*Electronic Journal of Differential Equations*, Vol. 2018 (2018), No. 38, pp. 1–9. ISSN: 1072-6691. URL: http://ejde.math.txstate.edu or http://ejde.math.unt.edu

# EXISTENCE AND UNIQUENESS OF SOLUTIONS TO SINGULAR QUASILINEAR SCHRÖDINGER EQUATIONS

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Communicated by Vicentiu D. Radulescu

ABSTRACT. In this article we study a quasilinear Schrödinger equations with singularity. We obtain a unique and positive solution by using the minimax method and some analysis techniques.

#### 1. INTRODUCTION AND STATEMENT OF MAIN RESULTS

This article concerns the singular quasilinear Schrödinger equation with the Dirichlet boundary value condition

$$-\Delta u - \Delta (u^2)u = g(x)u^{-r} - u^{p-1} \quad \text{in } \Omega,$$
  

$$u > 0 \quad \text{in } \Omega,$$
  

$$u = 0 \quad \text{on } \partial\Omega,$$
(1.1)

where  $\Omega \subset \mathbb{R}^N$   $(N \geq 3)$  is a bounded smooth domain with boundary  $\partial\Omega$ ,  $r \in (0, 1)$ and  $p \in [2, 22^*]$  are constants. The coefficient  $g \in L^{\frac{22^*}{2^{2^*-1+r}}}(\Omega)$  with g(x) > 0 for almost every  $x \in \Omega$  and  $2^* = \frac{2N}{N-2}$  denotes the critical Sobolev exponent for the embedding  $H_0^1(\Omega) \hookrightarrow L^q(\Omega)$  for every  $q \in [1, 2^*]$ .

Solutions of (1.1) are related to standing wave solutions for the quasilinear Schrödinger equations

$$i\partial_t \psi = -\Delta \psi + \psi + \eta (|\psi|^2)\psi - k\Delta \rho (|\psi|^2)\rho'(|\psi|^2)\psi, \qquad (1.2)$$

where  $\psi = \psi(t, x)$ ,  $\psi : \mathbb{R} \times \Omega \to \mathbb{C}$ , k > 0 is a constant. The quasilinear equations of the form (1.2) play an important role in several areas of physics in correspondence to different type of functions  $\rho$ . For example, it models the superfluid film equation in plasma physics for  $\rho(s) = s$  (see [14]), while for  $\rho(s) = (1 + s)^{1/2}$  it models the self-channeling of a high-power ultra short laser pulse in matter (see [2, 6, 23]). For further physical motivations and developing the physical aspects we refer to [13, 15, 16, 21] and the references therein.

Motivated by the above mentioned physical aspects, equation (1.2) has received a lot of attention. Indeed, up to our knowledge, the first existence results for the subcritical quasilinear equations have been discussed in [21] using constraint minimization arguments. Subsequently, many authors in [4, 18, 19] were interested

<sup>2010</sup> Mathematics Subject Classification. 35J20, 35A15, 35J75, 35J62.

Key words and phrases. Quasilinear Schrödinger equation; singularity; uniqueness. ©2018 Texas State University.

Submitted June 23, 2017. Published January 30, 2018.

in the existence results of standing wave solutions for (1.2) by using a change of variable and reducing the quasilinear equations into the semilinear ones in an appropriate Orlicz space. For critical case, we can refer to [26, 10, 9, 19]. It is worth noticing that up to now there are only one paper [8] investigating the singular case, where they established the singular quasilinear Schrödinger equation

$$-\Delta u - \frac{1}{2}\Delta(u^2)u = \lambda u^3 - u - u^{-\alpha}, \quad u > 0, \ x \in \Omega,$$

where  $\Omega$  is a ball in  $\mathbb{R}^N$   $(N \geq 2)$  centered at the origin,  $0 < \alpha < 1$ . And they proved the existence of radially symmetric positive solutions by employing Nehari manifold and some techniques related to implicit function theorem when  $\lambda$  belongs to a certain neighborhood of the first eigenvalue  $\lambda_1$  of the eigenvalue problem

$$-\Delta u - \frac{1}{2}\Delta(u^2)u = \lambda u^3.$$

The singular problems are much more complicated than the regular one and they require some hard analysis. For singular elliptic problems, there are many authors (see e.g. [11, 5, 3, 27, 7, 12, 22]) have studied. Especially, Ghergu and Rădulescu in [11] established several existence and nonexistence results for the boundary value problem

$$\Delta u + K(x)g(u) = \lambda f(x, u) + \mu h(x) \quad \text{in } \Omega,$$
  

$$u > 0 \quad \text{in } \Omega,$$
  

$$u = 0 \quad \text{on } \partial\Omega,$$
(1.3)

where  $\Omega$  is a smooth bounded domain in  $\mathbb{R}^N$   $(N \ge 2)$ ,  $\lambda$  and  $\mu$  are positive parameters, h is a positive function, f has a sublinear growth and the function g satisfies the condition

$$\lim_{s \to \infty} g(s) = +\infty.$$

Obviously,  $g(s) = s^{-r}$ ,  $r \in (0, 1)$  satisfies the above assumption. When  $K(x) \equiv -1$ ,  $f(x, u) = u^p$  and  $g(s) = s^{-r}$  in (1.3), where  $r \in (0, 1)$ ,  $p \ge 0$ , Coclite and Palmieri in [3] proved that there is at least one solution for all  $\lambda \ge 0$  if  $0 , moreover, there exists a solution for small <math>\lambda > 0$  and no solution for large  $\lambda > 0$  if  $p \ge 1$ . For Second-Order Differential Equations, such as Sturm-Liouville operator, Dirac Operators etc., there are many authors being interested, we can refer to [20, 17] and the references therein.

The main purpose of this article is to study the singular quasilinear Schrödinger equation (1.1) and introduce a uniqueness result of solutions for (1.1), which is the first work on this subject up to our knowledge.

**Notation.** *C* is a positive constant whose value can be different. The domain of an integral is  $\Omega$  unless otherwise indicated.  $\int f(x)dx$  is abbreviated to  $\int f(x)$ .  $L^p(\Omega)$ ,  $1 \leq p \leq \infty$ , denotes the Lebesgue space with the norms  $||u||_p = (\int |u|^p)^{\frac{1}{p}}$ , for  $1 \leq p < \infty$ ,  $||u||_{\infty} = \inf\{C > 0 : |u(x)| \leq C$  almost everywhere in  $\Omega\}$ .  $X = H_0^1(\Omega)$  denotes the Hilbert space equipped with the norm  $||u|| = (\int |\nabla u|^2)^{1/2}$ . The main result is described as follows.

**Theorem 1.1.** Suppose that  $r \in (0,1)$ ,  $p \in [2,22^*]$  and  $g \in L^{\frac{22^*}{22^*-1+r}}(\Omega)$  with g(x) > 0 for almost every  $x \in \Omega$ . Then problem (1.1) has a unique positive solution in X. Moreover, this solution is the global minimizer solution.

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$$-\Delta u = g(x)u^{-r} + \lambda u^{p-1}, \quad \text{in } \Omega,$$
$$u = 0, \quad \text{on } \partial\Omega,$$

where  $p = 2^*$ , has been studied for  $\lambda > 0$  in [27] and also in [7] for  $\lambda = 0$  under the condition  $g(x) \in L^{\infty}(\Omega)$ . We point out that the condition  $g \in L^{\frac{22^*}{22^*-1+r}}(\Omega)$  is more general than the condition  $g(x) \in L^{\infty}(\Omega)$ . To the best of our knowledge, the existence and uniqueness of solutions for the quasilinear Schrödinger equation (1.1) has not been discussed up to now.

This article is organized as follows: Some preliminaries are given in the next section. In Section 3, we give the proof of Theorem 1.1.

## 2. Preliminary results

We observe that the energy functional corresponding to (1.1) given by

$$J(u) := \frac{1}{2} \int (1+2u^2) |\nabla u|^2 - \frac{1}{1-r} \int g(x) |u|^{1-r} + \frac{1}{p} \int |u|^p$$

is not well defined in X. To overcome this problem, we use the change of variable  $v := f^{-1}(u)$  introduced in [18], where f is defined by

$$f'(t) = \frac{1}{\sqrt{1+2f^2(t)}}$$
 on  $[0, +\infty)$ , and  $f(t) = -f(-t)$  on  $(-\infty, 0]$ .

We list some properties of f, whose proofs can be found in [4, 25].

**Lemma 2.1.** The function f satisfies the following properties:

- (1) f is uniquely defined,  $C^{\infty}$  and invertible;
- (2)  $|f'(t)| \leq 1$  for all  $t \in \mathbb{R}$ ;
- (3)  $|f(t)| \leq |t|$  for all  $t \in \mathbb{R}$ ;
- (4)  $f(t)/t \to 1 \text{ as } t \to 0;$
- (5)  $|f(t)f'(t)| < 1/\sqrt{2}, \forall t \in \mathbb{R};$
- (6)  $f(t)/2 \le tf'(t) \le f(t)$  for all  $t \ge 0$ ;
- (7)  $|f(t)| \leq 2^{1/4} |t|^{1/2}$  for all  $t \in \mathbb{R}$ ;
- (8) the function  $f^{-r}(t)f'(t)$  is decreasing for all t > 0;
- (9) the function  $f^{p-1}(t)f'(t)$  is increasing for all t > 0.

*Proof.* We only prove (8) and (9). By  $f''(t) = -2f(t)[f'(t)]^4$ , for all  $t \in \mathbb{R}$ ,  $p \ge 2$  and (5), with simple computation we obtain

$$\frac{d[f^{-r}(t)f'(t)]}{dt} = -rf^{-r-1}(t)[f'(t)]^2 - 2f^{1-r}(t)[f'(t)]^4 < 0, \quad \forall t > 0$$

and

$$\frac{d[f^{p-1}(t)f'(t)]}{dt} = f^{p-2}(t)[f'(t)]^2[p-1-2f^2(t)[f'(t)]^2] > 0, \quad \forall t > 0,$$

which imply that  $f^{-r}(t)f'(t)$  is decreasing and  $f^{p-1}(t)f'(t)$  is increasing for all t > 0.

By exploiting the change of variable, we can rewrite the functional in the form

$$I(v) := \frac{1}{2} \int |\nabla v|^2 - \frac{1}{1-r} \int g(x) |f(v)|^{1-r} + \frac{1}{p} \int |f(v)|^p, \quad v \in X.$$

By Lemma 2.1-(7), the Hölder inequality and the Sobolev inequality we have

$$\int g(x)|f(v)|^{1-r} \le C \|g\|_{\frac{22^*}{22^*-1+r}} \|v\|^{\frac{1-r}{2}}.$$
(2.1)

Then I is well-defined but only continuous on X. Also equation (1.1) can be rewritten as

$$-\Delta v = g(x)f^{-r}(v)f'(v) - f^{p-1}(v)f'(v), \ v > 0, \ x \in \Omega.$$
 (2.2)

In general, a function  $v \in X$  is called a weak solution of (2.2) with v > 0 in  $\Omega$  if it holds

$$\int \nabla v \nabla w - g(x) f^{-r}(v) f'(v) w + f^{p-1}(v) f'(v) w = 0, \quad \forall w \in X.$$
(2.3)

We observe that if  $v \in X$  is a weak solution of (2.2), the function  $u = f(v) \in X$  is a solution of (1.1) (cf:[4]).

# 3. Proof of Theorem 1.1

In this section, we shall show that there exists a unique positive solution  $v_0$  of (2.2), which is the global minimizer of the functional I in X, and then  $u_0 = f(v_0) \in X$  is the unique positive solution of (1.1).

**Lemma 3.1.** The functional I attains the global minimizer in X; that is, there exists  $v_0 \in X \setminus \{0\}$  such that  $I(v_0) = m := \inf_X I < 0$ .

*Proof.* For  $v \in X$ , from (2.1) it follows that

$$I(v) \ge \frac{1}{2} \|v\|^2 - \frac{C}{1-r} \|g\|_{\frac{22^*}{22^*-1+r}} \|v\|^{\frac{1-r}{2}}.$$
(3.1)

Since  $r \in (0, 1)$ , I is coercive and bounded from below on X. Thus  $m := \inf_X I$  is well defined. For t > 0 and given  $v \in X \setminus \{0\}$  by Lemma 2.1-(7) one gets

$$\begin{split} I(tv) &= \frac{t^2}{2} \|v\|^2 - \frac{1}{1-r} \int g(x) |f(tv)|^{1-r} + \frac{1}{p} \int |f(tv)|^p \\ &\leq \frac{t^2}{2} \|v\|^2 - \frac{1}{1-r} \int g(x) |f(tv)|^{1-r} + \frac{C}{p} t^{\frac{p}{2}} \int |v|^{\frac{p}{2}}. \end{split}$$

Note that the function  $|\frac{f(tv)}{tv}|^{1-r}$  is non-increasing for t > 0. By Lemma 2.1-(4) and Beppo-Levi Monotone Convergence Theorem, we can see

$$\lim_{t \to 0^+} \frac{I(tv)}{t^{1-r}} = -\frac{1}{1-r} \int g(x) |v|^{1-r} < 0.$$

So we have I(tv) < 0 for all  $v \neq 0$  and t > 0 small enough. Hence, we obtain m < 0.

According to the definition of m, there exists a minimizing sequence  $\{v_n\} \subset X$ such that  $\lim_{n\to\infty} I(v_n) = m < 0$ . Since  $I(v_n) = I(|v_n|)$ , we may assume that  $v_n \ge 0$ . It follows from (3.1) that there exists a constant C > 0 such that  $||v_n|| \le C$ . Passing if necessary to a subsequence, we can assume that there exists  $v_0 \in X$  such that

$$v_n \rightharpoonup v_0 \quad \text{in } X,$$
  
 $v_n \rightarrow v_0 \quad \text{in } L^p(\Omega), \ p \in [1, 2^*),$   
 $v_n(x) \rightarrow v_0(x) \quad \text{a.e. in } \Omega,$ 

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$$|u_n(x)| \le k(x) \quad \text{a.e. in } \Omega. \tag{3.2}$$

By Vitali's theorem (see [24]), we claim that

$$\lim_{n \to \infty} \int g(x) f^{1-r}(v_n) = \int g(x) f^{1-r}(v_0).$$
(3.3)

Indeed, we only need prove that  $\{\int g(x)f^{1-r}(v_n), n \in \mathbb{N}\}\$  is equi-absolutelycontinuous. For all  $\varepsilon > 0$ , by the absolutely-continuity of  $\int |g(x)|^{\frac{22^*}{2^{2^*-1+r}}}$ , there exists  $\delta > 0$  such that  $\int_E |g(x)|^{\frac{22^*}{2^{2^*-1+r}}} < \varepsilon^{\frac{22^*}{2^{2^*-1+r}}}$  for all  $E \subset \Omega$  with meas  $E < \delta$ . Consequently, by (2.1) and the fact that  $\|v_n\| \leq C$ , we have

$$\int_{E} g(x) f^{1-r}(v_n) \le C \|v_n\|^{\frac{1-r}{2}} \Big( \int_{E} |g(x)|^{\frac{22^*}{22^*-1+r}} \Big)^{\frac{22^*-1+r}{22^*}} < C\varepsilon.$$

Thus, (3.3) is valid. In the case that  $p \in [2, 22^*)$ , by Lemma 2.1-(7) and (3.2) we see

$$|f(v_n)|^p \le C|v_n|^{\frac{p}{2}} \le Ck^{\frac{p}{2}} \in L^1(\Omega),$$

then the Lebesgue Dominated Convergence Theorem implies

$$\int f^p(v_n) = \int f^p(v_0) + o(1).$$

Combining the above equality, the weakly lower semi-continuity of the norm, and (3.3), we have

$$m \le I(v_0) = \frac{1}{2} \|v_0\|^2 - \frac{1}{1-r} \int g(x) f^{1-r}(v_0) + \frac{1}{p} \int f^p(v_0) \le \liminf_{n \to \infty} I(v_n) = m,$$

which yields that  $I(v_0) = m < 0$  and  $v_0 \neq 0$ . In the case that  $p = 22^*$ , by Brézis-Lieb's Lemma (see [1]) and Lemma 2.1-(7), one obtains

$$\int f^{22^*}(v_n) = \int f^{22^*}(v_0) + \int f^{22^*}(v_n - v_0) + o(1),$$

which together with the weakly lower semi-continuity of the norm and (3.3), we have

$$m \leq I(v_0) = \frac{1}{2} ||v_0||^2 - \frac{1}{1-r} \int g(x) f^{1-r}(v_0) + \frac{1}{p} \int f^p(v_0)$$
$$\leq \liminf_{n \to \infty} I(v_n) - \lim_{n \to \infty} \frac{1}{22^*} \int f^{22^*}(v_n - v_0) \leq m,$$

which also implies that  $I(v_0) = m < 0$  and  $v_0 \neq 0$ .

Proof of Theorem 1.1. Since  $I(v_0) = m < 0$ , we obtain that  $v_0 \ge 0$  and  $v_0 \ne 0$ . Now, we divide the proof in three steps:

First, we claim that  $v_0 > 0$  in  $\Omega$ . Fix  $\phi \in X$  with  $\phi \ge 0$ , let t > 0, one has

$$0 \leq I(v_0 + t\phi) - I(v_0)$$
  
=  $\frac{1}{2} ||v_0 + t\phi||^2 - \frac{1}{2} ||v_0||^2 - \frac{1}{1-r} \int g(x) [f^{1-r}(v_0 + t\phi) - f^{1-r}(v_0)]$   
+  $\frac{1}{p} \int f^p(v_0 + t\phi) - f^p(v_0).$ 

Dividing by t>0 and passing to the limit as  $t\to 0^+$  in the above inequality, we have

$$\frac{1}{1-r} \liminf_{t \to 0^+} \int g(x) \frac{f^{1-r}(v_0 + t\phi) - f^{1-r}(v_0)}{t} \\
\leq \int \nabla v_0 \nabla \phi + f^{p-1}(v_0) f'(v_0) \phi.$$
(3.4)

Note that

$$\int g(x) \frac{f^{1-r}(v_0 + t\phi) - f^{1-r}(v_0)}{t} = (1-r) \int g(x) f^{-r}(v_0 + t\theta\phi) f'(v_0 + t\theta\phi)\phi,$$

where  $\theta(x) \in (0, 1)$ . For any  $x \in \Omega$ , we denote

$$h(t) = g(x)f^{-r}(v_0 + t\theta\phi)f'(v_0 + t\theta\phi)\phi, \quad t > 0.$$

It follows from g(x) > 0 a.e.  $x \in \Omega$  and Lemma 2.1-(8) that h(t) is non-increasing for t > 0. Moreover,

$$\lim_{t \to 0^+} h(t) = g(x) f^{-r}(v_0(x)) f'(v_0(x)) \phi(x)$$

for every  $x \in \Omega$ , which may be  $+\infty$  when  $v_0(x) = 0$ . Consequently, by the Beppo-Levi Monotone Convergence Theorem, we obtain

$$\liminf_{t \to 0^+} \frac{1}{1-r} \int g(x) \frac{f^{1-r}(v_0 + t\phi) - f^{1-r}(v_0)}{t} = \int g(x) f^{-r}(v_0) f'(v_0)\phi,$$

which together with (3.4) implies that

$$\int \nabla v_0 \nabla \phi - g(x) f^{-r}(v_0) f'(v_0) \phi + f^{p-1}(v_0) f'(v_0) \phi \ge 0, \quad \phi \in X, \ \phi \ge 0.$$
(3.5)

Therefore,

$$-\Delta v_0 + f^{p-1}(v_0)f'(v_0) \ge 0$$

in the weak sense. Hence the maximum principle implies that  $v_0 > 0$  in  $\Omega$ .

Secondly, we show that  $v_0$  is a solution of (2.2), that is, we prove  $v_0$  satisfies (2.3). For given  $\delta > 0$ , define  $H : [-\delta, \delta] \to \mathbb{R}$  by  $H(t) = I((1+t)v_0)$ , then H attains its minimum at t = 0 by Lemma 3.1, namely

$$H'(0) = ||v_0||^2 - \int g(x) f^{-r}(v_0) f'(v_0) v_0 - f^{p-1}(v_0) f'(v_0) v_0 = 0.$$
(3.6)

Choose  $\varphi \in X \setminus \{0\}, \varepsilon > 0$ . Define  $\phi \in X$  by  $\phi = (v_0 + \varepsilon \varphi)^+$ . Let

$$\Omega_1 = \{ x \in \Omega : v_0(x) + \varepsilon \varphi(x) > 0 \}, \quad \Omega_2 = \{ x \in \Omega : v_0(x) + \varepsilon \varphi(x) \le 0 \}.$$

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Easily, we see  $\phi|_{\Omega_1} = v_0 + \varepsilon \varphi$  and  $\phi|_{\Omega_2} = 0$ . Inserting  $\phi$  into (3.5) and applying with (3.6), one obtains

$$0 \leq \int \nabla v_0 \nabla \phi - g(x) f^{-r}(v_0) f'(v_0) \phi + f^{p-1}(v_0) f'(v_0) \phi$$

$$= \int_{\Omega_1} \nabla v_0 \nabla (v_0 + \varepsilon \varphi) - g(x) f^{-r}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$+ f^{p-1}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$= \int_{\Omega \setminus \Omega_2} \nabla v_0 \nabla (v_0 + \varepsilon \varphi) - g(x) f^{-r}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$+ f^{p-1}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$= \varepsilon \int \nabla v_0 \nabla \varphi - g(x) f^{-r}(v_0) f'(v_0) \varphi + f^{p-1}(v_0) f'(v_0) \varphi$$

$$- \int_{\Omega_2} \nabla v_0 \nabla (v_0 + \varepsilon \varphi) - g(x) f^{-r}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$+ f^{p-1}(v_0) f'(v_0) (v_0 + \varepsilon \varphi)$$

$$\leq \varepsilon \int \nabla v_0 \nabla \varphi - g(x) f^{-r}(v_0) f'(v_0) \varphi + f^{p-1}(v_0) f'(v_0) \varphi$$

$$- \varepsilon \int_{\Omega_2} \nabla v_0 \nabla \varphi + f^{p-1}(v_0) f'(v_0) \varphi.$$
(3.7)

From meas  $\Omega_2 \to 0$  as  $\varepsilon \to 0$ , it follows that

$$\int_{\Omega_2} \nabla u_0 \nabla \varphi + f^{p-1}(v_0) f'(v_0) \varphi \to 0 \quad \text{as } \varepsilon \to 0.$$

Then dividing by  $\varepsilon > 0$  and letting  $\varepsilon \to 0$  in (3.7), we conclude that

$$\int \nabla v_0 \nabla \varphi - g(x) f^{-r}(v_0) f'(v_0) \varphi + f^{p-1}(v_0) f'(v_0) \varphi \ge 0.$$

By the arbitrariness of  $\varphi$ , the above inequality also holds for  $-\varphi$ , so we get that  $v_0$  solves (2.3). Hence  $v_0 \in X$  is a positive solution of (2.2) with  $I(v_0) = m < 0$ , that is,  $v_0$  is the global minimizer solution.

Finally, we show that  $v_0 \in X$  is the unique solution of (2.2). Assume that  $v \in X$  is also a solution of (2.2), it follows from (2.3) that

$$\int \nabla v_0 \nabla (v_0 - v) - g(x) f^{-r}(v_0) f'(v_0) (v_0 - v) + f^{p-1}(v_0) f'(v_0) (v_0 - v) = 0 \quad (3.8)$$

and

$$\int \nabla v \nabla (v_0 - v) - g(x) f^{-r}(v) f'(v) (v_0 - v) + f^{p-1}(v) f'(v) (v_0 - v) = 0.$$
 (3.9)

Subtracting (3.8) and (3.9), since g(x) > 0 a.e.  $x \in \Omega$ , by Lemma 2.1-(8), (9) we get

$$||v_0 - v||^2 = \int g(x) [f^{-r}(v_0) f'(v_0) - f^{-r}(v) f'(v)](v_0 - v) - \int [f^{p-1}(v_0) f'(v_0) - f^{p-1}(v) f'(v)](v_0 - v) \le 0,$$

which implies that  $||v_0 - v|| = 0$ , that is  $v_0 = v$ . Therefore,  $v_0 \in X$  is the unique solution of (2.2), and then  $u_0 = f(v_0) \in X$  is the unique solution of (1.1). We complete the proof of Theorem 1.1.

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