
\left\|u_{n}-u\right\|_{W_{0}^{1, p}(\Omega)}=\left\|\nabla\left(u_{n}-u\right)\right\|_{L^{p}(\Omega)} \rightarrow 0 \quad \text { in } W_{0}^{1, p}(\Omega) \text { as } n \rightarrow \infty
$$

owing to the fact that $L^{p}(\Omega)$ (and similarly $\left[L^{p}(\Omega)\right]^{N}$ ) is a uniformly convex Banach space, by Clarkson's inequalities (Lemma 2.1).

Lemma 4.1. Let $\lambda \in \mathbb{R}$ be arbitrary. If $u_{n} \rightharpoonup u_{0}$ weakly in $W_{0}^{1, p}(\Omega)$ and $\mathcal{J}_{\lambda}\left(u_{n}\right) \rightarrow$ $\mathcal{J}_{\lambda}\left(u_{0}\right)$ as $n \rightarrow \infty$, then also $u_{n} \rightarrow u_{0}$ strongly in $W_{0}^{1, p}(\Omega)$.

We will use such convergence reasoning often throughout the entire lecture notes. In what follows we show a few applications of the reasoning from our proof of Lemma 4.1.
5. The first eigenvalue of $-\Delta_{p}$

Consider the Rayleigh quotient 1.2 for the first (smallest) eigenvalue $\lambda_{1}$ of $-\Delta_{p}$,

$$
\lambda_{1}=\inf \left\{\frac{\int_{\Omega}|\nabla u|^{p} \mathrm{~d} x}{\int_{\Omega}|u|^{p} \mathrm{~d} x}: 0 \neq u \in W_{0}^{1, p}(\Omega)\right\}
$$

The embedding $W_{0}^{1, p}(\Omega) \hookrightarrow L^{p}(\Omega)$ being compact, there exists a function $\varphi_{1} \in$ $W_{0}^{1, p}(\Omega)$ such that

$$
\int_{\Omega}\left|\varphi_{1}\right|^{p} \mathrm{~d} x=1 \quad \text { and } \quad \int_{\Omega}\left|\nabla \varphi_{1}\right|^{p} \mathrm{~d} x=\lambda_{1}
$$

Hence, $0<\lambda_{1}<\infty$. Next, we use the polar decomposition $u=u^{+}-u^{-}$of $u \in L^{p}(\Omega), u^{+} \stackrel{\text { def }}{=} \max \{u, 0\}$ and $u^{-} \stackrel{\text { def }}{=} \max \{-u, 0\}$, with $\nabla u=\nabla u^{+}-\nabla u^{-}$a.e. in $\Omega$ for $u \in W_{0}^{1, p}(\Omega)$; see, e.g., Gilbarg and Trudinger [21, Theorem 7.8, p. 153]. We observe that also the positive and negative parts $\varphi_{1}^{ \pm}$of $\varphi_{1}$ must satisfy

$$
\int_{\Omega}\left|\nabla \varphi_{1}^{ \pm}\right|^{p} \mathrm{~d} x=\lambda_{1} \int_{\Omega}\left(\varphi_{1}^{ \pm}\right)^{p} \mathrm{~d} x
$$

We will see in the next section, 6.2 . Theorem 6.8, that $\varphi_{1} \in W_{0}^{1, p}(\Omega)$ is determined uniquely by the conditions
$\left(\mathrm{i}_{\varphi_{1}}\right) \varphi_{1} \geq 0$ almost everywhere in $\Omega$;
(ii $\varphi_{1}$ ) $\int_{\Omega} \varphi_{1}^{p} \mathrm{~d} x=1$ and $\int_{\Omega}\left|\nabla \varphi_{1}\right|^{p} \mathrm{~d} x=\lambda_{1}$.
This uniqueness result is due to Anane [2, Théorème 1, p. 727] and Lindqvist [25, Theorem 1.3, p. 157]. Hence, either $\varphi_{1}^{+} \equiv 0$ or else $\varphi_{1}^{-} \equiv 0$ in $\Omega$, and so we may assume $\varphi_{1} \geq 0$ a.e. in $\Omega$.

It follows that $\lambda_{1}$ is a simple eigenvalue of the positive Dirichlet $p$-Laplacian $-\Delta_{p}$ with a nonnegative eigenfunction $\varphi_{1}$ satisfying

$$
\begin{equation*}
-\Delta_{p} \varphi_{1}=\lambda_{1}\left|\varphi_{1}\right|^{p-2} \varphi_{1} \quad \text { in } \Omega ; \quad \varphi_{1}=0 \quad \text { on } \partial \Omega \tag{5.1}
\end{equation*}
$$

Using this equation, Anane [3, Théorème A.1, p. 96] has derived also $\varphi_{1} \in L^{\infty}(\Omega)$.

## 6. Convexity And UNIQUENESS

Convexity of a function (or functional) is a standard tool for proving the uniqueness of a critical point for that function (or functional), provided the convexity is strict in some sense; cf. 6.1 below. We will see in 6.2 that if the strictness in the convexity is lost in some sense (partially), so may be the uniqueness of critical points (only partially, as well). The following simple example explains the key tool for this method.

Example 6.1. Let $X$ be a Banach space, $x_{0} \in X$ a point, and $v \in X \backslash\{0\}$ a direction. Consider the straight line $L=\left\{x=x_{0}+t v \in X: t \in \mathbb{R}\right\}$ in $X$. Given a functional $\Phi: X \rightarrow \mathbb{R}$ on $X$, consider its restriction $\left.\Phi\right|_{L}$ to the line $L$ or, equivalently, consider the function $\phi(t)=\Phi\left(x_{0}+t v\right)$ of the variable $t \in \mathbb{R}$. If $\phi$ happens to be convex and differentiable on $\mathbb{R}$ then the set of all critical points of $\phi$ coincides with a closed interval in $\mathbb{R}$ (which may be empty or unbounded). This interval coincides, in turn, with the set of all global minimizers for $\phi$. If $\phi$ is also strictly convex then it may possess at most one critical point in $\mathbb{R}$; this point is the global minimizer for $\phi$. Consequently, if $\Phi$ is convex and Gâteaux-differentiable on $X$, it suffices to investigate the strict convexity of $\Phi$ on every line $L$ in $X$ in order to determine the set of all critical points for $\Phi$ in $X$. This set is convex and consists precisely of all global minimizers for $\Phi$; it may be empty or unbounded in $X$.

Now let us treat the energy functional defined in 1.5 ,

$$
\mathcal{J}_{\lambda}(u) \equiv \mathcal{J}_{\lambda}(u ; f)=\frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u \mathrm{~d} x
$$

for $u \in W_{0}^{1, p}(\Omega)$. Recall that problem (1.1) is equivalent to $\mathcal{J}_{\lambda}^{\prime}(u)=0$ in $W^{-1, p^{\prime}}(\Omega)$, where $\mathcal{J}_{\lambda}^{\prime}(u)$ denotes the (first) Fréchet derivative of the functional $\mathcal{J}_{\lambda}$ on $W_{0}^{1, p}(\Omega)$.

From Section 4 we know that $\mathcal{J}_{\lambda}$ is coercive on $W_{0}^{1, p}(\Omega)$ provided $\lambda<\lambda_{1}$. Hence, if $\lambda<\lambda_{1}$ then $\mathcal{J}_{\lambda}$ has a global minimizer in $W_{0}^{1, p}(\Omega)$. We investigate its uniqueness (or multiplicity) in the next two paragraphs, for $\lambda \leq 0$ and $0<\lambda \leq \lambda_{1}$, respectively. From the end of Section 7 we recall $j_{\lambda_{1}}(\tau)=-c \cdot|\tau|^{2-p}+o\left(|\tau|^{2-p}\right)$ as $\tau \rightarrow \pm \infty$, where $c=c\left(f^{\top}\right)>0$ is a constant depending on $f^{\top}\left(f^{\top} \not \equiv 0\right.$ in $\left.\Omega\right)$. The function $j_{\lambda_{1}}$ being continuous, it attains a global minimum at $\tau_{0} \in \mathbb{R}$ if $p>2$. It follows that, even if $\mathcal{J}_{\lambda_{1}}$ is not coercive on $W_{0}^{1, p}(\Omega)$, for $p>2$ it possesses a global minimizer $u_{0}=\tau_{0} \varphi_{1}+u_{0}^{\top}$ with some $u_{0}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$.
6.1. Convexity for $\lambda \leq 0$ and any $f$. Let $\lambda \leq 0$ and $f \in W^{-1, p^{\prime}}(\Omega)$. Then both nonlinear terms on the right-hand side in (1.5) are nonnegative and convex, the first one even strictly convex on $W_{0}^{1, p}(\Omega)$. The uniqueness of the global minimizer for $\mathcal{J}_{\lambda}$ in $W_{0}^{1, p}(\Omega)$ now follows from Example 6.1 above. Moreover, this global minimizer is the unique critical point for $\mathcal{J}_{\lambda}$. Thus, we have proved the following theorem.

Theorem 6.2. Let $1<p<\infty,-\infty<\lambda \leq 0$, and $f \in W^{-1, p^{\prime}}(\Omega)$. Then the functional $\mathcal{J}_{\lambda}$ defined in 1.5 has a unique critical point in $W_{0}^{1, p}(\Omega)$. This critical point is its (unique) global minimizer. Moreover, $\mathcal{J}_{\lambda}$ is strictly convex on $W_{0}^{1, p}(\Omega)$.
6.2. Convexity for $0<\lambda \leq \lambda_{1}$ and $f \geq 0$. In this paragraph we restrict ourselves to the special case $0 \leq f \in L^{\infty}(\Omega)$ and investigate the functional $\mathcal{J}_{\lambda}(u)$ for $u \in$ $W_{0}^{1, p}(\Omega), u>0$ a.e. in $\Omega$. We follow the approach used in Fleckinger et al. 19,

Sect. 6 (Appendix)]; cf. also Girg and Takáč [22, §4.1], Takáč [34, Sect. 3], or Takáč, Tello, and Ulm [36, Sect. 2] for some generalizations.

Lemma 6.3. Let $0 \leq f \in L^{\infty}(\Omega)$ and $-\infty<\lambda \leq \lambda_{1}$. If $\lambda=\lambda_{1}$, assume also $f \not \equiv 0$ in $\Omega$. Then every critical point for $\mathcal{J}_{\lambda}$ is nonnegative.
Proof. Consider any critical point $u \in W_{0}^{1, p}(\Omega)$ for $\mathcal{J}_{\lambda}$. On the contrary, assume $u^{-} \not \equiv 0$ in $\Omega$. Then we have

$$
\begin{aligned}
0 & =\left\langle\mathcal{J}_{\lambda}^{\prime}(u), u^{-}\right\rangle \\
& =\int_{\Omega}|\nabla u|^{p-2}\left(\nabla u \cdot \nabla u^{-}\right) \mathrm{d} x-\lambda \int_{\Omega}|u|^{p-2} u u^{-} \mathrm{d} x-\int_{\Omega} f(x) u^{-} \mathrm{d} x \\
& =-\int_{\Omega}\left|\nabla u^{-}\right|^{p} \mathrm{~d} x+\lambda \int_{\Omega}\left|u^{-}\right|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u^{-} \mathrm{d} x \\
& \leq\left(\lambda-\lambda_{1}\right) \int_{\Omega}\left|u^{-}\right|^{p} \mathrm{~d} x-\int_{\Omega} f(x) u^{-} \mathrm{d} x \leq 0
\end{aligned}
$$

Since $u^{-} \not \equiv 0$ and $f \geq 0$ in $\Omega$, these inequalities force $\lambda=\lambda_{1}, u^{-}$is a minimizer for $\lambda_{1}$ in eq. 1.2 , and $u^{-}(x)=0$ almost everywhere in the set $\{x \in \Omega: f(x)>0\}$. On the other hand, from the strong maximum principle of Tolksdorf [37, Prop. 3.2.2, p. 801] or Vázquez [39, Theorem 5, p. 200] we deduce $u^{-}>0$ a.e. in $\Omega$. This forces $f=0$ a.e. in $\Omega$, a contradiction. The lemma is proved.

We say that a functional $\mathcal{K}$ is ray-strictly convex if it is convex on a convex set $\mathcal{C}\left(\right.$ say, $\left.\mathcal{C} \subset L_{\mathrm{loc}}^{1}(\Omega)\right), \mathcal{K}: \mathcal{C} \rightarrow \mathbb{R} \cup\{+\infty\}$, and if $v_{1}, v_{2} \in \mathcal{C}$ obey the equality

$$
\mathcal{K}\left((1-\theta) v_{1}+\theta v_{2}\right)=(1-\theta) \mathcal{K}\left(v_{1}\right)+\theta \mathcal{K}\left(v_{2}\right)<\infty
$$

for some $\theta \in(0,1)$, then $v_{1}$ and $v_{2}$ are linearly dependent.
We now define the functional

$$
\mathcal{K}(v) \stackrel{\text { def }}{=} \int_{\Omega}\left|\nabla\left(v^{1 / p}\right)\right|^{p} \mathrm{~d} x=p^{-p} \int_{\Omega} v|\nabla(\log v)|^{p} \mathrm{~d} x
$$

for all functions $v: \Omega \rightarrow(0, \infty)$ such that $v^{1 / p} \in W_{0}^{1, p}(\Omega)$. More generally, we may replace $\boldsymbol{v} \mapsto|\boldsymbol{v}|^{p}: \mathbb{R}^{N} \rightarrow \mathbb{R}_{+}$by any continuous, strictly convex function $K: \mathbb{R}^{N} \rightarrow \mathbb{R}_{+}$and define (up to the constant factor $p^{-p}$ )

$$
\mathcal{K}(v)=\int_{\Omega} v K(\nabla(\log v)) \mathrm{d} x \in \mathbb{R} \cup\{+\infty\}
$$

for all functions $v: \Omega \rightarrow(0, \infty)$ such that $v^{1 / p} \in W_{0}^{1, p}(\Omega)$, cf. Girg and Takáč [22, §4.1], Takáč [34, Sect. 3], or Takáč, Tello, and Ulm [36, Sect. 2]. (Notice that $\nabla\left(v^{1 / p}\right)=p^{-1} v^{1 / p} \nabla(\log v)$.)
Lemma 6.4. The functional $\mathcal{K}$ defined above is ray-strictly convex.
Proof. For $\theta \in(0,1), u_{1}>0, u_{2}>0$ and $\xi_{1}, \xi_{2} \in \mathbb{R}^{N}$, we compute

$$
\begin{aligned}
& \left((1-\theta) u_{1}+\theta u_{2}\right) K\left(\frac{(1-\theta) \xi_{1}+\theta \xi_{2}}{(1-\theta) u_{1}+\theta u_{2}}\right) \\
& =\left((1-\theta) u_{1}+\theta u_{2}\right) K\left(\frac{(1-\theta) u_{1}}{(1-\theta) u_{1}+\theta u_{2}} \frac{\xi_{1}}{u_{1}}+\frac{\theta u_{2}}{(1-\theta) u_{1}+\theta u_{2}} \frac{\xi_{2}}{u_{2}}\right) \\
& \leq(1-\theta) u_{1} K\left(\frac{\xi_{1}}{u_{1}}\right)+\theta u_{2} K\left(\frac{\xi_{2}}{u_{2}}\right)
\end{aligned}
$$

where equality holds if and only if $\xi_{1} / u_{1}=\xi_{2} / u_{2}$. Putting $u_{i}=v_{i}(x)$ and $\xi_{i}=$ $\nabla v_{i}(x)$ for a.e. $x \in \Omega$ and $i=1,2$, and integrating the last inequality over $\Omega$, we obtain

$$
\begin{equation*}
\mathcal{K}\left((1-\theta) v_{1}+\theta v_{2}\right) \leq(1-\theta) \mathcal{K}\left(v_{1}\right)+\theta \mathcal{K}\left(v_{2}\right) \tag{6.1}
\end{equation*}
$$

where equality holds if and only if $\nabla v_{1} / v_{1}=\nabla v_{2} / v_{2}$ a.e. in $\Omega$. The latter equality is equivalent to $v_{1}$ and $v_{2}$ being linearly dependent.

We combine Lemmas 6.3 and 6.4 to obtain the following theorem:
Theorem 6.5. Let $0 \leq f \in L^{\infty}(\Omega)$ with $f \not \equiv 0$ in $\Omega$. If $\lambda \in\left(0, \lambda_{1}\right)$ then the functional $\mathcal{J}_{\lambda}$ possesses a unique critical point $u \in W_{0}^{1, p}(\Omega)$. This critical point is the (unique) minimizer for $\mathcal{J}_{\lambda}$ and satisfies $u>0$ a.e. in $\Omega$. If, in addition, the boundary $\partial \Omega$ of $\Omega$ is of class $C^{1, \alpha}$ for some $\alpha \in(0,1)$, then $u$ satisfies also the Hopf maximum principle

$$
\begin{equation*}
u>0 \quad \text { in } \Omega \quad \text { and } \quad \frac{\partial u}{\partial \nu}<0 \quad \text { on } \partial \Omega . \tag{6.2}
\end{equation*}
$$

Proof. By our assumption $0<\lambda<\lambda_{1}$, the functional $\mathcal{J}_{\lambda}$ is coercive on $W_{0}^{1, p}(\Omega)$. Thus, it has a minimizer (which is a critical point). From Lemma 6.3 we know that every critical point $u \in W_{0}^{1, p}(\Omega)$ for $\mathcal{J}_{\lambda}$ must be nonnegative throughout $\Omega$. Moreover, the strong maximum principle of Tolksdorf [37, Prop. 3.2.2, p. 801] or Vázquez [39, Theorem 5, p. 200] guarantees $u>0$ a.e. in $\Omega$. For such $u$, let us now consider the functional $u \mapsto \mathcal{J}_{\lambda}\left(u^{1 / p}\right)$ which is strictly convex, by Lemma 6.4 combined with our hypotheses on $f$. Therefore, the critical point of this new functional and, consequently, also the critical point of $\mathcal{J}_{\lambda}$ are unique. Both are minimizers of the corresponding functionals.

Finally, assume that $\partial \Omega$ is of class $C^{1, \alpha}$. Then we have $u \in C^{1, \beta}(\bar{\Omega})$ for some $\beta \in$ $(0, \alpha)$, by a regularity result which is due to DiBenedetto [8, Theorem 2, p. 829] and Tolksdorf [38, Theorem 1, p. 127] (interior regularity, shown independently), and to Lieberman [24, Theorem 1, p. 1203] (regularity near the boundary). More precisely, in order to apply their regularity result, one needs to invoke the boundedness of $u \in L^{\infty}(\Omega)$ due to Anane [3, Théorème A.1, p. 96]. Thus, the Hopf maximum principle [37, Prop. 3.2.1 and 3.2.2, p. 801] or [39, Theorem 5, p. 200] can be applied to obtain $\sqrt{6.2}$ as desired.

Applying similar arguments as in the proof above, one can verify the following complementary result for $\lambda=\lambda_{1}$ :

Theorem 6.6. Let $0 \leq f \in L^{\infty}(\Omega)$ with $f \not \equiv 0$ in $\Omega$. Then the functional $\mathcal{J}_{\lambda_{1}}$ possesses no critical point $u \in W_{0}^{1, p}(\Omega)$. Furthermore, $\mathcal{J}_{\lambda_{1}}$ is unbounded from below with

$$
\begin{equation*}
\mathcal{J}_{\lambda_{1}}\left(t \varphi_{1}\right)=-t \int_{\Omega} f \varphi_{1} \mathrm{~d} x \longrightarrow-\infty \quad \text { as } \quad t \rightarrow+\infty \tag{6.3}
\end{equation*}
$$

Proof. On the contrary, assume that $\mathcal{J}_{\lambda_{1}}$ has a critical point $u_{0} \in W_{0}^{1, p}(\Omega)$. In analogy with the proof of Theorem 6.5 above, one shows that $u_{0} \in C^{1, \beta}(\bar{\Omega})$ for some $\beta \in(0, \alpha)$, together with the Hopf maximum principle 6.2 for $u_{0}$. The functional $u \mapsto \mathcal{J}_{\lambda}\left(u^{1 / p}\right)$ being strictly convex on the cone of all functions $u \in C^{1}(\bar{\Omega})$ satisfying (6.2), we conclude that $u_{0}$ is a global minimizer for $\mathcal{J}_{\lambda_{1}}$ over that cone. However, this conclusion contradicts 6.3 . The theorem is proved.

Remark 6.7. If $p \neq 2, f \in L^{\infty}(\Omega)$ changes sign, and $0<\lambda<\lambda_{1}$, then the functional $\mathcal{J}_{\lambda}$ may possess two or more distinct critical points in $W_{0}^{1, p}(\Omega)$. Examples of a suitable function $f$, such that $\mathcal{J}_{\lambda}$ exhibits multiple critical points, have been constructed in Fleckinger et al. [19, Example 2, p. 148] for $1<p<2$ and del Pino, Elgueta, and Manásevich [28, Eq. (5.26), p. 12] for $2<p<\infty$. There, $\Omega \subset \mathbb{R}^{1}$ is a bounded open interval and $\mathcal{J}_{\lambda}$ has a global minimizer together with a saddle point.

Finally, concerning minimizers in the variational formula for $\lambda_{1}$,

$$
\lambda_{1}=\inf \left\{\frac{\int_{\Omega}|\nabla u|^{p} \mathrm{~d} x}{\int_{\Omega}|u|^{p} \mathrm{~d} x}: 0 \neq u \in W_{0}^{1, p}(\Omega)\right\}
$$

we have the following result:
Theorem 6.8. A minimizer $u \in W_{0}^{1, p}(\Omega)$ for $\lambda_{1}$ is unique up to a constant multiple, that is, $u=c \varphi_{1}$ for some constant $c \in \mathbb{R}$, where $\varphi_{1} \in W_{0}^{1, p}(\Omega)$ is a minimizer for $\lambda_{1}$ satisfying $\varphi_{1}>0$ a.e. in $\Omega$ and $\int_{\Omega} \varphi_{1}^{p} \mathrm{~d} x=1$. If, in addition, the boundary $\partial \Omega$ of $\Omega$ is of class $C^{1, \alpha}$ for some $\alpha \in(0,1)$, then $\varphi_{1}$ satisfies also the Hopf maximum principle 6.2.

This theorem is due to Anane [2, Théorème 1, p. 727] and Lindqvist [25, Theorem 1.3, p. 157].

Proof. Let $u$ be any (nontrivial) minimizer for $\lambda_{1}$. First, suppose that $u$ changes $\operatorname{sign}$ in $\Omega$. Then we have

$$
\begin{aligned}
\lambda_{1} & =\frac{\int_{\Omega}\left(u^{+}\right)^{p}}{\int_{\Omega}|u|^{p}} \cdot \frac{\int_{\Omega}\left|\nabla u^{+}\right|^{p} \mathrm{~d} x}{\int_{\Omega}\left(u^{+}\right)^{p} \mathrm{~d} x}+\frac{\int_{\Omega}\left(u^{-}\right)^{p}}{\int_{\Omega}|u|^{p}} \cdot \frac{\int_{\Omega}\left|\nabla u^{-}\right|^{p} \mathrm{~d} x}{\int_{\Omega}\left(u^{-}\right)^{p} \mathrm{~d} x} \\
& \geq \lambda_{1}\left(\frac{\int_{\Omega}\left(u^{+}\right)^{p}}{\int_{\Omega}|u|^{p}}+\frac{\int_{\Omega}\left(u^{-}\right)^{p}}{\int_{\Omega}|u|^{p}}\right)=\lambda_{1} .
\end{aligned}
$$

Consequently, both $u^{+}$and $u^{-}$are (nontrivial) minimizers for $\lambda_{1}$. Hence, we must have $u^{+}>0$ and $u^{-}>0$ a.e. in $\Omega$, by the strong maximum principle [37, Prop. 3.2 .2 , p. 801] or [39, Theorem 5, p. 200]. But this is impossible. We conclude that either $u>0$ a.e. in $\Omega$ or else $u<0$ a.e. in $\Omega$.

Second, recall the proof of Theorem 6.5 above and take there $f \equiv 0$ in $\Omega$. Replacing $u$ by $-u$ if necessary, we may assume that $u>0$ a.e. in $\Omega$. For such $u$, the functional $u \mapsto \mathcal{J}_{\lambda}\left(u^{1 / p}\right)$ is ray-strictly convex, by Lemma 6.4. Therefore, the critical point of this new functional and, consequently, also the critical point of $\mathcal{J}_{\lambda}$ are unique up to a constant multiple.

Finally, the Hopf maximum principle $\sqrt{6.2}$ for $\varphi_{1}$ is proved in the same way as in Theorem 6.5.

## 7. Minimization with constraint

Recall the orthogonal decomposition $W_{0}^{1, p}(\Omega)=\operatorname{lin}\left\{\varphi_{1}\right\} \oplus W_{0}^{1, p}(\Omega)^{\top}$ induced by the inner product in $L^{2}(\Omega)$. For $u \in W_{0}^{1, p}(\Omega)$ we write $u=\tau \varphi_{1}+u^{\top}$ with $\tau \in \mathbb{R}$ and $\int_{\Omega} u^{\top} \varphi_{1} \mathrm{~d} x=0$. In analogy with the Rayleigh quotient in 1.2 , we have introduced another quotient in (1.6),

$$
\Lambda_{\infty} \stackrel{\text { def }}{=} \inf \left\{\frac{\int_{\Omega}\left|\nabla u^{\top}\right|^{p} \mathrm{~d} x}{\int_{\Omega}\left|u^{\top}\right|^{p} \mathrm{~d} x}: 0 \neq u \in W_{0}^{1, p}(\Omega)^{\top}\right\}
$$

Clearly, $\lambda_{1}<\Lambda_{\infty}<\infty$, because $\lambda_{1}$ is a simple eigenvalue of $-\Delta_{p}$. (If $\Omega$ has reflection symmetry, one can show $\Lambda_{\infty}=\lambda_{2}$, the second eigenvalue of $-\Delta_{p}$.)

Let $\lambda<\Lambda_{\infty}$ and consider the functional $\mathcal{J}_{\lambda}(u)=\mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ with $\tau \in \mathbb{R}$ being fixed (but arbitrary) and $u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$ variable. Then the restricted functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ is coercive on $W_{0}^{1, p}(\Omega)^{\top}$ and thus possesses a global minimizer $u_{\tau}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$. Such a global minimizer satisfies the boundary value problem

$$
\begin{gather*}
-\Delta_{p}\left(\tau \varphi_{1}+u^{\top}\right)=\lambda\left|\tau \varphi_{1}+u^{\top}\right|^{p-2}\left(\tau \varphi_{1}+u^{\top}\right)+f(x)+\zeta \cdot \varphi_{1}(x) \text { in } \Omega ; \\
u^{\top}=0 \quad \text { on } \partial \Omega  \tag{7.1}\\
\left\langle u^{\top}, \varphi_{1}\right\rangle=0
\end{gather*}
$$

where $\zeta \in \mathbb{R}$ is a Lagrange multiplier (which is unknown). In particular, when investigating the solvability of this problem, without loss of generality we may assume that $f=f^{\top} \in L^{\infty}(\Omega)^{\top}$, by simply substituting $\zeta$ for $f^{\|}+\zeta$. Notice that, for $u \equiv \tau \varphi_{1}+u^{\top}$ and $f \equiv \zeta \varphi_{1}+f^{\top}$, with $\tau, \zeta \in \mathbb{R}, u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$, and $f^{\top} \in L^{\infty}(\Omega)^{\top}$, we have

$$
\begin{equation*}
\mathcal{J}_{\lambda}(u ; f)=\mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top} ; f^{\top}\right)-\tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2} \tag{7.2}
\end{equation*}
$$

It is now clear that it suffices to determine the properties of $\mathcal{J}_{\lambda}$ in the special case $f=f^{\top} \in L^{\infty}(\Omega)^{\top}$.

By arguments used in the proof of Lemma 4.1 above, we conclude that any minimizing sequence for the restricted functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ on $W_{0}^{1, p}(\Omega)^{\top}$ contains a strongly convergent subsequence $u_{\tau, n}^{\top} \rightarrow u_{\tau}^{\top}$ in $W_{0}^{1, p}(\Omega)$ as $n \rightarrow \infty$, which converges to a global minimizer $u_{\tau}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$. Taking advantage of this technique, it is not difficult to see that

$$
\begin{equation*}
j_{\lambda}(\tau) \stackrel{\text { def }}{=} \inf \left\{\mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right): u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}\right\}=\mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u_{\tau}^{\top}\right) \tag{7.3}
\end{equation*}
$$

is a continuous function of $\tau \in \mathbb{R}$; a complete proof is in Takáč 32, Lemma 7.2, p. 222].

We notice that eq. (7.1) yields $\mathcal{J}_{\lambda}^{\prime}\left(\tau \varphi_{1}+u^{\top}\right)=\zeta \cdot \varphi_{1}$ in $W^{-1, p^{\prime}}(\Omega)$, which entails

$$
\begin{aligned}
\tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2} & =\zeta\left\langle\varphi_{1}, \tau \varphi_{1}+u^{\top}\right\rangle=\left\langle\mathcal{J}_{\lambda}^{\prime}\left(\tau \varphi_{1}+u^{\top}\right), \tau \varphi_{1}+u^{\top}\right\rangle \\
& =p \cdot \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)+(p-1)\left\langle f, \tau \varphi_{1}+u^{\top}\right\rangle
\end{aligned}
$$

Thus, if $f=f^{\top} \in L^{\infty}(\Omega)^{\top}$ and if $u_{\tau}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$ is any global minimizer for the restricted energy functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right)$ on $W_{0}^{1, p}(\Omega)^{\top}$, then the Lagrange multiplier $\zeta=\zeta_{\tau} \in \mathbb{R}$ from the boundary value problem (7.1) satisfies

$$
\begin{aligned}
\tau \zeta_{\tau}\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2} & =p \cdot \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u_{\tau}^{\top}\right)+(p-1)\left\langle f^{\top}, u_{\tau}^{\top}\right\rangle \\
& =p \cdot j_{\lambda}(\tau)+(p-1)\left\langle f^{\top}, u_{\tau}^{\top}\right\rangle
\end{aligned}
$$

Unfortunately, we do not know whether

$$
\begin{equation*}
\tau \mapsto\left\langle f^{\top}, u_{\tau}^{\top}\right\rangle=\int_{\Omega} f^{\top} u_{\tau}^{\top} \mathrm{d} x: \mathbb{R} \rightarrow \mathbb{R} \tag{7.4}
\end{equation*}
$$

is a continuous function of $\tau$ or whether this function is independent from the choice of the global minimizer $u_{\tau}^{\top}$ for the restricted energy functional. Consequently, also $\tau \mapsto \tau \zeta_{\tau}$ might not be continuous. Fortunately, and this fact is very important for us, we will be able to determine the asymptotic behavior of both, the global minimizer $u_{\tau}^{\top}$ and the Lagrange multiplier $\zeta_{\tau}$ rather precisely, depending on $\tau$, as $\tau \rightarrow \pm \infty$. Applying these asymptotic estimates to eq. 7.4 we will easily derive
the asymptotic behavior of the (continuous) function $j_{\lambda}(\tau)$ as $\tau \rightarrow \pm \infty$. It will depend on whether $1<p<2, p=2$, or $2<p<\infty$.

For instance, if $\lambda=\lambda_{1}$ and $f=f^{\top} \in L^{\infty}(\Omega), f^{\top} \not \equiv 0$ in $\Omega$, it has been shown in Takáč [34, Lemma 9.7, p. 466] that $j_{\lambda_{1}}(\tau)=-c \cdot|\tau|^{2-p}+o\left(|\tau|^{2-p}\right)$ as $\tau \rightarrow \pm \infty$, where $c=c\left(f^{\top}\right)>0$ is a constant depending on $f^{\top}$. (Of course, the symbol "o(.)" means $o(t) / t \rightarrow 0$ as either $t \rightarrow \pm \infty$ or $t \rightarrow 0$ in $\mathbb{R}, t \neq 0$.) The proof of this result relies on formula $(\overline{\mathrm{B} .18}$ ) from Proposition $\overline{\mathrm{B} .4}$ in the Appendix, $\S \overline{\mathrm{B} .2}$. For $p>2$ it follows that the function $j_{\lambda_{1}}$ possesses a global minimizer $\tau_{0} \in \mathbb{R}$, even though $j_{\lambda_{1}}$ is not coercive. For $1<p<2$ it possesses a global maximizer $\tau_{0} \in \mathbb{R}$ and tends to $-\infty$ as $\tau \rightarrow \pm \infty$. For $p=2$ it is an easy exercise to see that $j_{\lambda_{1}}(\tau) \equiv \mathrm{const}<0$ is a constant function.

## 8. Some elementary analysis

We know that $j_{\lambda}: \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function. Let us consider the following two standard cases:
(i) If $j_{\lambda}$ has a local minimum at $\tau=\tau_{0}$, then $u_{\tau_{0}}=\tau_{0} \varphi_{1}+u_{\tau_{0}}^{\top}$ is a local minimizer for $\mathcal{J}_{\lambda}: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$. (This claim is easy to verify.)
(ii) If $j_{\lambda}$ has a local maximum $\left(=\beta_{\lambda}\right)$ at $\tau=\tau_{0}$, then we do not know if $u_{\tau_{0}}=\tau_{0} \varphi_{1}+u_{\tau_{0}}^{\top}$ is a critical point for the energy functional $\mathcal{J}_{\lambda}$. However, again by arguments used in the proof of Lemma 4.1, it is not difficult to show the following lemma about the existence of a pair of sub- and supersolutions.

Lemma 8.1. Let $-\infty<\lambda<\Lambda_{\infty}$ and $f \in L^{\infty}(\Omega), f \not \equiv 0$. Assume that $j_{\lambda}: \mathbb{R} \rightarrow \mathbb{R}$ attains a local maximum $\beta_{\lambda}$ at some point $\tau_{0} \in \mathbb{R}$. Then there exist two functions

$$
\underline{u}=\tau_{0} \varphi_{1}+\underline{u}^{\top}, \quad \bar{u}=\tau_{0} \varphi_{1}+\bar{u}^{\top} \quad \text { with } \quad \underline{u}^{\top}, \bar{u}^{\top} \in W_{0}^{1, p}(\Omega)^{\top},
$$

such that

$$
\begin{equation*}
\mathcal{J}_{\lambda}\left(\tau_{0} \varphi_{1}+\underline{u}^{\top}\right)=\mathcal{J}_{\lambda}\left(\tau_{0} \varphi_{1}+\bar{u}^{\top}\right)=j_{\lambda}\left(\tau_{0}\right)=\beta_{\lambda} \tag{8.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{J}_{\lambda}^{\prime}\left(\tau_{0} \varphi_{1}+\underline{u}^{\top}\right)=\underline{\zeta} \cdot \varphi_{1}, \quad \mathcal{J}_{\lambda}^{\prime}\left(\tau_{0} \varphi_{1}+\bar{u}^{\top}\right)=\bar{\zeta} \cdot \varphi_{1} \tag{8.2}
\end{equation*}
$$

hold for some (Lagrange multipliers) $\underline{\zeta}, \bar{\zeta} \in \mathbb{R}$ with $\underline{\zeta} \leq 0 \leq \bar{\zeta}$.
A proof of this lemma is given in Takáč [35, Lemma 4.6, p. 715]. It is based on a construction of two arbitrary sequences $\left\{\tau_{n}^{\prime}\right\}_{n=1}^{\infty}$ and $\left\{\tau_{n}^{\prime \prime}\right\}_{n=1}^{\infty}$, satisfying

$$
-\infty<\tau_{1}^{\prime}<\tau_{2}^{\prime}<\cdots<\tau_{n}^{\prime}<\cdots<\tau_{0}<\cdots<\tau_{n}^{\prime \prime}<\cdots<\tau_{2}^{\prime \prime}<\tau_{1}^{\prime \prime}<\infty
$$

with $\tau_{n}^{\prime} \nearrow \tau_{0}$ and $\tau_{n}^{\prime \prime} \searrow \tau_{0}$ as $n \rightarrow \infty$, such that for some functions $u_{\tau}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$ indexed by $\tau \in\left\{\tau_{n}^{\prime}\right\}_{n=1}^{\infty} \cup\left\{\tau_{n}^{\prime \prime}\right\}_{n=1}^{\infty}$ we have

$$
\begin{equation*}
\mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u_{\tau}^{\top}\right)=j_{\lambda}(\tau) \quad\left(\leq \beta_{\lambda}\right) \tag{8.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathcal{J}_{\lambda}^{\prime}\left(\tau \varphi_{1}+u_{\tau}^{\top}\right)=\zeta_{\tau} \cdot \varphi_{1} \quad \text { with some } \quad \zeta_{\tau} \in \mathbb{R} \tag{8.4}
\end{equation*}
$$

for every $\tau \in\left\{\tau_{n}^{\prime}\right\}_{n=1}^{\infty} \cup\left\{\tau_{n}^{\prime \prime}\right\}_{n=1}^{\infty}$, where

$$
\begin{equation*}
\zeta_{\tau_{n}^{\prime}} \geq 0 \quad \text { and } \quad \zeta_{\tau_{n}^{\prime \prime}} \leq 0 \quad \text { for all } n=1,2, \ldots \tag{8.5}
\end{equation*}
$$

If $\underline{\zeta}=0$ and/or $\bar{\zeta}=0$, then we have a critical point for $\mathcal{J}_{\lambda}$; one may call it a simple saddle point for $\mathcal{J}_{\lambda}$. Otherwise, $\underline{u}$ is called a strict subsolution of the problem $\mathcal{J}_{\lambda}^{\prime}(u)=0$, because of $\underline{\zeta}<0$, and similarly, $\bar{u}$ is called a strict supersolution, because of $\bar{\zeta}>0$. In order to deduce the existence of a solution to $\mathcal{J}_{\lambda}^{\prime}(u)=0$ from
the existence of a pair of (strict) sub- and supersolutions, $\underline{u}$ and $\bar{u}$, we will apply a topological method (Leray-Schauder degree theory). Needless to say, we will lose all information about the "geometry" of the functional $\mathcal{J}_{\lambda}$ near such a critical point.

## 9. Existence by a topological DEGREE

Let us recall that the first (smallest) eigenvalue $\lambda_{1}$ of the positive Dirichlet $p$-Laplacian $-\Delta_{p}$ is simple with the associated eigenfunction $\varphi_{1}$ normalized by $\varphi_{1}>0$ in $\Omega$ and $\left\|\varphi_{1}\right\|_{L^{p}(\Omega)}=1$, by Anane [2, Théorème 1, p. 727] or Lindqvist [25, Theorem 1.3, p. 157]. We have $\varphi_{1} \in L^{\infty}(\Omega)$ by Anane [3. Théorème A.1, p. 96]. Consequently, recalling hypothesis (H1), we get even $\varphi_{1} \in C^{1, \beta}(\bar{\Omega})$ for some $\beta \in(0, \alpha)$, by a regularity result due to DiBenedetto [8, Theorem 2, p. 829] and Tolksdorf [38, Theorem 1, p. 127] (interior regularity), and to Lieberman [24, Theorem 1, p. 1203] (regularity near the boundary). The constant $\beta$ depends solely on $\alpha, N$, and $p$. We keep the meaning of the constants $\alpha$ and $\beta$ throughout the entire lecture notes. Finally, the Hopf maximum principle (see Tolksdorf [37, Prop. 3.2.1 and 3.2.2, p. 801] or Vázquez [39, Theorem 5, p. 200]) renders

$$
\begin{equation*}
\varphi_{1}>0 \quad \text { in } \Omega \quad \text { and } \quad \frac{\partial \varphi_{1}}{\partial \nu}<0 \quad \text { on } \partial \Omega . \tag{9.1}
\end{equation*}
$$

As usual, $\partial / \partial \nu$ denotes the outer normal derivative on $\partial \Omega$. We set

$$
U \stackrel{\text { def }}{=}\left\{x \in \Omega: \nabla \varphi_{1}(x) \neq \mathbf{0}\right\}, \quad \text { hence } \Omega \backslash U=\left\{x \in \Omega: \nabla \varphi_{1}(x)=\mathbf{0}\right\}
$$

and observe that $\Omega \backslash U$ is a compact subset of $\Omega$, by 9.1 .
As we have already mentioned at the end of Section 7 , if $f=f^{\top} \in L^{\infty}(\Omega)$, $f^{\top} \not \equiv 0$ in $\Omega$, then for $1<p<2$ the function $j_{\lambda_{1}}(\tau)$ possesses a global maximizer $\tau_{0} \in \mathbb{R}$ and tends to $-\infty$ as $|\tau| \rightarrow \infty$. As this topological method is typical for the case $1<p<2$ and $\lambda=\lambda_{1}$, to which it has been originally applied in Drábek and Holubová [14, Theorem 1.1, p. 184], we will explain it for this parameter setting. Of course, it works similarly for any $p>1$ and any $\lambda<\Lambda_{\infty}$; see Takáč [35].

So fix $1<p<2$ and $\lambda=\lambda_{1}$. In the (resonant) Dirichlet problem

$$
\begin{equation*}
-\Delta_{p} u=\lambda_{1}|u|^{p-2} u+f(x) \quad \text { in } \Omega ; \quad u=0 \quad \text { on } \partial \Omega, \tag{9.2}
\end{equation*}
$$

assume $f=f^{\top}+\zeta \varphi_{1}$, where $f^{\top} \in L^{\infty}(\Omega)^{\top}, f^{\top} \not \equiv 0$ in $\Omega$, and $\zeta \in \mathbb{R}$. If $f^{\top}$ is continuous in a an open neighborhood of the (compact) set $\left\{x \in \Omega: \nabla \varphi_{1}(x)=\mathbf{0}\right\}$ and if $|\zeta|$ is small enough, then it is possible to show that the functional $\mathcal{J}_{\lambda_{1}}$ has a "saddle point geometry" ( Drábek and Holubová [14, Lemma 2.1, p. 185]). If also $\zeta \neq 0$, then $\mathcal{J}_{\lambda_{1}}$ satisfies the so-called "Palais-Smale condition" ( 14 , Lemma 2.2, p. 188]). Thus, if $|\zeta|>0$ is small enough, a "saddle point theorem" from Rabinowitz [30, Theorem 4.6, p. 24] guarantees the existence of a critical point $u_{0} \in W_{0}^{1, p}(\Omega)$ for $\mathcal{J}_{\lambda_{1}}$. If $\zeta=0$, the validity of the Palais-Smale condition for $\mathcal{J}_{\lambda_{1}}$ is still an open question and, as indicated in Drábek and Takáč [15], it might not be satisfied at all; see [15, Theorem 4.1, pp. 47-48] for difficulties and hints to ramifications. This means that we will not be able to apply the saddle point theorem [30, Theorem 4.6, p. 24] to treat the most natural case $\zeta=0$. Taking $|\zeta|>0$ small enough one can apply this theorem to construct only a pair of strict sub- and supersolutions, $\underline{u}$ and $\bar{u}$, as in the previous section (Section 8). Notice that the construction in the previous section does not require $f^{\top}$ to be continuous
in a an open neighborhood of the (compact) set $\Omega \backslash U$ defined above. Besides, it gives

$$
\begin{equation*}
\left\langle\underline{u}, \varphi_{1}\right\rangle=\left\langle\bar{u}, \varphi_{1}\right\rangle=\tau_{0}\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2} \quad \text { with some } \tau_{0} \in \mathbb{R} . \tag{9.3}
\end{equation*}
$$

However, it uses the asymptotic behavior $j_{\lambda_{1}}(\tau) \rightarrow-\infty$ as $\tau \rightarrow \pm \infty$ which is not easy to establish (except for the case when $f^{\top}$ is continuous in an open neighborhood of $\Omega \backslash U)$.

We will therefore use a topological (hence, nonvariational) method to handle this situation. It has been introduced in De Coster and Henrard [6, Theorem 8.2, p. 448] for semilinear elliptic boundary value problems. Given a pair of unordered sub- and supersolutions, a fixed point mapping is constructed first and then its Leray-Schauder degree is computed. We follow the presentation given in Takáč [35, §4.5, pp. 727-733].
Theorem 9.1. Let $1<p<\infty, \lambda=\lambda_{1}$, and $f=\zeta \varphi_{1}+f^{\top}$ with some $\zeta \in \mathbb{R}$ and $f^{\top} \in L^{\infty}(\Omega)^{\top}$, $f^{\top} \not \equiv 0$ in $\Omega$. Assume that $\underline{u}, \bar{u} \in W_{0}^{1, p}(\Omega)$ is a pair of strict sub- and supersolutions of the problem $\mathcal{J}_{\lambda_{1}}^{\prime}(u)=0$ as described in Lemma 8.1. (In particular, $\underline{u}$ and $\bar{u}$ are unordered, by eq. (9.3).) Then the Dirichlet problem $\mathcal{J}_{\lambda_{1}}^{\prime}(u)=0$ possesses a weak solution $u \in W_{0}^{1, p}(\Omega)$.

We remark that $\underline{u}, \bar{u} \in C^{1, \beta}(\bar{\Omega})$ for some $\beta \in(0, \alpha)$, by the regularity result mentioned above [3, 8, 24, 38. We use this fact repeatedly in an essential way.

We will prove Theorem 9.1 using the topological (Leray-Schauder) degree. In the proof of the next lemma we obtain another pair of sub- and supersolutions, ordered by " $\leq$ ", which provides lower and upper bounds for the unordered pair.

Recalling $\varphi_{1} \in C^{1, \beta}(\bar{\Omega})$ and the Hopf maximum principle (9.1), we introduce the space $X$ of all functions $\phi \in C(\bar{\Omega})$ such that

$$
\begin{equation*}
\|\phi\|_{X} \stackrel{\text { def }}{=} \sup _{\Omega}\left(|\phi| / \varphi_{1}\right)<\infty . \tag{9.4}
\end{equation*}
$$

Then $X$ endowed with the norm $\|\cdot\|_{X}$ is a Banach space. Notice that the embeddings $C_{0}^{1}(\bar{\Omega}) \hookrightarrow X \hookrightarrow C(\bar{\Omega})$ are continuous, where

$$
C_{0}^{1}(\bar{\Omega}) \stackrel{\text { def }}{=}\left\{\phi \in C^{1}(\bar{\Omega}): \phi=0 \text { on } \partial \Omega\right\}
$$

is a closed linear subspace of $C^{1}(\bar{\Omega})$.
We denote $\mathbb{R}_{+}=[0, \infty)$. Given any $R>0$, let us define the function $\gamma_{R}: \mathbb{R}_{+} \rightarrow$ $[0,1]$ by

$$
\gamma_{R}(\xi) \stackrel{\text { def }}{=} \begin{cases}1 & \text { if } 0 \leq \xi \leq R  \tag{9.5}\\ 2-(\xi / R) & \text { if } R<\xi \leq 2 R \\ 0 & \text { if } \xi>2 R\end{cases}
$$

Notice that $\gamma_{R}$ is a monotone decreasing, Lipschitz-continuous function. Next, for $u \in X$ we define $G_{R}(u): \Omega \rightarrow \mathbb{R}$ by

$$
\left[G_{R}(u)\right](x) \stackrel{\text { def }}{=} \begin{cases}\lambda_{1}|u|^{p-2} u+\gamma_{R}\left(\frac{|u(x)|}{\varphi_{1}(x)}\right) f(x) & \text { if } \frac{|u(x)|}{\varphi_{1}(x)} \leq 2 R  \tag{9.6}\\ -\lambda_{1}\left[2 R \varphi_{1}(x)\right]^{p-1} & \text { if } \frac{u(x)}{\varphi_{1}(x)}<-2 R \\ \lambda_{1}\left[2 R \varphi_{1}(x)\right]^{p-1} & \text { if } \frac{u(x)}{\varphi_{1}(x)}>2 R\end{cases}
$$

at every $x \in \Omega$. As $\gamma_{R}(2 \varepsilon)=0, f \in L^{\infty}(\Omega)$, and $u / \varphi_{1} \in L^{\infty}(\Omega)$, it is easy to see that the mapping

$$
G_{R}: u \mapsto G_{R}(u): X \rightarrow L^{\infty}(\Omega)
$$

is continuous.
Lemma 9.2. Assume that $f$ and the sub- and supersolutions $\underline{u}$ and $\bar{u}$ are exactly as in Lemma 8.1. Let $\left\{\eta_{n}\right\}_{n=1}^{\infty} \subset(0,1)$ and $\left\{R_{n}\right\}_{n=1}^{\infty} \subset(0, \infty)$ satisfy $\eta_{n} \rightarrow 0$ and $R_{n} \rightarrow \infty$ as $n \rightarrow \infty$. Finally, for each $n=1,2, \ldots$, let $u_{n} \in W_{0}^{1, p}(\Omega)$ have the following properties:
(i) $u_{n} \in C_{0}^{1}(\bar{\Omega})$;
(ii) $u_{n}$ is a weak solution of the boundary value problem

$$
\begin{equation*}
-\Delta_{p} u_{n}=\left[G_{R_{n}}\left(u_{n}\right)\right](x) \quad \text { in } \Omega ; \quad u_{n}=0 \quad \text { on } \partial \Omega \tag{9.7}
\end{equation*}
$$

(iii) there exist points $x_{n}^{\prime}, x_{n}^{\prime \prime} \in \Omega$ such that

$$
\begin{align*}
& u_{n}\left(x_{n}^{\prime}\right) \leq \underline{u}\left(x_{n}^{\prime}\right)+\eta_{n} R_{n} \varphi_{1}\left(x_{n}^{\prime}\right),  \tag{9.8}\\
& u_{n}\left(x_{n}^{\prime \prime}\right) \geq \bar{u}\left(x_{n}^{\prime \prime}\right)-\eta_{n} R_{n} \varphi_{1}\left(x_{n}^{\prime \prime}\right) . \tag{9.9}
\end{align*}
$$

Then, given any $0<\varepsilon \leq 1$, there exists an integer $n_{\varepsilon} \geq 1$ such that inequalities

$$
\begin{equation*}
\left\|u_{n}\right\|_{C^{1}(\bar{\Omega})}+\sup _{\Omega}\left(\left|u_{n}\right| / \varphi_{1}\right) \leq \varepsilon R_{n} \tag{9.10}
\end{equation*}
$$

hold for every $n \geq n_{\varepsilon}$. In particular, for every $n \geq n_{\varepsilon}$, $u_{n}$ is a weak solution of problem 9.2 as well, i.e., $\mathcal{J}_{\lambda_{1}}^{\prime}\left(u_{n}\right)=0$.

In fact, we wish to prove Theorem 9.1 by computing the Leray-Schauder degree in subsets of

$$
\begin{aligned}
& \mathcal{U}_{n}^{\prime}=\left\{u \in X: u(x)>\underline{u}(x)+\eta_{n} \varphi_{1}(x)\right\} \\
& \mathcal{U}_{n}^{\prime \prime}=\left\{u \in X: u(x)<\bar{u}(x)-\eta_{n} \varphi_{1}(x)\right\}
\end{aligned}
$$

Here, we have dropped the factor $R_{n}(\geq 1$ for all $n$ sufficiently large) from the product $\eta_{n} R_{n}$ in 9.8 and 9.9 ; the (weaker) inequalities above will do. Lemma 9.2 is needed to take care of the complement (in $X$ ) of the union of these two sets, $X \backslash\left(\mathcal{U}_{n}^{\prime} \cup \mathcal{U}_{n}^{\prime \prime}\right)$. Clearly, the "pointwise boundedness" conditions 9.8) and 9.9) are very generous as $\eta_{n}$ and $R_{n}$ are not related.

Proof of Lemma 9.2. The "normalized" sequence $v_{n} \stackrel{\text { def }}{=} R_{n}^{-1} u_{n}(n=1,2, \ldots)$ satisfies

$$
\begin{equation*}
-\Delta_{p} v_{n}=R_{n}^{-(p-1)}\left[G_{R_{n}}\left(R_{n} v_{n}\right)\right](x) \quad \text { in } \Omega ; \quad v_{n}=0 \quad \text { on } \partial \Omega \tag{9.11}
\end{equation*}
$$

Since $\partial \Omega$ is assumed to be of class $C^{1, \alpha}$, for some $0<\alpha<1$, we conclude that $v_{n} \in C^{1, \beta}(\bar{\Omega})$, for some $\beta \in(0, \alpha)$, and the sequence $\left\{v_{n}\right\}_{n=1}^{\infty}$ is bounded in $C^{1, \beta}(\bar{\Omega})$, by the regularity result mentioned above [3, 8, 24, 38. Now, for any fixed $\beta^{\prime} \in(0, \beta)$, we can apply Arzelà-Ascoli's theorem in $C^{1, \beta^{\prime}}(\bar{\Omega})$ to the sequence $\left\{v_{n}\right\}_{n=1}^{\infty}$ to obtain a convergent subsequence $v_{n} \rightarrow v^{*}$ in $C^{1, \beta^{\prime}}(\bar{\Omega})$ as $n \rightarrow \infty$. Letting $n \rightarrow \infty$ in the weak formulation of problem 9.11 , and recalling our notation from 9.5 , we arrive at

$$
\begin{equation*}
-\Delta_{p} v^{*}=\left[H\left(v^{*}\right)\right](x) \quad \text { in } \Omega ; \quad v^{*}=0 \quad \text { on } \partial \Omega \tag{9.12}
\end{equation*}
$$

where $H(v): \Omega \rightarrow \mathbb{R}$ is defined by

$$
[H(v)](x) \stackrel{\text { def }}{=} \begin{cases}\lambda_{1}|v|^{p-2} v & \text { if } \frac{|v(x)|}{\varphi_{1}(x)} \leq 2 \\ -\lambda_{1}\left[2 \varphi_{1}(x)\right]^{p-1} & \text { if } \frac{v(x)}{\varphi_{1}(x)}<-2 \\ \lambda_{1}\left[2 \varphi_{1}(x)\right]^{p-1} & \text { if } \frac{v(x)}{\varphi_{1}(x)}>2\end{cases}
$$

at every $x \in \Omega$, for $v \in X$. As both functions $v_{ \pm}= \pm 2 \varphi_{1}$ are solutions of problem 9.12 and $H\left(v_{-}\right) \leq H\left(v^{*}\right) \leq H\left(v_{+}\right)$in $\Omega$, we conclude that $v^{*}$ itself must satisfy $v_{-} \leq v^{*} \leq v_{+}$in $\Omega$, by the weak comparison principle (see e.g. 37, Lemma 3.1, p. 800]). Consequently, eq. 9.12 reads

$$
-\Delta_{p} v^{*}=\lambda_{1}\left|v^{*}\right|^{p-2} v^{*} \quad \text { in } \Omega ; \quad v^{*}=0 \quad \text { on } \partial \Omega
$$

Eigenvalue $\lambda_{1}$ of $-\Delta_{p}$ being simple, this equation forces $v^{*}=\kappa \varphi_{1}$ in $\Omega$ for some $\kappa \in \mathbb{R}$ with $|\kappa| \leq 2$.

Next, we observe that (9.8) and (9.9), respectively, are equivalent to

$$
\begin{align*}
& v_{n}\left(x_{n}^{\prime}\right) \leq R_{n}^{-1} \underline{u}\left(x_{n}^{\prime}\right)+\eta_{n} \varphi_{1}\left(x_{n}^{\prime}\right)  \tag{9.13}\\
& v_{n}\left(x_{n}^{\prime \prime}\right) \geq R_{n}^{-1} \bar{u}\left(x_{n}^{\prime \prime}\right)-\eta_{n} \varphi_{1}\left(x_{n}^{\prime \prime}\right) \tag{9.14}
\end{align*}
$$

From $v_{n} \rightarrow v^{*}=\kappa \varphi_{1}$ in $C^{1, \beta^{\prime}}(\bar{\Omega})$ as $n \rightarrow \infty$ we deduce that $v_{n} / \varphi_{1} \rightarrow v^{*} / \varphi_{1}=$ $\kappa$ in $L^{\infty}(\Omega)$. We claim that $\kappa=0$ which implies the conclusion of our lemma immediately. So, on the contrary, suppose that $\kappa \neq 0$.

If $\kappa>0$ then there exists an integer $n_{0} \geq 1$ such that $v_{n} / \varphi_{1} \geq \frac{1}{2} \kappa$ in $\Omega$ for all $n \geq n_{0}$. Combining this inequality with 9.13 we arrive at

$$
R_{n}^{-1} \frac{\underline{u}\left(x_{n}^{\prime}\right)}{\varphi_{1}\left(x_{n}^{\prime}\right)}+\eta_{n} \geq \frac{v_{n}\left(x_{n}^{\prime}\right)}{\varphi_{1}\left(x_{n}^{\prime}\right)} \geq \frac{\kappa}{2}>0 \quad \text { for all } n \geq n_{0}
$$

But this contradicts $R_{n} \rightarrow \infty$ and $\eta_{n} \rightarrow 0$ as $n \rightarrow \infty$.
Similarly, if $\kappa<0$ then $v_{n} / \varphi_{1} \leq \frac{1}{2} \kappa$ in $\Omega$ for all $n \geq n_{0}$. Combining this inequality with 9.14 we get

$$
R_{n}^{-1} \frac{\bar{u}\left(x_{n}^{\prime \prime}\right)}{\varphi_{1}\left(x_{n}^{\prime \prime}\right)}-\eta_{n} \leq \frac{v_{n}\left(x_{n}^{\prime \prime}\right)}{\varphi_{1}\left(x_{n}^{\prime \prime}\right)} \leq \frac{\kappa}{2}<0 \quad \text { for all } n \geq n_{0}
$$

Again, this contradicts $R_{n} \rightarrow \infty$ and $\eta_{n} \rightarrow 0$. The lemma follows from $R_{n}^{-1} u_{n}=$ $v_{n} \rightarrow \kappa \varphi_{1}=0$ in $C_{0}^{1}(\bar{\Omega})$.

Let us denote by $X_{+}$the positive cone in $X$, that is,

$$
X_{+} \stackrel{\text { def }}{=}\{\phi \in X: \phi \geq 0 \text { in } \Omega\},
$$

and by $\stackrel{\circ}{X}_{+}$its (topological) interior,

$$
\stackrel{\circ}{X}_{+}=\left\{\phi \in X: \phi \geq \kappa \varphi_{1} \text { in } \Omega \text { for some } \kappa \in(0, \infty)\right\}
$$

Given any $a, b \in X$, we write $a \ll b$ (or, equivalently, $b \gg a$ ) if and only if $b-a \in \stackrel{\circ}{X}_{+}$. We denote

$$
[a, b] \stackrel{\text { def }}{=}\{\phi \in X: a \leq \phi \leq b \text { in } \Omega\} \text { and }[[a, b]] \stackrel{\text { def }}{=}\{\phi \in X: a \ll \phi \ll b\}
$$

Notice that $[[a, b]]$ is the (topological) interior of $[a, b]$ in $X$.
Proof of Theorem 9.1. With regard to Lemma 9.2 above, it suffices to construct a weak solution $u_{n} \in W_{0}^{1, p}(\Omega)$ of problem (9.7) with properties (i), (ii), and (iii) of Lemma 9.2, for each $n=1,2, \ldots$ The sequences $\left\{\eta_{n}\right\}_{n=1}^{\infty} \subset(0,1)$ and $\left\{R_{n}\right\}_{n=1}^{\infty} \subset$ $(0, \infty)$ may be chosen arbitrarily with $\eta_{n} \rightarrow 0$ and $R_{n} \rightarrow \infty$ as $n \rightarrow \infty$.

Given $0<r<\infty$, we denote by

$$
\mathcal{B}_{r}=\left\{u \in X:\|u\|_{X}<r\right\}
$$

the open ball in $X$ with radius $r$ centered at the origin, and by

$$
\overline{\mathcal{B}}_{r}=\left\{u \in X:\|u\|_{X} \leq r\right\}
$$

its closure in $X$. Set

$$
R_{0}=\max \left\{\|\underline{u}\|_{X},\|\bar{u}\|_{X}\right\}+1
$$

In particular, recalling (9.5), for $R \geq R_{0}$ we have $\gamma_{R}\left(|\underline{u}| / \varphi_{1}\right)=1$ and $\gamma_{R}\left(|\bar{u}| / \varphi_{1}\right)=$ 1 throughout $\Omega$. Hence, from now on, we may assume $R_{n} \geq R_{0}$ for all $n \geq 1$. Let us fix any $n \geq 1$ and recall $0<\eta_{n}<1 \leq R_{n}<\infty$.

Now we follow Drábek and Holubová [14, proof of Lemma 2.4, pp. 191-192. First, fix any number $\varrho>3 R_{n}$. We define the (fixed point) mapping

$$
\mathcal{T}: \overline{\mathcal{B}}_{\varrho} \rightarrow X: u \mapsto \mathcal{T} u \stackrel{\text { def }}{=} \tilde{u}
$$

where $\tilde{u} \in C_{0}^{1}(\bar{\Omega})$ is the unique weak solution of

$$
\begin{equation*}
-\Delta_{p} \tilde{u}=\left[G_{R_{n}}(u)\right](x) \quad \text { in } \Omega ; \quad \tilde{u}=0 \quad \text { on } \partial \Omega \tag{9.15}
\end{equation*}
$$

We claim that $\mathcal{T}$ is compact, i.e., $\mathcal{T}$ is continuous and its image is contained in a compact set. Indeed, it is easy to see that $\mathcal{T}: \overline{\mathcal{B}}_{\varrho} \subset X \rightarrow W_{0}^{1, p}(\Omega)$ is continuous with the image $\mathcal{T}\left(\overline{\mathcal{B}}_{\varrho}\right)$ being a bounded set in $C^{1, \beta}(\bar{\Omega})$, by regularity [3, 8, 24, 38]. Consequently, for any fixed $\beta^{\prime} \in(0, \beta)$,

$$
\mathcal{T}: \overline{\mathcal{B}}_{\varrho} \subset X \rightarrow C^{1, \beta^{\prime}}(\bar{\Omega}) \cap W_{0}^{1, p}(\Omega)
$$

is continuous with $\mathcal{T}\left(\overline{\mathcal{B}}_{\varrho}\right)$ having compact closure in each of the spaces

$$
C^{1, \beta^{\prime}}(\bar{\Omega}) \cap W_{0}^{1, p}(\Omega) \hookrightarrow C_{0}^{1}(\bar{\Omega}) \hookrightarrow X
$$

by Arzelà-Ascoli's theorem. Thus, $\mathcal{T}: \overline{\mathcal{B}}_{\varrho} \rightarrow X$ is compact.
If there exists a fixed point $u_{n} \in \overline{\mathcal{B}}_{\varrho}$ of $\mathcal{T}$, i.e., $\mathcal{T} u_{n}=u_{n}$, such that both inequalities (9.8) and 9.9) are satisfied, then we are done. So let us assume the contrary, that is, if $u_{n} \in \mathcal{B}_{\varrho}$ satisfies $\mathcal{T} u_{n}=u_{n}$ then at least one of the following two inequalities must be valid:

$$
\begin{array}{ll}
u_{n}(x)>\underline{u}(x)+\eta_{n} \varphi_{1}(x) & \text { for all } x \in \Omega \\
u_{n}(x)<\bar{u}(x)-\eta_{n} \varphi_{1}(x) & \text { for all } x \in \Omega . \tag{9.17}
\end{array}
$$

Notice that we have dropped the factor $R_{n}(\geq 1)$ from the product $\eta_{n} R_{n}$ in 9.8 and (9.9); the (weaker) inequalities above will suffice to get a contradiction. Consequently, we get $u_{n} \gg \underline{u}$ or $u_{n} \ll \bar{u}$ in $X$. Moreover, both inequalities cannot hold simultaneously; for otherwise we would have $\underline{u} \leq \bar{u}$ throughout $\Omega$ which forces $\underline{u}=\bar{u}$ in $\Omega$, owing to eq. (9.3). Hence, there exists a point $y \in \Omega$ such that $\bar{u}(y)<\underline{u}(y)$. From either inequality $u_{n} \gg \underline{u}$ or $u_{n} \ll \bar{u}$ in $X$ we deduce easily that $u_{n} \in X \backslash \overline{\mathcal{S}}$ where $\overline{\mathcal{S}}$ denotes the closure in $X$ of the set

$$
\mathcal{S}=\left\{u \in X: u\left(x^{\prime}\right)<\underline{u}\left(x^{\prime}\right) \text { and } u\left(x^{\prime \prime}\right)>\bar{u}\left(x^{\prime \prime}\right) \text { for some } x^{\prime}, x^{\prime \prime} \in \Omega\right\}
$$

Clearly, $\mathcal{S}$ is open in $X$ with the complement

$$
X \backslash \mathcal{S}=\{u \in X: u \geq \underline{u} \text { in } \Omega\} \cup\{u \in X: u \leq \bar{u} \text { in } \Omega\} .
$$

Next, we introduce the functions $A_{ \pm} \stackrel{\text { def }}{=} \pm 3 R_{n} \varphi_{1}$. We have $A_{ \pm} \in \mathcal{B}_{\varrho}$, together with $A_{-} \ll \underline{u} \ll A_{+}$and $A_{-} \ll \bar{u} \ll A_{+}$. Hence, also $\underline{u}, \bar{u} \in \mathcal{B}_{\varrho}$. Observe that both
$A_{-}$and $\underline{u}\left(A_{+}\right.$and $\left.\bar{u}\right)$ are strict subsolutions (supersolutions, respectively) of the boundary value problem 9.7); more precisely, they satisfy

$$
\begin{gather*}
-\Delta_{p} u-\left[G_{R_{n}}(u)\right](x) \leq-\phi_{1}(x)<0 \quad\left(\geq \phi_{1}(x)>0\right) \quad \text { in } \Omega ;  \tag{9.18}\\
u=0 \quad \text { on } \partial \Omega
\end{gather*}
$$

where $\phi_{1}=c_{R_{n}} \cdot \min \left\{\varphi_{1}, \varphi_{1}^{p-1}\right\}$ with some constant $c_{R_{n}}>0$. This in turn implies $u \ll \mathcal{T} u(u \gg \mathcal{T} u)$ in $X$, by the strong comparison principle due to Cuesta and Takáč 4, Theorem 1, p. 81] (see also [5, Theorem 2.1, p. 725]). We remark that the connectedness of the boundary $\partial \Omega$, assumed in [4, Theorem 1], is not needed here owing to the strict inequality in eq. 9.18 throughout the domain $\Omega$. Hence, in the proof of [4, Theorem 1, p. 81], one may apply [4, Prop. 3, p. 82] on any connected component of the boundary $\partial \Omega$.

Finally, let $\operatorname{deg}[I-\mathcal{T} ; \mathcal{U}, 0]$ denote the Leray-Schauder degree of the mapping $I-\mathcal{T}: \overline{\mathcal{U}} \rightarrow X$ relative to the origin $0 \in X$, where $\mathcal{U}$ is any open set in $X$ such that $\mathcal{U} \subset \mathcal{B}_{\varrho}$ and $0 \notin(I-\mathcal{T})(\partial \mathcal{U})$. As usual, $I$ stands for the identity mapping and $\partial \mathcal{U}$ for the boundary of $\mathcal{U}$ in $X$. We compute this degree in the sets $\left[\left[A_{-}, A_{+}\right]\right]$, $\left[\left[A_{-}, \bar{u}_{n}\right]\right],\left[\left[\underline{u}_{n}, A_{+}\right]\right]$, and $\mathcal{S} \cap\left[\left[A_{-}, A_{+}\right]\right]$, all of which are open in $X$. Clearly, the last three sets, $\left[\left[A_{-}, \bar{u}_{n}\right]\right]$, $\left[\left[\underline{u}_{n}, A_{+}\right]\right]$, and $\mathcal{S} \cap\left[\left[A_{-}, A_{+}\right]\right]$, are pairwise disjoint and the union of their closures equals $\left[A_{-}, A_{+}\right] \subset \overline{\mathcal{B}}_{\varrho}$. Using the excision property of the Leray-Schauder degree, we compute

$$
\begin{align*}
& \operatorname{deg}\left[I-\mathcal{T} ;\left[\left[A_{-}, A_{+}\right]\right], 0\right] \\
& =\operatorname{deg}\left[I-\mathcal{T} ;\left[\left[A_{-}, \bar{u}_{n}\right]\right], 0\right]+\operatorname{deg}\left[I-\mathcal{T} ;\left[\left[\underline{u}_{n}, A_{+}\right]\right], 0\right]  \tag{9.19}\\
& \quad+\operatorname{deg}\left[I-\mathcal{T} ; \mathcal{S} \cap\left[\left[A_{-}, A_{+}\right]\right], 0\right]
\end{align*}
$$

Recalling the fact that $\mathcal{T}$ has no fixed point $u_{n} \in \overline{\mathcal{B}}_{\varrho}$ on the boundary of any of the sets $\left[\left[A_{-}, A_{+}\right]\right]$, $\left[\left[A_{-}, \bar{u}_{n}\right]\right]$, and $\left[\left[\underline{u}_{n}, A_{+}\right]\right]$, we may apply [14, Lemma 2.3, p. 190] to conclude that

$$
\begin{aligned}
\operatorname{deg}\left[I-\mathcal{T} ;\left[\left[A_{-}, A_{+}\right]\right], 0\right] & =\operatorname{deg}\left[I-\mathcal{T} ;\left[\left[A_{-}, \bar{u}_{n}\right]\right], 0\right] \\
& =\operatorname{deg}\left[I-\mathcal{T} ;\left[\left[\underline{u}_{n}, A_{+}\right]\right], 0\right]=1
\end{aligned}
$$

Furthermore, since $\mathcal{T}$ has no fixed point in $\overline{\mathcal{S}}$, we must have also

$$
\operatorname{deg}\left[I-\mathcal{T} ; \mathcal{S} \cap\left[\left[A_{-}, A_{+}\right]\right], 0\right]=0
$$

Inserting these results into eq. (9.19) we arrive at a contradiction, $1=1+1+0$.
Hence, we have proved that, indeed, there exists a fixed point $u_{n} \in \overline{\mathcal{B}}_{\varrho}$ of $\mathcal{T}$ such that both inequalities $(9.8)$ and $(9.9)$ are valid. So Lemma 9.2 can be applied and Theorem 9.1 is proved.

## 10. Large critical points of $\mathcal{J}_{\lambda}$

In the previous two sections we have shown how to obtain a (weak) solution to the resonant problem (9.2) (i.e., when $\lambda=\lambda_{1}$ ), first for $p>2$ (in Section 8) and then for $1<p<2$ (in Section 99. When $\lambda<\Lambda_{\infty}$ and $f \equiv \zeta \varphi_{1}+f^{\top}$ with some $\zeta \in \mathbb{R}$ and $f^{\top} \in L^{\infty}(\Omega)^{\top}, f^{\top} \not \equiv 0$ in $\Omega$, a refinement of the techniques from Sections 8 and 9 yields multiple critical points of $\mathcal{J}_{\lambda}$ for suitable combinations of the pair of parameters $(\lambda, \zeta)$ near $\left(\lambda_{1}, 0\right)$. Such critical points $u=\tau\left(\varphi_{1}+v^{\top}\right)$ are distinguished from each other by the size of $\tau \in \mathbb{R}$; one has $v^{\top} \rightarrow 0$ in $C^{1}(\bar{\Omega})$ as $\tau \rightarrow \pm \infty$. Thus, such "large solutions" of the equation $\mathcal{J}_{\lambda}^{\prime}(u)=0$ need to be obtained. This is done
as follows, using the function $j_{\lambda} \equiv j_{\lambda}(\cdot ; f) \mathbb{R} \rightarrow \mathbb{R}$ and starting from the simpliest case $\lambda=\lambda_{1}$ and $\zeta=0$.

The results obtained in Section 8 (Section 9, respectively) apply to this case if $p>2(1<p<2)$. Indeed, from the end of Section 7 we recall $j_{\lambda_{1}}(\tau)=$ $-c \cdot|\tau|^{2-p}+o\left(|\tau|^{2-p}\right)$ as $\tau \rightarrow \pm \infty$, where $c=c\left(f^{\top}\right)>0$ is a constant depending on $f^{\top}$. The function $j_{\lambda_{1}}$ being continuous, it attains a global minimum (maximum, respectively) at $\tau_{0} \in \mathbb{R}$ if $p>2(1<p<2)$. We note that this scenario is a special case of what has been described at the beginning of Section 8 in cases (i) and (ii). Next, in $f \equiv \zeta \varphi_{1}+f^{\top}$ the original choice of $\zeta=0$ is perturbed to $\zeta \neq 0$ with $|\zeta|$ small enough. Since formula 7.2 yields

$$
\begin{equation*}
j_{\lambda}(\tau ; f)=j_{\lambda}\left(\tau ; f^{\top}\right)-\tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2} \tag{10.1}
\end{equation*}
$$

this means that for $\lambda=\lambda_{1}$ the second term on the right-hand side above, the linear function $\tau \mapsto \tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2}$, determines the asymptotic behavior of $j_{\lambda_{1}}(\tau ; f)$ as $\tau \rightarrow \pm \infty$ :

$$
\begin{aligned}
j_{\lambda_{1}}(\tau ; f) & =-c\left(f^{\top}\right) \cdot|\tau|^{2-p}-\tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2}+o\left(|\tau|^{2-p}\right) \\
& =-|\tau|^{2-p}\left(c\left(f^{\top}\right)+|\tau|^{p-2} \tau \zeta\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{2}+o(1)\right)
\end{aligned}
$$

It is not difficult to see that if $|\zeta|>0$ is small enough then $j_{\lambda_{1}}$ possesses a local minimizer and a local maximizer, such that one of them stays in a bounded interval and the other tends to $+\infty$ or $-\infty$ as $\zeta \rightarrow 0$, depending on the signs of $p-2$ and $\zeta$. Consequently, the local minimizer and maximizer are distinguished from each other by the size of their absolute values. Finally, keeping $\zeta$ constant (with $|\zeta|>0$ small enough), we perturb $\lambda=\lambda_{1}$ to $\lambda$ near $\lambda_{1}$ (with $\left|\lambda-\lambda_{1}\right|>0$ small enough) in order to obtain a second local minimizer (local maximizer, respectively) for $j_{\lambda}$ if $\lambda>\lambda_{1}$ $\left(\lambda<\lambda_{1}\right)$, whose absolute value is even much larger than the absolute values of the local minimizers and maximizers constructed before for the case $\lambda=\lambda_{1}$. With some additional caution about the size of critical points, the (multiple) critical points of $\mathcal{J}_{\lambda}$ corresponding to the local minimizers and maximizers of $j_{\lambda}$ are now obtained by the methods presented in Sections 8 and 9 . We refer the interested reader to the article Takáč [35, Sect. 4 and 5] for (rather complicated) technical details.

An essential tool in the perturbation process just described is, of course, continuous dependence of the function $j_{\lambda}\left(\tau ; \zeta \varphi_{1}+f^{\top}\right)$ on all (real) variables $\tau, \lambda$, and $\zeta$, which is proved in Takáč [32, Lemma 7.2, p. 222].

## 11. A collection of main results

In order to give an idea to the reader interested in what kinds of results can be obtained by the techniques from Sections 8 and 9 applied to the energy functional $\mathcal{J}_{\lambda}$ (concerning multiple critical points and their classification), below we present a collection of the main results from Takáč [35, Sect. 2, pp. 698-705]. Some of them appeared before in [10, 11, 12, 13, 14, 20, 22, 26, 27, 22, 32, 33, 34,

Recall that we always assume that the domain $\Omega \subset \mathbb{R}^{N}$ satisfies hypothesis (H1).
The first (smallest) eigenvalue $\lambda_{1}$ of the positive Dirichlet $p$-Laplacian $-\Delta_{p}$ for $1<p<\infty$ is given by formula 1.2 . We recall from the beginning of Section 9 that the eigenvalue $\lambda_{1}$ is simple and the eigenfunction $\varphi_{1}$ associated with $\lambda_{1}$ can be normalized by $\varphi_{1}>0$ in $\Omega$ and $\left\|\varphi_{1}\right\|_{L^{p}(\Omega)}=1$. Furthermore, we have $\varphi_{1} \in C^{1, \beta}(\bar{\Omega})$
for some $\beta \in(0, \alpha)$, together with the Hopf maximum principle

$$
\begin{equation*}
\varphi_{1}>0 \quad \text { in } \Omega \quad \text { and } \quad \frac{\partial \varphi_{1}}{\partial \nu}<0 \quad \text { on } \partial \Omega \tag{9.1}
\end{equation*}
$$

There, we have also introduced the set

$$
U=\left\{x \in \Omega: \nabla \varphi_{1}(x) \neq \mathbf{0}\right\}
$$

Often, a function $u \in L^{1}(\Omega)$ will be decomposed as the orthogonal sum $u=$ $u^{\|} \cdot \varphi_{1}+u^{\top}$ according to (1.4). Given a linear subspace $\mathcal{M}$ of $L^{1}(\Omega)$ with $\varphi_{1} \in \mathcal{M}$, we write

$$
\mathcal{M}^{\top} \stackrel{\text { def }}{=}\left\{u \in \mathcal{M}:\left\langle u, \varphi_{1}\right\rangle=0\right\}
$$

The following concept is tailored for our treatment of the functional $\mathcal{J}_{\lambda}$ defined in (1.5); we recall

$$
j_{\lambda}(\tau) \stackrel{\text { def }}{=} \min _{u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}} \mathcal{J}_{\lambda}\left(\tau \varphi_{1}+u^{\top}\right) \quad \text { for } \tau \in \mathbb{R}
$$

Definition 11.1. $u_{0} \in W_{0}^{1, p}(\Omega)$ will be called a simple saddle point for $\mathcal{J}_{\lambda}$ if $u_{0}=\tau_{0} \varphi_{1}+u_{0}^{\top}$ is a critical point for $\mathcal{J}_{\lambda}, u_{0}^{\top}$ is a global minimizer for the restricted functional $u^{\top} \mapsto \mathcal{J}_{\lambda}\left(\tau_{0} \varphi_{1}+u^{\top}\right)$ on $W_{0}^{1, p}(\Omega)^{\top}$, and the function $j_{\lambda}: \mathbb{R} \rightarrow \mathbb{R}$ attains a local maximum at $\tau_{0}$.

A more general type of a saddle point is obtained in Rabinowitz 30, Theorem 4.6 , p. 24]. From now on we separate the cases $p>2$ and $1<p<2$, respectively.
11.1. The degenerate case $2<p<\infty$. Let $2<p<\infty$. We introduce a new norm on $W_{0}^{1, p}(\Omega)$ by

$$
\begin{equation*}
\|v\|_{\varphi_{1}} \stackrel{\text { def }}{=}\left(\int_{\Omega}\left|\nabla \varphi_{1}\right|^{p-2}|\nabla v|^{2} \mathrm{~d} x\right)^{1 / 2} \quad \text { for } v \in W_{0}^{1, p}(\Omega) \tag{11.1}
\end{equation*}
$$

and denote by $\mathcal{D}_{\varphi_{1}}$ the completion of $W_{0}^{1, p}(\Omega)$ with respect to this norm. That the seminorm 11.1) is in fact a norm on $W_{0}^{1, p}(\Omega)$ follows from an inequality in 32, ineq. (4.7), p. 200]. The Hilbert space $\mathcal{D}_{\varphi_{1}}$ coincides with the domain of the closure of the quadratic form $\mathcal{Q}_{0}: W_{0}^{1, p}(\Omega) \rightarrow \mathbb{R}$ given by

$$
\begin{align*}
2 \cdot \mathcal{Q}_{0}(\phi)= & \int_{\Omega}\left|\nabla \varphi_{1}\right|^{p-2}\left\{|\nabla \phi|^{2}+(p-2)\left|\frac{\nabla \varphi_{1}}{\left|\nabla \varphi_{1}\right|} \cdot \nabla \phi\right|^{2}\right\} \mathrm{d} x  \tag{11.2}\\
& -\lambda_{1}(p-1) \int_{\Omega} \varphi_{1}^{p-2} \phi^{2} \mathrm{~d} x, \quad \phi \in W_{0}^{1, p}(\Omega)
\end{align*}
$$

We impose the following additional hypothesis on the domain $\Omega$ :
(H2) If $N \geq 2$ and $\partial \Omega$ is not connected, then there is no function $v \in \mathcal{D}_{\varphi_{1}}$, $\mathcal{Q}_{0}(v)=0$, with the following four properties:
(i) $v=\varphi_{1} \cdot \chi_{S}$ a.e. in $\Omega$, where $S \subset \Omega$ is Lebesgue measurable, $0<|S|_{N}<$ $|\Omega|_{N} ;$
(ii) $\bar{S}$ is connected and $\bar{S} \cap \partial \Omega \neq \emptyset$;
(iii) if $V$ is a connected component of $U$, then either $V \subset S$ or else $V \subset$ $\Omega \backslash S$;
(iv) $(\partial S) \cap \Omega \subset \Omega \backslash U$. ( Recall $\Omega \backslash U=\left\{x \in \Omega: \nabla \varphi_{1}(x)=\mathbf{0}\right\}$.)

It has been conjectured in Takáč [32, §2.1] that (H2) always holds true provided (H1) is satisfied. The cases, when $\Omega$ is either an interval in $\mathbb{R}^{1}$ or else $\partial \Omega$ is connected if $N \geq 2$, have been covered within the proof of Proposition 4.4 in 32, pp. 202-205] which claims:

Proposition 11.2. Let $2<p<\infty$ and assume both hypotheses (H1) and (H2). Then a function $u \in \mathcal{D}_{\varphi_{1}}$ satisfies $\mathcal{Q}_{0}(u)=0$ if and only if $u=\kappa \varphi_{1}$ for some constant $\kappa \in \mathbb{R}$.

In particular, there is no function $v \in \mathcal{D}_{\varphi_{1}}, \mathcal{Q}_{0}(v)=0$, with properties (i)-(iv). This proposition is the only place where $(\overline{\mathrm{H} 2})$ is needed explicitly. All other results in these notes depend solely on the conclusion of the proposition which, in turn, implies (H2).

We write $f \equiv f^{\top}+\zeta \varphi_{1}$ with $f^{\top} \in K$ and $\zeta \in \mathbb{R}$, where $K$ is as follows:
(H3) $K$ is a nonempty, weakly-star compact set in $L^{\infty}(\Omega)$ such that $0 \notin K$ and $\left\langle g, \varphi_{1}\right\rangle=0$ for all $g \in K$.
We begin by stating the following existence result which generalizes the existence part of Takáč [32, Theorem 2.2, p. 194].

Theorem 11.3. There exist positive constants $\delta \equiv \delta(K), \delta^{\prime} \equiv \delta^{\prime}(K)$, and $C(K)$ such that, whenever $\lambda \leq \lambda_{1}+\delta, f^{\top} \in K$, and $|\zeta| \leq \delta^{\prime}$, the functional $\mathcal{J}_{\lambda}$ possesses a local minimizer $u_{1} \in W_{0}^{1, p}(\Omega)$ (hence, a weak solution to (1.1)) that satisfies $\left\|u_{1}\right\|_{C^{1, \beta}(\bar{\Omega})} \leq C(K)$. Furthermore, if $\delta_{0}, \delta_{0}^{\prime}>0$ (in place of $\delta$ and $\delta^{\prime}$ ) are arbitrary and $\lambda \leq \lambda_{1}-\delta_{0},|\zeta| \leq \delta_{0}^{\prime}$, the same bound (depending also on $\delta_{0}$ and $\delta_{0}^{\prime}$ ) holds for any global minimizer of $\mathcal{J}_{\lambda}$.

A variational proof of this theorem relies on the methods described in Sections 7 and 8, case (i). It can be found in [35, §6.1, pp. 738-739] (proof of Theorem 2.2 in [35). For all $\lambda<\lambda_{1}$ and $\zeta \in \mathbb{R}$, this result follows from the coercivity of the energy functional $\mathcal{J}_{\lambda}$, whereas for $0<\lambda-\lambda_{1} \leq \delta$ and any $\zeta \in \mathbb{R}$, it can be proved by a well-known argument employing topological degree; see Drábek [9, Theorem 14.18, p. 189]. Finally, for $\lambda=\lambda_{1}$ it has been established in Fleckinger and Takáč [20, Theorem 3.3] and Takáč 32, Theorem 2.2] if $\zeta=0$, and in Takáč 33, Theorem 3.1] if $|\zeta| \leq \delta^{\prime}$.

Remark 11.4. The local minimizer $u_{1} \in W_{0}^{1, p}(\Omega)$ described in Theorem 11.3 is the same as the one obtained in Theorems 11.5, 11.7, and 11.8 below.

Our second theorem is a multiplicity result for the resonant value $\lambda=\lambda_{1}$. Although it has been obtained originally in [33, Theorem 3.1], its present form (taken from [35, Theorem 2.4, p. 701]) is more specific about the qualitative description of solutions.

Theorem 11.5. There exists a constant $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that problem 1.1. with $\lambda=\lambda_{1}$ and $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least two (distinct) weak solutions $u_{1}, u_{2}$ specified as follows, whenever $f^{\top} \in K$ and $0<|\zeta| \leq \delta^{\prime}$ : Functional $\mathcal{J}_{\lambda_{1}}$ (which is unbounded from below) possesses a local minimizer $u_{1} \in W_{0}^{1, p}(\Omega)$ and another critical point $u_{2} \in W_{0}^{1, p}(\Omega)$.

The proof of this theorem can be derived from that of Theorem 11.3 , see 35 , §6.2, pp. 739-741] (proof of Theorem 2.4 in 35).
Remark 11.6. The critical point $u_{2} \in W_{0}^{1, p}(\Omega)$ obtained in Theorem 11.5 above is constructed from a suitable pair of sub- and supersolutions to problem 1.1 satisfying (1.7) and 1.8), respectively, with $\lambda=\lambda_{1}$. This method is a refinement of the topological degree arguments described in Section 9 . If the sub- and supersolutions coincide, then $u_{2}=\underline{u}=\bar{u}$ is a simple saddle point for $\mathcal{J}_{\lambda_{1}}, u_{2}=\tau_{2} \varphi_{1}+u_{2}^{\top}$, and, moreover, $j_{\lambda_{1}}$ is differentiable at $\tau_{2}$ with vanishing derivative, $j_{\lambda_{1}}^{\prime}\left(\tau_{2}\right)=0$.

Analogous remarks apply to all critical points (other than local minimizers) obtained in our theorems below, Theorems 11.7 and 11.8 in this paragraph, and Theorems $11.13,11.15,11.16$, and 11.17 in the next one ( $\$ 11.2$ ).

The following two theorems on the existence of at least three solutions to the Dirichlet problem (1.1) are the main new results for $p>2$ obtained in 35. First, we consider the subcritical case $\lambda_{1}-\delta \leq \lambda<\lambda_{1}$.

Theorem 11.7. There exists a constant $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that, for any $d \in$ $\left(0, \delta^{\prime}\right)$, there is another constant $\delta \equiv \delta(K, d)>0$ such that problem 1.1 with $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least three (pairwise distinct) weak solutions $u_{1}, u_{2}, u_{3}$ specified as follows, whenever $\lambda_{1}-\delta \leq \lambda<\lambda_{1}, f^{\top} \in K$, and $d \leq|\zeta| \leq \delta^{\prime}$ : Functional $\mathcal{J}_{\lambda}$ (which is bounded from below) possesses two local minimizers $u_{1}, u_{2} \in W_{0}^{1, p}(\Omega)$ of which at least one is global, and another critical point $u_{3} \in W_{0}^{1, p}(\Omega)$.

The proof of this theorem is derived from those of Theorems 11.3 and 11.5. see [35, §6.3, pp. 742-744] (proof of Theorem 2.6 in [35]).

Finally, we treat the supercritical case $\lambda_{1}<\lambda \leq \lambda_{1}+\delta$. Here we obtain the following multiplicity and uniform boundedness results for problem 1.1):
Theorem 11.8. There exist constants $\delta \equiv \delta(K)>0$ and $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that problem (1.1) with $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least three (pairwise distinct) weak solutions $u_{1}, u_{2}, u_{3}$ specified as follows, whenever $\lambda_{1}<\lambda \leq \lambda_{1}+\delta, f^{\top} \in K$, and $|\zeta| \leq \delta^{\prime}:$ Functional $\mathcal{J}_{\lambda}$ (which is unbounded from below) possesses a local minimizer $u_{1} \in W_{0}^{1, p}(\Omega)$ and two other critical points $u_{2}, u_{3} \in W_{0}^{1, p}(\Omega)$.

The proof of this theorem is derived from that of Theorem 11.3, see [35, §6.4, pp. 745-746] (proof of Theorem 2.7 in [35]).

Remark 11.9. In Theorem 11.5, the orthogonal projections of $u_{1}$ and $u_{2}$ onto $\operatorname{lin}\left\{\varphi_{1}\right\}$ satisfy $u_{1}^{\|}<u_{2}^{\|}$if $\zeta>0$, and $u_{1}^{\|}>u_{2}^{\|}$if $\zeta<0$. In Theorem 11.7. $u_{3}^{\|}$lies between $u_{1}^{\|}$and $u_{2}^{\|}$, and in Theorem 11.8, $u_{1}^{\|}$lies between $u_{2}^{\|}$and $u_{3}^{\|}$.

For the question of boundedness of the solution set for problem (1.1) with $\lambda$ near $\lambda_{1}$, we refer to Drábek et al. [13] and Takáč [32, Sect. 2] and [33, Prop. 6.1]. Although the variational methods developed in our present lecture notes are clearly not suitable for resolving this question, in the proofs of all our theorems one makes essential use of [33, Prop. 6.1] (stated as Proposition B.4 in the Appendix, $\$$ B.2 which in turn provides the following answer in the special case $\lambda=\lambda_{1}$; see [33, Theorem 3.2]:
Theorem 11.10. Let $f^{\top}$ be as in Theorem 11.3 above. If $\zeta=0$ then the set of all weak solutions to problem (1.1) with $\lambda=\lambda_{1}$ is bounded in $C^{1, \beta}(\bar{\Omega})$. Given any $\delta>0$, this set is bounded in $C^{1, \beta}(\bar{\Omega})$ uniformly for all $|\zeta| \geq \delta$ as well.

This theorem is proved in [35, §6.5, p. 747] (proof of Theorem 2.9 in [35]).
In contrast with Theorem 11.3, if $|\zeta|$ in $f \equiv f^{\top}+\zeta \varphi_{1}$ is "too large" relative to the size of $\left\|f^{\top}\right\|_{L^{\infty}(\Omega)}$, say $|\bar{\zeta}| \geq \delta>0$, then problem 1.1) with $\lambda=\lambda_{1}$ has no weak solution; see [32, Corollary 2.4, p. 195] or [33, Theorem 3.1]:
Corollary 11.11. Given an arbitrary function $g \in L^{\infty}(\Omega)$ with $0 \leq g \not \equiv 0$ in $\Omega$, there exists a constant $\gamma \equiv \gamma(g)>0$ with the following property: If $f \in L^{\infty}(\Omega)$, $f \not \equiv 0$, is such that

$$
f=f^{g} \cdot g+\bar{f}^{g} \quad \text { with some } f^{g} \in \mathbb{R} \quad \text { and } \bar{f}^{g} \in L^{\infty}(\Omega)
$$

and $\left\|\bar{f}^{g}\right\|_{L^{\infty}(\Omega)} \leq \gamma\left|f^{g}\right|$, then problem (1.1) with $\lambda=\lambda_{1}$ has no weak solution.
Equivalently, given $g$ as above, notice that there is an open cone $\mathcal{C}$ in $L^{\infty}(\Omega)$ with vertex at the origin $(0 \notin \mathcal{C})$ such that $g \in \mathcal{C}$ and problem (1.1) with $\lambda=\lambda_{1}$ has no weak solution whenever $f \in \mathcal{C}$. This result improves a nonexistence result due to [17, Théorème 1] (see also [31, Theorem 7.2, p. 154]) for $0 \leq f \not \equiv 0$ in $\Omega$.

As already mentioned in the Introduction, one needs a number of auxiliary results to prove these theorems. Complete proofs can be found in Takáč 35, Sect. 6, pp. 738-747]. Additional results revealing more details about the structure of solutions to problem 1.1) have been established within these proofs, e.g., the positivity or negativity of solutions with a sufficiently large norm.
11.2. The singular case $1<p<2$. We further require hypothesis (H1); H 2 will be replaced by a hypothesis on $f$. In fact, hypothesis (H2) always holds true in this case; see Takáč [32, Sect. 8, p. 225].

Remark 11.12. It is not difficult to verify that the conclusion of Proposition 11.2 remains valid also for $1<p<2$, by [32, Remark 8.1, p. 225].

The Hilbert space $\mathcal{D}_{\varphi_{1}}$, endowed with the norm (11.1) for $p>2$, needs to be redefined for $1<p<2$ as follows: We define $v \in \mathcal{D}_{\varphi_{1}}$ if and only if $v \in W_{0}^{1,2}(\Omega)$, $\nabla v(x)=\mathbf{0}$ for almost every $x \in \Omega \backslash U=\left\{x \in \Omega: \nabla \varphi_{1}(x)=\mathbf{0}\right\}$, and

$$
\begin{equation*}
\|v\|_{\varphi_{1}} \stackrel{\text { def }}{=}\left(\int_{U}\left|\nabla \varphi_{1}\right|^{p-2}|\nabla v|^{2} \mathrm{~d} x\right)^{1 / 2}<\infty . \tag{11.3}
\end{equation*}
$$

Consequently, $\mathcal{D}_{\varphi_{1}}$ endowed with the norm $\|\cdot\|_{\varphi_{1}}$ is continuously embedded into $W_{0}^{1,2}(\Omega)$. We conjecture that $\mathcal{D}_{\varphi_{1}}$ is dense in $L^{2}(\Omega)$. This conjecture would immediately follow from $|\Omega \backslash U|_{N}=0$. The latter holds true if $\Omega$ is convex; then also $\Omega \backslash U$ is a convex set in $\mathbb{R}^{N}$ with empty interior, and hence of zero Lebesgue measure, see [18, Lemma 2.6, p. 55].

If the conjecture is false, we need to consider also the orthogonal complement

$$
\mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}=\left\{v \in L^{2}(\Omega):\langle v, \phi\rangle=0 \text { for all } \phi \in \mathcal{D}_{\varphi_{1}}\right\}
$$

Notice that $v \in \mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}$ implies $v=0$ almost everywhere in $U$. This means that $\mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}$ is isometrically isomorphic to a closed linear subspace of $L^{2}(\Omega \backslash U)$. Moreover, $\chi_{\Omega \backslash U} \notin \mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}$ since $\Omega \backslash U$ is a compact subset of $\Omega$; hence, there is a $C^{1}$ function $\phi \in \mathcal{D}_{\varphi_{1}}, 0 \leq \phi \leq 1$, with compact support in $\Omega$ and such that $\phi=1$ in an open neighborhood of $\Omega \backslash U$.

As above, we write $f \equiv f^{\top}+\zeta \varphi_{1}$ with $f^{\top} \in K$ and $\zeta \in \mathbb{R}$, where our hypothesis on $K$ below admits the possibility $\mathcal{D}_{\varphi_{1}}^{\perp, L^{2}} \neq\{0\}$.
(H3') $K$ is a nonempty, weakly-star compact set in $L^{\infty}(\Omega)$ such that $K \cap \mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}=$ $\emptyset$ and $\left\langle g, \varphi_{1}\right\rangle=0$ for all $g \in K$.
The condition $g \notin \mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}$ is satisfied if $g$ is continuous in $\Omega$ and $g \not \equiv 0$. Our first result for $p<2$ below is an analogue of Theorem 11.3 it generalizes the existence part of Drábek and Holubová [14, Theorem 1.1, p. 184] and Takáč [32, Theorem 2.6, p. 196]. We assume that both hypotheses (H1) and (H3) are satisfied.

Theorem 11.13. There exist positive constants $\delta \equiv \delta(K), \delta^{\prime} \equiv \delta^{\prime}(K)$, and $C(K)$ such that, whenever $\left|\lambda-\lambda_{1}\right| \leq \delta, f^{\top} \in K$, and $|\zeta| \leq \delta^{\prime}$, the functional $\mathcal{J}_{\lambda}$ possesses a critical point $u_{1} \in W_{0}^{1, p}(\Omega)$ (hence, a weak solution to (1.1) that
satisfies $\left\|u_{1}\right\|_{C^{1, \beta}(\bar{\Omega})} \leq C(K)$. Furthermore, if $\delta_{0}, \delta_{0}^{\prime}>0$ (in place of $\delta$ and $\delta^{\prime}$ ) are arbitrary and $\lambda \leq \lambda_{1}-\delta_{0},|\zeta| \leq \delta_{0}^{\prime}$, the same bound (depending also on $\delta_{0}$ and $\delta_{0}^{\prime}$ ) holds for any global minimizer of $\mathcal{J}_{\lambda}$.

A proof is given in [35, §7.1, pp. 747-749] (proof of Theorem 2.12 in [35]). It is based on the topological (Leray-Schauder) degree as described in Section 9 , It has been originally taken from [32, $\S 8.4$, p. 229] and is analogous to that of Theorem 11.3. For all $\lambda \leq \lambda_{1}+\delta, \lambda \neq \lambda_{1}$, and $\zeta \in \mathbb{R}$, this result can be proved in the same way as for $p>2$; see [9, Theorem 14.18, p. 189]. For $\lambda=\lambda_{1}$ it was established in [14, Theorem 1.1] and [33, Theorem 3.5] if $|\zeta| \leq \delta^{\prime}$ (by completely different methods), and in [32, Theorem 2.6] if $\zeta=0$ (by the same variational method we use here).
Remark 11.14. The critical point $u_{1} \in W_{0}^{1, p}(\Omega)$ described in Theorem 11.13 is the same as the one obtained in Theorems 11.15 , 11.16, and 11.17 below.

We recall that Remark 11.6 applies also to all critical points (other than local minimizers) obtained in our theorems throughout this paragraph, Theorems 11.13 . 11.15 , 11.16, and 11.17 .

Again, our second theorem for $p<2$ is a multiplicity result for $\lambda=\lambda_{1}$ taken from [33, Theorem 3.5] in a more specific form obtained in [35, Theorem 2.14, p. 704].

Theorem 11.15. There exists a constant $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that problem 1.1) with $\lambda=\lambda_{1}$ and $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least two (distinct) weak solutions $u_{1}, u_{2}$ specified as follows, whenever $f^{\top} \in K$ and $0<|\zeta| \leq \delta^{\prime}$ : Functional $\mathcal{J}_{\lambda_{1}}$ (which is unbounded from below) possesses a critical point $u_{1} \in W_{0}^{1, p}(\Omega)$ and a local minimizer $u_{2} \in W_{0}^{1, p}(\Omega)$.

The proof of this theorem can be derived from that of Theorem 11.13, see 35, §7.2, pp. 749-750] (proof of Theorem 2.14 in [35]).

The following theorem on the existence of at least three solutions to the Dirichlet problem (1.1) in the subcritical case $\lambda_{1}-\delta \leq \lambda<\lambda_{1}$ is a generalization of 32, Theorem 2.7, p. 196] where it is established for $\zeta=0$ only.

Theorem 11.16. There exist constants $\delta \equiv \delta(K)>0$ and $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that problem (1.1) with $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least three (pairwise distinct) weak solutions $u_{1}, u_{2}, u_{3}$ specified as follows, whenever $\lambda_{1}-\delta \leq \lambda<\lambda_{1}, f^{\top} \in K$, and $|\zeta| \leq \delta^{\prime}$ : Functional $\mathcal{J}_{\lambda}$ (which is bounded from below) possesses a critical point $u_{1} \in W_{0}^{1, p}(\Omega)$ and two (distinct) local minimizers $u_{2}, u_{3} \in W_{0}^{1, p}(\Omega)$ of which at least one is global.

Again, the proof of this theorem is derived from that of Theorem 11.13; see 35, $\S 7.3$, p. 751 ] (proof of Theorem 2.15 in [35).

Our last theorem on the existence of at least three solutions to problem 1.1) appeared for the first time in Takáč [35, Theorem 2.16, p. 705]. Here we consider the supercritical case $\lambda_{1}<\lambda \leq \lambda_{1}+\delta$.

Theorem 11.17. There exists a constant $\delta^{\prime} \equiv \delta^{\prime}(K)>0$ such that, for any $d \in\left(0, \delta^{\prime}\right)$, there is another constant $\delta \equiv \delta(K, d)>0$ such that problem 1.1) with $f \equiv f^{\top}+\zeta \varphi_{1}$ has at least three (pairwise distinct) weak solutions $u_{1}, u_{2}, u_{3}$ specified as follows, whenever $\lambda_{1}<\lambda \leq \lambda_{1}+\delta$, $f^{\top} \in K$, and $d \leq|\zeta| \leq \delta^{\prime}$ : Functional $\mathcal{J}_{\lambda}$ (which is unbounded from below) possesses two (distinct) critical points $u_{1}, u_{2} \in W_{0}^{1, p}(\Omega)$ and a local minimizer $u_{3} \in W_{0}^{1, p}(\Omega)$.

The proof is derived from those of Theorems 11.13 and 11.16 , see 35, §7.4, pp. 751-754] (proof of Theorem 2.16 in [35]).

Remark 11.18. In Theorem 11.15, the orthogonal projections of $u_{1}$ and $u_{2}$ on $\operatorname{lin}\left\{\varphi_{1}\right\}$ satisfy $u_{1}^{\|}<u_{2}^{\|}$if $\zeta<0$, and $u_{1}^{\|}>u_{2}^{\|}$if $\zeta>0$. In Theorem 11.16, $u_{1}^{\|}$lies between $u_{2}^{\|}$and $u_{3}^{\|}$, and in Theorem 11.17, $u_{3}^{\|}$lies between $u_{1}^{\|}$and $u_{2}^{\|}$.

Under the same hypotheses, we obtain the corresponding uniform boundedness result [33, Theorem 3.6]; we refer to [13], [32, Sect. 2], and [33, Prop. 6.1] for additional results:

Theorem 11.19. The conclusion of Theorem 11.10 is valid also for $1<p<2$.
The proof of this theorem is identical with the proof of Theorem 11.10 above ([35, §7.5, p. 754], proof of Theorem 2.18 in [35]).

Finally, the nonexistence for $f \equiv f^{\top}+\zeta \varphi_{1}$ with $|\zeta|$ large enough has been proved in [14, Theorem 1.1, p. 184], [32, Corollary 2.9, p. 197], or [33, Theorem 3.5] in various ways:

Corollary 11.20. Let $g \in L^{\infty}(\Omega)$ be an arbitrary function such that $g \geq 0$ in $\Omega$ and $g \not \equiv 0$. Then the conclusion of Corollary 11.11 is valid also for $1<p<2$.

Complete proofs of all these results can be found in Takáč 35, Sect. 7, pp. 747-754].

## 12. Discussion

The variational method used in this work can be applied to finding critical points of some functionals of the following more general type,

$$
\begin{equation*}
\mathcal{J}_{\lambda}(u) \stackrel{\text { def }}{=} \frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}|u|^{p} \mathrm{~d} x-\int_{\Omega} F(x, u(x)) \mathrm{d} x \tag{12.1}
\end{equation*}
$$

on $W_{0}^{1, p}(\Omega)$. This functional corresponds to the "spectral" Dirichlet problem 1.10), considered in the same setting as problem (1.1), with

$$
F(x, u) \stackrel{\text { def }}{=} \int_{0}^{u} f(x, t) \mathrm{d} t \quad \text { for } x \in \Omega \text { and } u \in \mathbb{R}
$$

The reaction $f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a given function of Carathéodory type with suitable growth or decay properties as $|u| \rightarrow \infty$. For instance, one may assume $f(\cdot, u) \stackrel{*}{ } f_{\infty}$ weakly-star in $L^{\infty}(\Omega)$ as $|u| \rightarrow \infty$, where $f_{\infty} \not \equiv 0$ in $\Omega$.

For $p=2$ both the resonant and nonresonant cases of problem 1.10 have been studied in numerous works; see [9, 12, 22, for references. In contrast, the more
 41 . For technical reasons (e.g., complicated asymptotic expressions), in the present work we have treated only the special case when $f(x, u)$ is independent from the (unknown) state variable $u$, i.e., $f(x, u) \equiv f(x)$ for a.e. $x \in \Omega$, where $f \in L^{\infty}(\Omega)$ with $f \not \equiv 0$ in $\Omega$. The general problem 1.10 can be treated similarly provided $f$ satisfies

$$
\begin{equation*}
f(x, u) /|u|^{p-1} \rightarrow 0 \quad \text { as }|u| \rightarrow \infty \text { uniformly for } x \in \Omega \tag{12.2}
\end{equation*}
$$

Our method applies to a number of related problems at resonance for $\lambda$ near $\lambda_{1}$ that have to be treated individually. We refer the interested reader to [12] and [22].

So let us assume the asymptotic growth condition 12.2 . Obviously, all what is needed is the asymptotic behavior of the function $j_{\lambda_{1}}: \mathbb{R} \rightarrow \mathbb{R}$ near $\pm \infty$, i.e., some analogue of the formula

$$
\begin{equation*}
|\tau|^{p-2} \cdot j_{\lambda_{1}}(\tau ; f) \rightarrow-\mathcal{Q}_{0}(w, w) \quad \text { as }|\tau| \rightarrow \infty \tag{12.3}
\end{equation*}
$$

Here, $w \in \mathcal{D}_{\varphi_{1}}^{\top}$ is the unique weak solution of problem $(\overline{\mathrm{B} .12}$ if $p>2$, and B .13 if $p<2$. (We refer to 35, Lemmas 5.2 (p. 736) and Lemmas 5.3 (p. 737), respectively.) With regard to Proposition B.4 this means investigating sequences of large solutions,

$$
u_{n}=t_{n}^{-1} \varphi_{1}+u_{n}^{\top}=t_{n}^{-1}\left(\varphi_{1}+v_{n}^{\top}\right) \text { with } t_{n} \rightarrow 0 \text { and }\left\|v_{n}^{\top}\right\|_{C^{1, \beta^{\prime}}(\bar{\Omega})} \rightarrow 0 \text { as } n \rightarrow \infty
$$

to the following generalized version of problem $\overline{\mathrm{B} .16}$, see $\$ \overline{\mathrm{~B} .2}$ (Appendix):

$$
\begin{gather*}
-\Delta_{p}\left(t^{-1} \varphi_{1}+u^{\top}\right)-\lambda_{1}\left|t^{-1} \varphi_{1}+u^{\top}\right|^{p-2}\left(t^{-1} \varphi_{1}+u^{\top}\right) \\
=f(x, u(x))^{\top}+\zeta \cdot \varphi_{1}(x) \quad \text { in } \Omega \\
u^{\top}=0 \quad \text { on } \partial \Omega  \tag{12.4}\\
\left\langle u^{\top}, \varphi_{1}\right\rangle=0
\end{gather*}
$$

After a careful inspection of the proof of Proposition B. 4 one finds out that only Theorem B. 2 is needed. Although we will not provide formal proofs of our claims in the present lecture notes, all these auxiliary results can be established without major changes provided $f$ satisfies the following two conditions, cf. Girg and Takáč [22, §2.3, hypothesis $\left(H_{\infty}^{\prime}\right)$ ]:
(f1) $f: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a given function of Carathéodory type such that the function $u \mapsto f(\cdot u)$ maps bounded intervals in $\mathbb{R}$ into bounded sets in $L^{\infty}(\Omega)$.
(f2) $f$ satisfies $f(\cdot, u) / \theta(u) \stackrel{*}{\hookrightarrow} f_{ \pm \infty}$ weakly-star in $L^{\infty}(\Omega)$ as $u \rightarrow \pm \infty$, where $f_{ \pm \infty} \not \equiv 0$ in $\Omega$, and either $\theta(u) \equiv 1$ for $u \in \mathbb{R}$, or else $\theta: \mathbb{R} \rightarrow \mathbb{R}$ is some $C^{1}$ function such that $\theta(0)=0, \theta^{\prime}(u) \neq 0$ for $u \neq 0$,

$$
\lim _{|u| \rightarrow \infty}\left(\theta(u) /|u|^{p-1}\right)=0, \quad \sup _{u \neq 0}\left|\theta^{\prime}(u) u / \theta(u)\right|<\infty
$$

and
$\theta\left(\tau \varphi_{1}(x)\right) / \theta(\tau) \rightarrow \theta_{ \pm \infty}(x) \quad$ uniformly for $x \in \Omega$ as $\tau \rightarrow \pm \infty$,
with $\theta_{ \pm \infty}>0$ in $\Omega$.
In particular, the expression $V_{n}=t_{n}^{1-p} v_{n}^{\top}$ (for $\theta \equiv 1$ ) in Theorem B.2 becomes

$$
V_{n}=\left[t_{n}^{p-1} \theta\left(t_{n}^{-1}\right)\right]^{-1} v_{n}^{\top}
$$

Notice that $t_{n} \rightarrow 0$ entails $t_{n}^{p-1} \theta\left(t_{n}^{-1}\right) \rightarrow 0$. Of course, first, formula B.18 has to be recalculated, and then also formula (12.3).

In contrast with the case $\theta \equiv 1$, two obvious nontrivial examples when $f$ satisfies conditions (f1) and (f2) are as follows:

$$
f(x, u)=f_{\infty}(x)|u|^{q-1}+f_{0}(x, u) ; \quad x \in \Omega, u \in \mathbb{R}
$$

and

$$
f(x, u)=f_{\infty}(x)|u|^{q-2} u+f_{0}(x, u) ; \quad x \in \Omega, u \in \mathbb{R}
$$

where $q$ is a constant, $1<q<p, f_{\infty} \in L^{\infty}(\Omega), f_{\infty} \not \equiv 0$ in $\Omega$, and $f_{0}$ satisfies condition (f1) together with

$$
f_{0}(x, u) /|u|^{q-1} \rightarrow 0 \quad \text { as }|u| \rightarrow \infty \text { uniformly for } x \in \Omega .
$$

Consequently, in condition (f2 $\mid$ we may take $\theta(u)=|u|^{q-1}$ in the former case and $\theta(u)=|u|^{q-2} u$ in the latter one.

The Neumann boundary conditions, $\partial u / \partial \nu=0$ on $\partial \Omega$, can be treated as well by replacing the underlying space $W_{0}^{1, p}(\Omega)$ by $W^{1, p}(\Omega)$. Then $\lambda_{1}=0$ and $\varphi_{1} \equiv$ const $=1 /|\Omega|_{N}^{1 / p}$ in $\Omega$. Hence, the energy functional 12.1 becomes

$$
\begin{align*}
\mathcal{J}_{\lambda}(u) & \equiv \mathcal{J}_{\lambda}\left(\tau+u^{\top}\right) \\
& \stackrel{\text { def }}{=} \frac{1}{p} \int_{\Omega}\left|\nabla u^{\top}\right|^{p} \mathrm{~d} x-\frac{\lambda}{p} \int_{\Omega}\left|\tau+u^{\top}\right|^{p} \mathrm{~d} x-\int_{\Omega} F\left(x, \tau+u^{\top}(x)\right) \mathrm{d} x \tag{12.5}
\end{align*}
$$

for $u \equiv \tau+u^{\top} \in W^{1, p}(\Omega)$, where $\tau \in \mathbb{R}$ and $u^{\top} \in W^{1, p}(\Omega)$ satisfies $\int_{\Omega} u^{\top} \mathrm{d} x=0$. Consequently, the resonant case $\lambda=\lambda_{1}=0$ is somewhat easier to treat than for the Dirichlet boundary conditions. For instance, setting $u^{\top} \equiv 0$ in $\Omega$ we get

$$
j_{0}(\tau) \leq \mathcal{J}_{0}(\tau)=-\int_{\Omega} F(x, \tau) \mathrm{d} x \quad \text { for } \tau \in \mathbb{R}
$$

Thus, as $|\tau| \rightarrow \infty$, if $\int_{\Omega} F(x, \tau) \mathrm{d} x \rightarrow+\infty$ then $j_{0}(\tau) \rightarrow-\infty$.

## Appendix A. Some auxiliary functional-analytic results

A.1. Linearization and quadratic forms. In order to determine the asymptotic behavior of the function $j_{\lambda_{1}}(\tau)$ as $|\tau| \rightarrow \infty$ which has been introduced in eq. (7.3), we will estimate the functional $u^{\top} \mapsto \mathcal{J}_{\lambda_{1}}\left(\tau \varphi_{1}+u^{\top}\right)$ by suitable quadratic forms. We need to compute the first two Fréchet derivatives of the functional $\mathcal{J}_{\lambda_{1}}$, see [32, Sect. 3, p. 197]. Define

$$
\begin{equation*}
\mathcal{F}(u) \stackrel{\text { def }}{=} \frac{1}{p} \int_{\Omega}|\nabla u|^{p} \mathrm{~d} x, \quad u \in W_{0}^{1, p}(\Omega) \tag{A.1}
\end{equation*}
$$

The first Fréchet derivative $\mathcal{F}^{\prime}(u)$ of $\mathcal{F}$ at $u \in W_{0}^{1, p}(\Omega)$ is given by $\mathcal{F}^{\prime}(u)=-\Delta_{p} u$ in $W^{-1, p^{\prime}}(\Omega)$, where $\frac{1}{p}+\frac{1}{p^{\prime}}=1$. The second Fréchet derivative $\mathcal{F}^{\prime \prime}(u)$ is a bit more complicated; if $1<p<2$, it might have to be considered only as a Gâteaux derivative which is not even densely defined: For all $\phi, \psi \in W_{0}^{1, p}(\Omega)$, one has (if $2 \leq p<\infty)$

$$
\begin{align*}
& \left\langle\mathcal{F}^{\prime \prime}(u) \psi, \phi\right\rangle= \\
& \int_{\Omega}|\nabla u|^{p-2}\left\{(\nabla \phi \cdot \nabla \psi)+(p-2)|\nabla u|^{-2}(\nabla u \cdot \nabla \phi)(\nabla u \cdot \nabla \psi)\right\} \mathrm{d} x  \tag{A.2}\\
& =\int_{\Omega}|\nabla u|^{p-2}\left\langle I+(p-2) \frac{\nabla u \otimes \nabla u}{|\nabla u|^{2}}, \nabla \phi \otimes \nabla \psi\right\rangle_{\mathbb{R}^{N \times N}} \mathrm{~d} x .
\end{align*}
$$

Here, $I$ is the identity matrix in $\mathbb{R}^{N \times N}, \mathbf{a} \otimes \mathbf{b}$ is the $(N \times N)$-matrix $\mathbf{T}=\left(a_{i} b_{j}\right)_{i, j=1}^{N}$ for $\mathbf{a}=\left(a_{i}\right)_{i=1}^{N}, \mathbf{b}=\left(b_{i}\right)_{i=1}^{N} \in \mathbb{R}^{N}$, and $\langle\cdot, \cdot\rangle_{\mathbb{R}^{N \times N}}$ is the Euclidean inner product in $\mathbb{R}^{N \times N}$.

For $\mathbf{a} \in \mathbb{R}^{N}(\mathbf{a}=\nabla u$ in our case $), \mathbf{a} \neq \mathbf{0} \in \mathbb{R}^{N}$, we abbreviate

$$
\begin{equation*}
\mathbf{A}(\mathbf{a}) \stackrel{\text { def }}{=}|\mathbf{a}|^{p-2}\left(I+(p-2) \frac{\mathbf{a} \otimes \mathbf{a}}{|\mathbf{a}|^{2}}\right) \tag{A.3}
\end{equation*}
$$

If $p>2$, we set also $\mathbf{A}(\mathbf{0}) \stackrel{\text { def }}{=} \mathbf{0} \in \mathbb{R}^{N \times N}$. For $\mathbf{a} \neq \mathbf{0}, \mathbf{A}(\mathbf{a})$ is a positive definite, symmetric matrix. The spectrum of $|\mathbf{a}|^{2-p} \mathbf{A}(\mathbf{a})$ consists of eigenvalues 1 and $p-1$, whence

$$
\begin{equation*}
\min \{1, p-1\} \leq \frac{\langle\mathbf{A}(\mathbf{a}) \mathbf{v}, \mathbf{v}\rangle_{\mathbb{R}^{N}}}{|\mathbf{a}|^{p-2}|\mathbf{v}|^{2}} \leq \max \{1, p-1\}, \quad \mathbf{a}, \mathbf{v} \in \mathbb{R}^{N} \backslash\{\mathbf{0}\} \tag{A.4}
\end{equation*}
$$

From this point on, until the end of this paragraph, we restrict ourselves to $p \geq 2$. The case $1<p<2$ will be taken care of in the next paragraph, A.2 We rewrite the $p$-homogeneous part of the functional 1.5 with $\lambda=\lambda_{1}$ as follows [32, eq. (4.1), p. 198]:

$$
\begin{align*}
& \mathcal{J}_{\lambda_{1}}\left(\varphi_{1}+\phi\right)+\left\langle f, \varphi_{1}+\phi\right\rangle \\
&= \frac{1}{p} \int_{\Omega}\left|\nabla\left(\varphi_{1}+\phi\right)\right|^{p} \mathrm{~d} x-\frac{\lambda_{1}}{p} \int_{\Omega}\left|\varphi_{1}+\phi\right|^{p} \mathrm{~d} x \\
&= \int_{0}^{1} \int_{\Omega}\left|\nabla\left(\varphi_{1}+s \phi\right)\right|^{p-2} \nabla\left(\varphi_{1}+s \phi\right) \cdot \nabla \phi \mathrm{d} x \mathrm{~d} s  \tag{A.5}\\
&-\lambda_{1} \int_{0}^{1} \int_{\Omega}\left|\varphi_{1}+s \phi\right|^{p-2}\left(\varphi_{1}+s \phi\right) \phi \mathrm{d} x \mathrm{~d} s
\end{align*}
$$

for all $\phi \in W_{0}^{1, p}(\Omega)$. Similarly, using A.2), we get

$$
\begin{equation*}
\mathcal{J}_{\lambda_{1}}\left(\varphi_{1}+\phi\right)+\left\langle f, \varphi_{1}+\phi\right\rangle=\mathcal{Q}_{\phi}(\phi, \phi), \tag{A.6}
\end{equation*}
$$

where $\mathcal{Q}_{\phi}$ is the symmetric bilinear form on $\left[W_{0}^{1, p}(\Omega)\right]^{2}$ defined as follows, using A.3):

$$
\begin{align*}
\mathcal{Q}_{\phi}(v, w) \stackrel{\text { def }}{=} & \int_{\Omega}\left\langle\left[\int_{0}^{1} \mathbf{A}\left(\nabla\left(\varphi_{1}+s \phi\right)\right)(1-s) \mathrm{d} s\right] \nabla v, \nabla w\right\rangle_{\mathbb{R}^{N}} \mathrm{~d} x  \tag{A.7}\\
& -\lambda_{1}(p-1) \int_{\Omega}\left[\int_{0}^{1}\left|\varphi_{1}+s \phi\right|^{p-2}(1-s) \mathrm{d} s\right] v w \mathrm{~d} x
\end{align*}
$$

for $v, w \in W_{0}^{1, p}(\Omega)$. In particular, one has (cf. 11.2) )

$$
2 \cdot \mathcal{Q}_{0}(v, v)=\int_{\Omega}\left\langle\mathbf{A}\left(\nabla \varphi_{1}\right) \nabla v, \nabla v\right\rangle_{\mathbb{R}^{N}} \mathrm{~d} x-\lambda_{1}(p-1) \int_{\Omega} \varphi_{1}^{p-2} v^{2} \mathrm{~d} x
$$

Furthermore, equations (1.2) and A.6) guarantee (see [32, ineq. (4.4), p. 199])

$$
\begin{equation*}
\mathcal{Q}_{0}(\phi, \phi) \geq 0 \quad \text { for all } \phi \in W_{0}^{1, p}(\Omega) \tag{A.8}
\end{equation*}
$$

Form $\mathcal{Q}_{0}$ is closable in $L^{2}(\Omega)$ and the domain of its closure is $\mathcal{D}_{\varphi_{1}}$ (see [32, Sect. 4, p. 201]).
A.2. The weighted Sobolev space $\mathcal{D}_{\varphi_{1}}$. We set $\mathbb{R}_{+}=[0, \infty)$ and begin with a few inequalities from Takáč [32, Lemma A.1, p. 233]. Let $1<p<\infty$ and $p \neq 2$. Assume that $\Theta \in L^{\infty}(0,1)$ satisfies $\Theta \geq 0$ in $(0,1)$ and $T=\int_{0}^{1} \Theta(s) \mathrm{d} s>0$. Then there exists a constant $c_{p}(\Theta)>0$ such that the following inequalities hold true for all $\mathbf{a}, \mathbf{b} \in \mathbb{R}^{N}$ : If $p>2$ then

$$
\begin{align*}
c_{p}(\Theta)^{p-2}\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2} & \leq \int_{0}^{1}|\mathbf{a}+s \mathbf{b}|^{p-2} \Theta(s) \mathrm{d} s  \tag{A.9}\\
& \leq T \cdot\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}
\end{align*}
$$

and if $1<p<2$ and $|\mathbf{a}|+|\mathbf{b}|>0$ then

$$
\begin{align*}
T \cdot\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2} & \leq \int_{0}^{1}|\mathbf{a}+s \mathbf{b}|^{p-2} \Theta(s) \mathrm{d} s  \tag{A.10}\\
& \leq c_{p}(\Theta)^{p-2}\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}
\end{align*}
$$

The inequalities below are a combination of A.4 with A.9) (if $p>2$ ) and A.10 (if $p<2$ ), see 32, Lemma A.2]: If $p>2$ then

$$
\begin{align*}
c_{p}(\Theta)^{p-2}\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}|\mathbf{v}|^{2} & \leq \int_{0}^{1}\langle\mathbf{A}(\mathbf{a}+s \mathbf{b}) \mathbf{v}, \mathbf{v}\rangle \Theta(s) \mathrm{d} s  \tag{A.11}\\
& \leq(p-1) T \cdot\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}|\mathbf{v}|^{2}
\end{align*}
$$

for all $\mathbf{a}, \mathbf{b}, \mathbf{v} \in \mathbb{R}^{N}$, and if $1<p<2$ and $|\mathbf{a}|+|\mathbf{b}|>0$ then

$$
\begin{align*}
(p-1) T \cdot\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}|\mathbf{v}|^{2} & \leq \int_{0}^{1}\langle\mathbf{A}(\mathbf{a}+s \mathbf{b}) \mathbf{v}, \mathbf{v}\rangle \Theta(s) \mathrm{d} s  \tag{A.12}\\
& \leq c_{p}(\Theta)^{p-2}\left(\max _{0 \leq s \leq 1}|\mathbf{a}+s \mathbf{b}|\right)^{p-2}|\mathbf{v}|^{2}
\end{align*}
$$

Several important properties of $\mathcal{D}_{\varphi_{1}}$ established in Takáč 32 are listed below.
The following claim is obvious ([32, Lemma 4.1]): If $1<p<\infty, p \neq 2$, and if (H1) is satisfied, then one has $\mathcal{Q}_{0}\left(\varphi_{1}, \varphi_{1}\right)=0$ and $0 \leq \mathcal{Q}_{0}(v, v)<\infty$ for all $v \in \mathcal{D}_{\varphi_{1}}$.

Now we need to distinguish between the cases $p>2$ and $1<p<2$. Assume $2<p<\infty$ together with (H1). Notice that inequality (A.4) entails

$$
\begin{equation*}
\|v\|_{\varphi_{1}}^{2} \leq \int_{\Omega}\left\langle\mathbf{A}\left(\nabla \varphi_{1}\right) \nabla v, \nabla v\right\rangle_{\mathbb{R}^{N}} \mathrm{~d} x \leq(p-1)\|v\|_{\varphi_{1}}^{2} \quad \text { for } v \in \mathcal{D}_{\varphi_{1}} \tag{A.13}
\end{equation*}
$$

For $0<\delta<\infty$, we denote by

$$
\begin{equation*}
\Omega_{\delta} \stackrel{\text { def }}{=}\{x \in \Omega: \operatorname{dist}(x, \partial \Omega)<\delta\} \tag{A.14}
\end{equation*}
$$

the $\delta$-neighborhood of $\partial \Omega$. Its complement in $\Omega$ is denoted by $\Omega_{\delta}^{\prime}=\Omega \backslash \Omega_{\delta}$.
The following compact embedding result is proved in [32, Lemma 4.2, p. 199].
Lemma A.1. Let $2<p<\infty$ and assume that hypothesis H1 is satisfied. Then we have:
(a) For every $\delta>0$ small enough, $\|\cdot\|_{\varphi_{1}}$ is an equivalent norm on $W_{0}^{1,2}\left(\Omega_{\delta}\right)$.
(b) The embedding $\mathcal{D}_{\varphi_{1}} \hookrightarrow L^{2}(\Omega)$ is compact.

Due to inequality A.13 combined with Lemma A.1, Part (b) above, we can extend the domain of $\mathcal{Q}_{0}$ to $\mathcal{D}_{\varphi_{1}} \times \mathcal{D}_{\varphi_{1}}$. This extension of $\mathcal{Q}_{0}$ is unique and closed in $L^{2}(\Omega)$. We denote by $\mathcal{A}_{\varphi_{1}}$ the Friedrichs representation of the quadratic form $2 \cdot \mathcal{Q}_{0}$ in $L^{2}(\Omega)$; see [23, Theorem VI.2.1, p. 322]. This means that $\mathcal{A}_{\varphi_{1}}$ is a positive semidefinite, selfadjoint linear operator on $L^{2}(\Omega)$ with domain $\operatorname{dom}\left(\mathcal{A}_{\varphi_{1}}\right)$ dense in $\mathcal{D}_{\varphi_{1}}$ and

$$
\left\langle\mathcal{A}_{\varphi_{1}} v, w\right\rangle=2 \cdot \mathcal{Q}_{0}(v, w) \quad \text { for all } v, w \in \operatorname{dom}\left(\mathcal{A}_{\varphi_{1}}\right)
$$

Notice that our definition of $\mathcal{Q}_{0}$ yields $\mathcal{A}_{\varphi_{1}} \varphi_{1}=0$. Since the embedding $\mathcal{D}_{\varphi_{1}} \hookrightarrow$ $L^{2}(\Omega)$ is compact, by Lemma A.1. Part (b), the null space of $\mathcal{A}_{\varphi_{1}}$ denoted by

$$
\operatorname{ker}\left(\mathcal{A}_{\varphi_{1}}\right)=\left\{v \in \operatorname{dom}\left(\mathcal{A}_{\varphi_{1}}\right): \mathcal{A}_{\varphi_{1}} v=0\right\}
$$

is finite-dimensional, by the Riesz-Schauder theorem [23, Theorem III.6.29, p. 187]. Owing to hypothesis (H2), we have even $\operatorname{ker}\left(\mathcal{A}_{\varphi_{1}}\right)=\operatorname{lin}\left\{\varphi_{1}\right\}$, by Proposition 11.2 .

Now we switch to the case $1<p<2$ and again require only (H1). We highlight a few places at which the proof of the boundedness part in Theorem 11.13 differs from that in Theorem 11.3. The most substantial difference is that the role of the compact embedding $\mathcal{D}_{\varphi_{1}} \hookrightarrow L^{2}(\Omega)$ needs to be replaced by that of $W_{0}^{1,2}(\Omega) \hookrightarrow \mathcal{H}_{\varphi_{1}}$, where $\mathcal{H}_{\varphi_{1}}$ is the Hilbert space defined below, $\mathcal{H}_{\varphi_{1}} \hookrightarrow L^{2}(\Omega)$. Let us define another norm on $W_{0}^{1,2}(\Omega)$ by

$$
\begin{equation*}
|v|_{\varphi_{1}} \stackrel{\text { def }}{=}\left(\int_{\Omega} \varphi_{1}^{p-2} v^{2} \mathrm{~d} x\right)^{1 / 2} \quad \text { for } v \in W_{0}^{1,2}(\Omega) \tag{A.15}
\end{equation*}
$$

and denote by $\mathcal{H}_{\varphi_{1}}$ the completion of $W_{0}^{1,2}(\Omega)$ with respect to this norm.
The embeddings below are taken from [32, Lemma 8.2, p. 226].
Lemma A.2. Let $1<p<2$ and let hypothesis H1 be satisfied. Then we have:
(a) The embedding $\mathcal{H}_{\varphi_{1}} \hookrightarrow L^{2}(\Omega)$ is continuous.
(b) The embedding $W_{0}^{1,2}(\Omega) \hookrightarrow \mathcal{H}_{\varphi_{1}}$ is compact.

## Appendix B. Auxiliary results for the equation with $\Delta_{p}$

B.1. An approximation scheme for a solution. Here we investigate an approximation scheme for a weak solution to the Dirichlet problem (1.1) in order to compute the asymptotic behavior of its large solutions provided $f \in L^{\infty}(\Omega)$ satisfies $f \not \equiv 0$ and $\lambda$ is close to $\lambda_{1}$. The condition $\left\langle f, \varphi_{1}\right\rangle=0$ is not required in this paragraph.

We study the sequence of Dirichlet problems for $n=1,2, \ldots$,

$$
\begin{equation*}
-\Delta_{p} u_{n}=\left(\lambda_{1}+\mu_{n}\right)\left|u_{n}\right|^{p-2} u_{n}+f_{n}(x) \quad \text { in } \Omega ; \quad u_{n}=0 \quad \text { on } \partial \Omega \tag{B.1}
\end{equation*}
$$

that is, in the weak formulation, for all $\phi \in W_{0}^{1, p}(\Omega)$,

$$
\begin{equation*}
\int_{\Omega}\left|\nabla u_{n}\right|^{p-2}\left\langle\nabla u_{n}, \nabla \phi\right\rangle \mathrm{d} x=\left(\lambda_{1}+\mu_{n}\right) \int_{\Omega}\left|u_{n}\right|^{p-2} u_{n} \phi \mathrm{~d} x+\int_{\Omega} f_{n} \phi \mathrm{~d} x \tag{B.2}
\end{equation*}
$$

Here, $\left\{\mu_{n}\right\}_{n=1}^{\infty} \subset \mathbb{R}$ and $\left\{f_{n}\right\}_{n=1}^{\infty} \subset L^{\infty}(\Omega)$ are bounded sequences, and $\left\{u_{n}\right\}_{n=1}^{\infty}$ is an unbounded sequence of corresponding weak solutions to problem (B.1) in $W_{0}^{1, p}(\Omega)$.

We assume that these sequences satisfy the following hypotheses:
(S1) $\mu_{n} \rightarrow 0$ as $n \rightarrow \infty$.
(S2) $f_{n} \stackrel{*}{\rightharpoonup} f$ in $L^{\infty}(\Omega)$ (in the weak-star topology) as $n \rightarrow \infty$, where $f \not \equiv 0$ in $\Omega$.
(S3) $\left\|u_{n}\right\|_{L^{\infty}(\Omega)} \rightarrow \infty$ as $n \rightarrow \infty$.
By a regularity result [3, Théorème A.1, p. 96], hypothesis (S3) is equivalent to
$\left(\mathbf{S 3}^{\prime}\right)\left\|u_{n}\right\|_{W_{0}^{1, p}(\Omega)} \rightarrow \infty$ as $n \rightarrow \infty$.
Furthermore, since $\partial \Omega$ is assumed to be of class $C^{1, \alpha}$, for some $0<\alpha<1$, we can apply another regularity result, 8, Theorem 2, p. 829] or [38, Theorem 1, p. 127] for interior regularity, and [24, Theorem 1, p. 1203] for regularity near the boundary, to conclude that $u_{n} \in C^{1, \beta}(\bar{\Omega})$, for some $\beta \in(0, \alpha)$, and hypothesis (S3) is equivalent to
$\left(\mathbf{S 3}{ }^{\prime}\right) \quad\left\|u_{n}\right\|_{C^{1, \beta}(\bar{\Omega})} \rightarrow \infty$ as $n \rightarrow \infty$.

We often work with a chain of subsequences of $\left\{\left(\mu_{n}, f_{n}, u_{n}\right)\right\}_{n=1}^{\infty}$ by passing from the current one to the next, but keeping the index $n$ unchanged if no confusion may arise.

We commence with the asymptotic behavior of the normalized sequence $\tilde{u}_{n} \stackrel{\text { def }}{=}$ $\left\|u_{n}\right\|_{L^{\infty}(\Omega)}^{-1} u_{n}$ as $n \rightarrow \infty$. Observe that each $\tilde{u}_{n}$ satisfies $\left\|\tilde{u}_{n}\right\|_{L^{\infty}(\Omega)}=1$ and

$$
\begin{gather*}
-\Delta_{p} \tilde{u}_{n}=\left(\lambda_{1}+\mu_{n}\right)\left|\tilde{u}_{n}\right|^{p-2} \tilde{u}_{n}+\left\|u_{n}\right\|_{L^{\infty}(\Omega)}^{1-p} f_{n}(x) \quad \text { in } \Omega  \tag{B.3}\\
\tilde{u}_{n}=0 \quad \text { on } \partial \Omega
\end{gather*}
$$

Hence, $\left\{\tilde{u}_{n}\right\}_{n=1}^{\infty}$ is bounded in $C^{1, \beta}(\bar{\Omega})$, by regularity [8, 24, 38]. We allow $1<p<$ $\infty$.

Lemma B. 1 ([32, Lemma 5.1]). Let $\beta^{\prime} \in(0, \beta)$. The sequence $\left\{\tilde{u}_{n}\right\}_{n=1}^{\infty}$ contains a convergent subsequence $\tilde{u}_{n} \rightarrow \kappa \varphi_{1}$ in $C^{1, \beta^{\prime}}(\bar{\Omega})$ as $n \rightarrow \infty$, where $\kappa \in \mathbb{R}$ is a constant, $|\kappa| \cdot\left\|\varphi_{1}\right\|_{L^{\infty}(\Omega)}=1$. In particular, we have $u_{n}=t_{n}^{-1}\left(\varphi_{1}+v_{n}^{\top}\right)$, where $\left\{t_{n}\right\}_{n=1}^{\infty} \subset \mathbb{R}$ is a sequence such that $\kappa t_{n}>0$ and $t_{n} u_{n} \geq \frac{1}{2} \varphi_{1}$ in $\Omega$ for all $n$ large enough; moreover, $t_{n} \rightarrow 0$ and $v_{n}^{\top} \rightarrow 0$ in $C^{1, \beta^{\prime}}(\bar{\Omega})$ as $n \rightarrow \infty$, with $\left\langle v_{n}^{\top}, \varphi_{1}\right\rangle=0$ for $n=1,2, \ldots$.

As a consequence of this lemma, we can rewrite problem (B.3) as

$$
\begin{gather*}
-\Delta_{p}\left(\varphi_{1}+v_{n}^{\top}\right)=\left(\lambda_{1}+\mu_{n}\right)\left|\varphi_{1}+v_{n}^{\top}\right|^{p-2}\left(\varphi_{1}+v_{n}^{\top}\right)+t_{n}^{p-1} \overline{f_{n}(x)} \text { in } \Omega \\
v_{n}^{\top}=0 \quad \text { on } \partial \Omega  \tag{B.4}\\
\left\langle v_{n}^{\top}, \varphi_{1}\right\rangle=0
\end{gather*}
$$

with all $t_{n}>0, t_{n} \searrow 0$ as $n \rightarrow \infty$. Indeed, if $\kappa<0$, we take advantage of the ( $p-1$ )-homogeneity of problem (B.1) and replace all functions $f_{n}, f$ and $u_{n}$ by $-f_{n},-f$ and $-u_{n}$, respectively, thus switching to the case $\kappa>0$. Hence, without loss of generality, we may assume $t_{n}>0$ and $t_{n} u_{n}=\varphi_{1}+v_{n}^{\top} \geq \frac{1}{2} \varphi_{1}>0$ in $\Omega$ for all $n \geq 1$.

A useful equivalent form of problem (B.1) is obtained by subtracting equation (5.1) from (B.4) and using the Taylor formula with a help from identity (A.2), for $n=1,2, \ldots$ :
$-\operatorname{div}\left(\mathbf{A}_{n} \nabla v_{n}^{\top}\right)=(p-1)\left(\lambda_{1}+\mu_{n}\right) a_{n} v_{n}^{\top}+\mu_{n} \varphi_{1}^{p-1}+\left|t_{n}\right|^{p-2} t_{n} f_{n}(x) \quad$ in $\Omega ;$

$$
v_{n}^{\top}=0 \quad \text { on } \partial \Omega
$$

$$
\begin{equation*}
\left\langle v_{n}^{\top}, \varphi_{1}\right\rangle=0 \tag{B.5}
\end{equation*}
$$

with the abbreviations

$$
\begin{equation*}
\mathbf{A}_{n} \stackrel{\text { def }}{=} \int_{0}^{1} \mathbf{A}\left(\nabla \varphi_{1}+s \nabla v_{n}^{\top}\right) \mathrm{d} s \quad \text { and } \quad a_{n} \stackrel{\text { def }}{=} \int_{0}^{1}\left|\varphi_{1}+s v_{n}^{\top}\right|^{p-2} \mathrm{~d} s \tag{B.6}
\end{equation*}
$$

Recall that the matrix $\mathbf{A}(\mathbf{a})$ is defined in A.3). We abbreviate also

$$
\begin{equation*}
\mathbf{A}_{\varphi_{1}} \stackrel{\text { def }}{=} \mathbf{A}\left(\nabla \varphi_{1}\right) \quad \text { and write } \quad \mathbf{A}_{\varphi_{1}}^{1 / 2}=\sqrt{\mathbf{A}_{\varphi_{1}}} \tag{B.7}
\end{equation*}
$$

Equivalently, $V_{n} \stackrel{\text { def }}{=} t_{n}^{1-p} v_{n}^{\top} \in C^{1, \beta^{\prime}}(\bar{\Omega})$ satisfies the linear boundary value problem

$$
\begin{gather*}
-\operatorname{div}\left(\mathbf{A}_{n} \nabla V_{n}\right)=(p-1)\left(\lambda_{1}+\mu_{n}\right) a_{n} V_{n}+\frac{\mu_{n}}{\left|t_{n}\right|^{p-2} t_{n}} \varphi_{1}^{p-1}+f_{n}(x) \quad \text { in } \Omega \\
V_{n}=0 \quad \text { on } \partial \Omega  \tag{B.8}\\
\left\langle V_{n}, \varphi_{1}\right\rangle=0
\end{gather*}
$$

The asymptotic behavior of $V_{n}$ and $\mu_{n} /\left(\left|t_{n}\right|^{p-2} t_{n}\right)$ as $n \rightarrow \infty$ is determined as follows ([13, Theorem 4.1]).
Theorem B.2. Let $1<p<\infty, p \neq 2$, and let $\left\{\mu_{n}\right\}_{n=1}^{\infty} \subset \mathbb{R},\left\{f_{n}\right\}_{n=1}^{\infty} \subset L^{\infty}(\Omega)$, and $\left\{u_{n}\right\}_{n=1}^{\infty} \subset W_{0}^{1, p}(\Omega)$ be sequences satisfying hypotheses $(\mathbf{S 1})$, (S2), and (S3), respectively. In addition, assume that they satisfy equation (B.2) for all $\phi \in$ $W_{0}^{1, p}(\Omega)$ and for each $n \in \mathbb{N}$. Then, writing $u_{n}=t_{n}^{-1}\left(\varphi_{1}+v_{n}^{\top}\right)$ with $t_{n} \in \mathbb{R}, t_{n} \neq 0$, and $v_{n}^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$, we have $t_{n} \rightarrow 0$ as $n \rightarrow \infty, V_{n}=\left(\left|t_{n}\right|^{p-2} t_{n}\right)^{-1} v_{n}^{\top} \rightarrow V^{\top}$ strongly in $\mathcal{D}_{\varphi_{1}}$ if $p>2$ and in $W_{0}^{1,2}(\Omega)$ if $1<p<2$, and

$$
\begin{gather*}
\mu_{n}=-\left|t_{n}\right|^{p-2} t_{n} \int_{\Omega} f \varphi_{1} \mathrm{~d} x+o\left(\left|t_{n}\right|^{p-1}\right)  \tag{B.9}\\
\mu_{n}=-\left|t_{n}\right|^{p-2} t_{n} \int_{\Omega} f_{n} \varphi_{1} \mathrm{~d} x+(p-2)\left|t_{n}\right|^{2(p-1)} \mathcal{Q}_{0}\left(V^{\top}, V^{\top}\right)  \tag{B.10}\\
+(p-1)\left|t_{n}\right|^{2(p-1)}\left(\int_{\Omega} f \varphi_{1} \mathrm{~d} x\right)\left(\int_{\Omega} \varphi_{1}^{p-1} V^{\top} \mathrm{d} x\right)+o\left(\left|t_{n}\right|^{2(p-1)}\right)
\end{gather*}
$$

Moreover, the limit function $V^{\top} \in \mathcal{D}_{\varphi_{1}} \cap\left\{\varphi_{1}\right\}^{\perp, L^{2}}$ is the (unique) solution to

$$
\begin{equation*}
2 \cdot \mathcal{Q}_{0}\left(V^{\top}, \phi\right)=\int_{\Omega} f^{\dagger} \phi \mathrm{d} x \quad \text { for all } \phi \in \mathcal{D}_{\varphi_{1}} \tag{B.11}
\end{equation*}
$$

where the symmetric bilinear form $\mathcal{Q}_{0}$ is given by 11.2 and

$$
f^{\dagger}=f-\left(\int_{\Omega} f \varphi_{1} \mathrm{~d} x\right) \varphi_{1}^{p-1}
$$

Formula (B.9) is an improvement of Takáč [33, Prop. 6.1, p. 331] whereas (B.10) is established in Drábek et al. 13, Theorem 4.1]. Notice that $\mathcal{Q}_{0}\left(V^{\top}, V^{\top}\right)>0$ holds by Proposition 11.2 and Remark 11.12. In addition, we have $\int_{\Omega} f^{\dagger} \varphi_{1} \mathrm{~d} x=0$.

The linear degenerate Dirichlet problem (B.11) above has been obtained by linearizing (1.1) with $\lambda=\lambda_{1}$ about $\varphi_{1}$, that is to say, from

$$
\begin{gather*}
-\operatorname{div}\left(\mathbf{A}\left(\nabla \varphi_{1}\right) \nabla w\right)=\lambda_{1}(p-1) \varphi_{1}^{p-2} w+f(x) \quad \text { in } \Omega ; \\
w=0 \quad \text { on } \partial \Omega \tag{B.12}
\end{gather*}
$$

It plays a crucial role in our asymptotic formulas as $|\tau| \rightarrow \infty$. Its solution set in $\mathcal{D}_{\varphi_{1}}$ is described in Theorem B.2. If $p<2$ then $\mathcal{D}_{\varphi_{1}}$ is not necessarily dense in $L^{2}(\Omega)$, and so equation B.12 can be satisfied only in the following weak sense, cf. eq. B.11): For all test functions $\phi \in \mathcal{D}_{\varphi_{1}}$,

$$
\begin{equation*}
\int_{U}\left\langle\mathbf{A}\left(\nabla \varphi_{1}\right) \nabla w, \nabla \phi\right\rangle \mathrm{d} x=\lambda_{1}(p-1) \int_{\Omega} \varphi_{1}^{p-2} w \phi \mathrm{~d} x+\int_{\Omega} f \phi \mathrm{~d} x \tag{B.13}
\end{equation*}
$$

The following two special cases of formula (B.10) are of particular interest in the present work; both force $\int_{\Omega} f \varphi_{1} \mathrm{~d} x=0$.
Corollary B.3. In the situation of Theorem B. 2 we have: If $\int_{\Omega} f_{n} \varphi_{1} \mathrm{~d} x=0$ for all $n \in \mathbb{N}$, then

$$
\begin{equation*}
\mu_{n}=(p-2)\left|t_{n}\right|^{2(p-1)} \mathcal{Q}_{0}\left(V^{\top}, V^{\top}\right)+o\left(\left|t_{n}\right|^{2(p-1)}\right) \tag{B.14}
\end{equation*}
$$

On the other hand, if $\mu_{n}=0$ for all $n \in \mathbb{N}$, then

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{1}{\left|t_{n}\right|^{p-2} t_{n}} \int_{\Omega} f_{n} \varphi_{1} \mathrm{~d} x=(p-2) \mathcal{Q}_{0}\left(V^{\top}, V^{\top}\right) \tag{B.15}
\end{equation*}
$$

In particular, in both cases we must have $\int_{\Omega} f \varphi_{1} \mathrm{~d} x=0$.
B.2. Uniform boundedness of the solution set. Finally, we are ready to establish the asymptotic behavior (blow-up) of every weak solution to the resonant problem (9.2), that is,

$$
\begin{equation*}
-\Delta_{p} u=\lambda_{1}|u|^{p-2} u+f(x) \quad \text { in } \Omega ; \quad u=0 \quad \text { on } \partial \Omega \tag{9.2}
\end{equation*}
$$

with $f \equiv f^{\top}+\zeta \varphi_{1}$, where $f^{\top} \in L^{\infty}(\Omega)^{\top}$ and $\zeta \in \mathbb{R}$. It turns out to be convenient to apply Lemma B.1 that is, to fix an arbitrary number $t \in \mathbb{R} \backslash\{0\}$ and consider only those weak solutions to problem (9.2) that take the form $u=t^{-1} \varphi_{1}+u^{\top}$ where $u^{\top} \in W_{0}^{1, p}(\Omega)^{\top}$ is an unknown function. Hence $u^{\top} \in C^{1, \beta}(\bar{\Omega})$ by regularity [3, 8, 24, 38. While determining the asymptotic behavior of $u$ as $t \rightarrow 0$, we regard $\zeta \in \mathbb{R}$ in eq. 9.2 as a parameter depending on $t$ as well.

Let $F(t)$ denote the set of all pairs $\left(\zeta, u^{\top}\right) \in \mathbb{R} \times W_{0}^{1, p}(\Omega)^{\top}$ satisfying the boundary value problem

$$
\begin{align*}
& -\Delta_{p}\left(t^{-1} \varphi_{1}+u^{\top}\right)-\lambda_{1}\left|t^{-1} \varphi_{1}+u^{\top}\right|^{p-2}\left(t^{-1} \varphi_{1}+u^{\top}\right) \\
& =f^{\top}(x)+\zeta \cdot \varphi_{1}(x) \quad \text { in } \Omega ; \\
& u^{\top}=0 \quad \text { on } \partial \Omega ;  \tag{B.16}\\
& \left\langle u^{\top}, \varphi_{1}\right\rangle=0 .
\end{align*}
$$

The asymptotic behavior of $F(t)$ as $t \rightarrow 0$ is determined next. The following equivalent form of problem (B.16) will be needed with the new unknown function $v^{\top} \stackrel{\text { def }}{=} t u^{\top}$ :

$$
\begin{gather*}
-\Delta_{p}\left(\varphi_{1}+v^{\top}\right)-\lambda_{1}\left|\varphi_{1}+v^{\top}\right|^{p-2}\left(\varphi_{1}+v^{\top}\right) \\
=|t|^{p-2} t\left(f^{\top}(x)+\zeta \cdot \varphi_{1}(x)\right) \quad \text { in } \Omega \\
v^{\top}=0 \quad \text { on } \partial \Omega ;  \tag{B.17}\\
\left\langle v^{\top}, \varphi_{1}\right\rangle=0 .
\end{gather*}
$$

We take a sequence of nonzero real numbers $t_{n} \rightarrow 0$ as $n \rightarrow \infty$ and a sequence of pairs $\left(\zeta_{n}, u_{n}^{\top}\right) \in F\left(t_{n}\right)$. We substitute $v_{n}^{\top} \stackrel{\text { def }}{=} t_{n} u_{n}^{\top}$ and $V_{n} \stackrel{\text { def }}{=}\left|t_{n}\right|^{-(p-2)} u_{n}^{\top}=$ $\left|t_{n}\right|^{-(p-2)} t_{n}^{-1} v_{n}^{\top}$, and abbreviate $f_{n} \stackrel{\text { def }}{=} f^{\top}+\zeta_{n} \varphi_{1}$. More generally, we can replace function $f^{\top} \in L^{\infty}(\Omega)^{\top}, f^{\top} \not \equiv 0$ in $\Omega$, by a bounded sequence $\left\{f_{n}^{\top}\right\}_{n=1}^{\infty}$ of functions from $L^{\infty}(\Omega)^{\top}$ satisfying the following hypothesis (cf. (S2) in $\S$ B.1 :
$\left(\mathbf{S 2}^{\top}\right) f_{n}^{\top} \xrightarrow{*} f^{\top}$ in $L^{\infty}(\Omega)$ (weakly-star) as $n \rightarrow \infty$. We require $f^{\top} \notin \mathcal{D}_{\varphi_{1}}^{\perp, L^{2}}$.
The following a priori asymptotic formula was obtained in Takáč [33, Prop. 6.1]:

Proposition B.4. Assume ( $\left.\mathbf{S 2}^{\top}\right)$. If $t_{n} \neq 0$ and $t_{n} \rightarrow 0$ as $n \rightarrow \infty$, then $\zeta_{n} \rightarrow 0$, all conclusions of Theorem B. 2 and Corollary B. 3 remain valid with $f=f^{\top}$, and moreover

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \frac{\zeta_{n}}{\left|t_{n}\right|^{p-2} t_{n}}=(p-2)\left\|\varphi_{1}\right\|_{L^{2}(\Omega)}^{-2} \cdot \mathcal{Q}_{0}(w, w) \neq 0 \tag{B.18}
\end{equation*}
$$

Here, for $p>2, w \in \mathcal{D}_{\varphi_{1}}$ is the unique weak solution of problem (B.12) with $f=f^{\top}$ satisfying $\left\langle w, \varphi_{1}\right\rangle=0$. For $p<2$, equation B.13 replaces B.12). Finally, Proposition 11.2 and Remark 11.12 guarantee $\mathcal{Q}_{0}(w, w)>0$.

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