# PERIODIC SOLUTIONS OF MULTISPECIES-COMPETITION PREDATOR-PREY SYSTEM WITH HOLLING'S TYPE III FUNCTIONAL RESPONSE AND PREY SUPPLEMENT 

JIWEI HE


#### Abstract

In this paper, we consider a nonautonomous multispecies competition predator-prey system with Holling's type III functional response and prey supplement. It is proved that the system is uniformly persistent under some conditions. Furthermore, we show that the system has a unique positive periodic solution which is globally asymptotically stable.


## 1. Introduction

The ecological predator-prey systems with Holling's type functional response have been studied extensively by many authors [1, 2, 3, 4, 5, 7, 8, 2, 12, 13, 14, 15]. One of the most interesting questions in mathematical biology concerns the existence of positive periodic solutions for population dynamical systems 6, 11, 16, 17, 18. For the continuous Lotka-Volterra systems, such a problem has been investigated extensively, and many skills and techniques have been developed.

The existence of positive periodic solutions for such systems can be obtained by standard techniques of bifurcation theory [5], or by theory of topological degree [11]. In fact, these methods have been widely applied to various Lotka-Volterra systems [16, 17, 18]. However, in population dynamics, in order to keep the persistence of Lotka-Volterra system, human always give some supplement of prey. To the author's knowledge, the population dynamical systems with prey supplement are seldom discussed.

The purpose of this paper is to study the asymptotic behavior of a nonautonomous multispecies predator-prey system with Holling's type III functional response and prey supplement. Moreover, the competition among predator species and among prey species is simultaneously considered. We will investigate the following nonautonomous predator-prey system of differential equations

[^0]\[

$$
\begin{gather*}
\dot{x}_{i}(t)=x_{i}(t)\left[b_{i}(t)-\sum_{k=1}^{n} a_{i k}(t) x_{k}(t)-\sum_{k=1}^{m} \frac{c_{i k}(t) x_{i}(t) y_{k}(t)}{f_{i k}(t)+x_{i}^{2}(t)}\right]+\phi_{i}(t)  \tag{1.1}\\
\dot{y}_{j}(t)=y_{j}(t)\left[-r_{j}(t)+\sum_{k=1}^{n} \frac{d_{j k}(t) x_{k}^{2}(t)}{f_{j k}(t)+x_{k}^{2}(t)}-\sum_{k=1}^{m} e_{j k}(t) y_{k}(t)\right] \tag{1.2}
\end{gather*}
$$
\]

Here, $x_{i}(t)$ denotes the density of prey species $x_{i}$ at time $t, y_{j}(t)$ denotes the density of predator species $y_{j}$ at time $t, \phi_{i}(t)$ represents the supplement of prey, the functions $b_{i}(t), r_{j}(t), a_{i j}(t), c_{i j}(t), d_{i j}(t), e_{i j}(t)(i=1,2, \ldots, n, j=1,2, \ldots, m)$ are continuous, nonnegative and $b_{i}(t), f_{j k}(t), a_{i i}(t), e_{j j}(t)$ are below bounded by positive constants. In section 2 , we prove the uniform persistence of the system. In section 3, we prove the existence of positive periodic solution of the system. In section 4 , the sufficient conditions for the uniqueness and global attractivity of the positive periodic solution of system (1.1)-1.2) are obtained.

## 2. Uniform Persistence

For the sake of simplicity, we take some notations as following:

$$
X=\left(x_{1}, x_{2}, \ldots, x_{n}\right), \quad Y=\left(y_{1}, y_{2}, \ldots, y_{m}\right), \quad F=(X, Y)
$$

It is obvious that there exists a unique solution of the system $1.1-(1.2)$ corresponding to any initial value $F=(X, Y) \in R^{n+m}$. Assume that

$$
\begin{aligned}
F(t, F) & =(X(t, F), Y(t, F)) \\
& =\left(x_{1}(t, F), x_{2}(t, F), \ldots, x_{n}(t, F), y_{1}(t, F), y_{2}(t, F), \ldots, y_{m}(t, F)\right)
\end{aligned}
$$

and $F(0, F)=F, t>0$.
Lemma 2.1. If $a>0, b>0$ and $\frac{d x}{d t} \leq(\geq) x(b-a x)$, when $t \geq 0$, for any positive initial value we have

$$
\limsup _{t \rightarrow \infty} x(t) \leq \frac{b}{a} \quad\left(\liminf _{t \rightarrow \infty} x(t) \geq \frac{b}{a}\right)
$$

Lemma 2.2. Both positive and nonnegative cones of $R^{n+m}$ are invariant with respect to system (1.1)- 1.2 .

It follows from this lemma that any solution of system $1.1-1.2$ with nonnegative initial conditions remains nonnegative.

Definition 2.3. System 1.1-1.2 is said to be uniformly persistent if for any positive initial value, there exist positive constants $A, B, C, D$ such that $0<A \leq$ $\liminf _{t \rightarrow+\infty} x_{i}(t) \leq \limsup _{t \rightarrow+\infty} x_{i}(t) \leq B<+\infty(i=1,2, \ldots, n)$ and $0<C \leq$ $\liminf _{t \rightarrow+\infty} y_{j}(t) \leq \limsup _{t \rightarrow+\infty} y_{j}(t) \leq D<+\infty(j=1,2, \ldots, m)$.

Assume that $0<f^{L}=\inf _{t \geq 0} f(t) \leq \sup _{t \geq 0} f(t)=f^{M}<+\infty$. In the following, it is convenient to assume that

$$
\begin{gathered}
p_{i}=\frac{b_{i}^{M}}{a_{i i}^{L}}+\sqrt{\frac{\phi_{i}^{M}}{a_{i i}^{L}}}, \quad q_{j}=\frac{1}{e_{j j}^{L}}\left(-r_{j}^{L}+\sum_{k=1}^{n} d_{j k}^{M}\right), \\
\alpha_{i}=\frac{1}{a_{i i}^{M}}\left(b_{i}^{L}-\sum_{k=1, k \neq i}^{n} a_{i k}^{M} p_{k}-\sum_{k=1}^{m} \frac{c_{i k}^{M} q_{k} p_{i}}{f_{i k}^{L}}\right)+\sqrt{\frac{\phi_{i}^{L}}{a_{i i}^{M}}}, \\
\beta_{j}=\frac{1}{e_{j j}^{M}}\left(-r_{j}^{M}+\sum_{k=1}^{n} \frac{d_{j k}^{L} \alpha_{k}^{2}}{f_{j k}^{M}+p_{k}^{2}}-\sum_{k=1, k \neq j}^{m} e_{j k}^{M} q_{k}\right)
\end{gathered}
$$

$(i=1,2, \ldots, n ; j=1,2, \ldots, m)$. It is obvious that if $q_{j}>0$, then $\alpha_{i}<p_{i}$, and if $q_{j}>0, \alpha_{i}>0$, then $\beta_{j}<q_{j}(i=1,2, \ldots, n ; j=1,2, \ldots, m)$. So, from now on, we suppose that $q_{j}>0(j=1,2, \ldots, m)$.

Theorem 2.4. If $\alpha_{i}>0, \beta_{j}>0, q_{j}>0,(i=1,2, \ldots, n ; j=1,2, \ldots, m)$, then system (1.1)-1.2) is uniformly persistent.

Proof. It follows from Lemma 2.2 that any solution of system $\sqrt{1.1}-(1.2)$ which has a nonnegative initial condition remains nonnegative. From equation 1.1), we have $\dot{x}_{i} \leq x_{i}\left(b_{i}^{M}-a_{i i}^{L} x_{i}\right)+\phi_{i}^{M}$. For any initial value $x_{i}(0)>0$, from Lemma 2.1, we have

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} x_{i}(t) \leq \frac{b_{i}^{M}}{a_{i i}^{L}}+\sqrt{\frac{\phi_{i}^{M}}{a_{i i}^{L}}}=p_{i}, \quad(i=1,2, \ldots, n) . \tag{2.1}
\end{equation*}
$$

From (1.2), we have $\dot{y}_{j} \leq y_{j}\left(-r_{j}^{L}+\sum_{k=1}^{n} d_{j k}^{M}-e_{j j}^{L} y_{j}\right)$. Thus for any $y_{j}(0)>0$, from Lemma 2.1, we have

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} y_{j}(t) \leq \frac{1}{e_{j j}^{L}}\left(-r_{j}^{L}+\sum_{k=1}^{n} d_{j k}^{M}\right)=q_{j}, \quad(j=1,2, \ldots, m) \tag{2.2}
\end{equation*}
$$

For $\varepsilon_{1}>0$ small enough, there exists $t_{1}>0$ such that

$$
\begin{equation*}
x_{k}(t)<p_{k}+\varepsilon_{1}, \text { and } y_{k}(t)<q_{k}+\varepsilon_{1} \tag{2.3}
\end{equation*}
$$

for $t>t_{1}$. From (1.1) and inequality (2.3), we have

$$
\begin{equation*}
\dot{x}_{i} \geq x_{i}\left(b_{i}^{L}-\sum_{k=1, k \neq i}^{n} a_{i k}^{M}\left(p_{k}+\epsilon_{1}\right)-\sum_{k=1}^{m} \frac{c_{i k}^{M}\left(q_{k}+\epsilon_{1}\right)\left(p_{i}+\epsilon_{1}\right)}{f_{i k}^{L}}-a_{i i}^{M} x_{i}\right)+\phi_{i}^{L}, \tag{2.4}
\end{equation*}
$$

$(i=1,2, \ldots, n)$ for $t>t_{1}$. From the above inequality, for any initial value $x_{i}(0)>0$, using Lemma 2.1, we get

$$
\liminf _{t \rightarrow+\infty} x_{i}(t) \geq \frac{1}{a_{i i}^{M}}\left(b_{i}^{L}-\sum_{k=1, k \neq i}^{n} a_{i k}^{M}\left(p_{k}+\epsilon_{1}\right)-\sum_{k=1}^{m} \frac{c_{i k}^{M}\left(q_{k}+\epsilon_{1}\right)\left(p_{i}+\epsilon_{1}\right)}{f_{i k}^{L}}\right)+\sqrt{\frac{\phi_{i}^{L}}{a_{i i}^{M}}}
$$

$(i=1,2, \ldots, n)$. Let $\epsilon_{1} \rightarrow 0$, we have

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} x_{i}(t) \geq \frac{1}{a_{i i}^{M}}\left(b_{i}^{L}-\sum_{k=1, k \neq i}^{n} a_{i k}^{M} p_{k}-\sum_{k=1}^{m} \frac{c_{i k}^{M} q_{k} p_{i}}{f_{i k}^{L}}\right)+\sqrt{\frac{\phi_{i}^{L}}{a_{i i}^{M}}}=\alpha_{i} \tag{2.5}
\end{equation*}
$$

$(i=1,2, \ldots, n)$. For $\epsilon_{2}>0$ small enough, there exists $t_{2}>t_{1}$ such that

$$
\begin{equation*}
x_{k}(t)>\alpha_{k}-\epsilon_{2}>0, \quad(k=1,2, \ldots, n) \tag{2.6}
\end{equation*}
$$

for $t>t_{2}$. Using equation (1.2) and inequalities (2.3) and (2.6), we have

$$
\dot{y}_{j} \geq y_{j}\left(-r_{j}^{M}+\sum_{k=1}^{n} \frac{d_{j k}^{L}\left(\alpha_{k}-\epsilon_{2}\right)^{2}}{f_{j k}^{M}+\left(p_{k}+\epsilon_{1}\right)^{2}}-\sum_{k=1, k \neq j}^{m} e_{j k}^{M}\left(q_{k}+\epsilon_{1}\right)-e_{j j}^{M} y_{j}\right), \quad t>t_{2} .
$$

So, for any initial value $y_{j}(0)>0$, from Lemma 2.1, we obtain

$$
\liminf _{t \rightarrow+\infty} y_{j}(t) \geq \frac{1}{e_{j j}^{M}}\left(-r_{j}^{M}+\sum_{k=1}^{n} \frac{d_{j k}^{L}\left(\alpha_{k}-\epsilon_{2}\right)^{2}}{f_{j k}^{M}+\left(p_{k}+\epsilon_{1}\right)^{2}}-\sum_{k=1, k \neq j}^{m} e_{j k}^{M}\left(q_{k}+\epsilon_{1}\right)\right)
$$

$(j=1,2, \ldots, m)$, by the arbitrariness of $\epsilon_{1}$ and $\epsilon_{2}$, we have

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} y_{j}(t) \geq \frac{1}{e_{j j}^{M}}\left(-r_{j}^{M}+\sum_{k=1}^{n} \frac{d_{j k}^{L} \alpha_{k}^{2}}{f_{j k}^{M}+p_{k}^{2}}-\sum_{k=1, k \neq j}^{m} e_{j k}^{M} q_{k}\right)=\beta_{j} \tag{2.7}
\end{equation*}
$$

$(j=1,2, \ldots, m)$. Then, from (2.1), 2.5) and 2.2, 2.7), we conclude that system (1.1)-1.2) is uniformly persistent.

Assume $K_{0}=\left\{F=(X, Y) \in R_{+}^{n+m}: \alpha_{i}^{\star} \leq x_{i}(t) \leq p_{i}^{\star}(i=1,2, \ldots, n), \beta_{j}^{\star} \leq\right.$ $\left.y_{j}(t) \leq q_{j}^{\star}(j=1,2, \ldots, m)\right\}$, where

$$
\begin{equation*}
0<\alpha_{i}^{\star}<\alpha_{i}, \quad p_{i}^{\star}>p_{i}, \quad 0<\beta_{j}^{\star}<\beta_{j}, \quad q_{j}^{\star}>q_{j} . \tag{2.8}
\end{equation*}
$$

Corollary 2.5. $K_{0}$ is an invariant set with respect to system 1.1-1.2 and is ultimately bounded area of the solution of (1.1)-1.2.

Proof. Since $\alpha_{i} \leq \liminf _{t \rightarrow+\infty} x_{i}(t) \leq \lim \sup _{t \rightarrow+\infty} x_{i}(t) \leq p_{i}$, then there exists $t_{1}>0$ such that $\alpha_{i}^{\star} \leq x_{i}(t) \leq P_{i}^{\star}$ for $t \geq t_{1}$.

By analogy with $x_{i}$, we know that there exists $t_{2}>t_{1}$, such that $\beta_{j}^{\star} \leq y_{j}(t) \leq q_{j}^{\star}$ for $t \geq t_{2}$. It is obvious that $0<\alpha_{i}^{\star}<p_{i}^{\star}$ and $0<\beta_{j}^{\star}<q_{j}^{\star}$ are independent of any positive solution of system (1.1) 1.2. So for any solution $F=$ $\left(x_{1}(t), \ldots, x_{n}(t), y_{1}(t), \ldots, y_{m}(t)\right)$ with positive initial value, we have

$$
\left(x_{1}(t), \ldots, x_{n}(t) ; y_{1}(t), \ldots, y_{m}(t)\right) \in K_{0}
$$

for $t \geq t_{2}$.

## 3. Existence of Positive Periodic Solution

In this section, we assume that all the coefficient functions are $\omega$-periodic $(\omega>0)$, continuous and nonnegative, and $b_{i}(t), r_{j}(t), a_{i i}(t), e_{j j}(t)$ are positive functions, then system $1.1-1.2$ will be a $\omega$ period system.

Lemma 3.1 (10). Suppose that a continuous operator $U$ maps a closed bounded convex set $\Omega \subset R^{n}$ into itself. Then $\Omega$ contains at least one fixed point of $U$; that is, there exists at least one $z \in \Omega$ for which $U z=z$ holds.

Theorem 3.2. If system (1.1)-1.2 satisfies conditions (2.8), then system (1.1)(1.2) at least have a positive $\omega$ period solution in $R^{+}$.

Proof. Firstly we define a Poincaré mapping $P: R^{n+m} \rightarrow R^{n+m}$, i.e. $P x_{0}=x(\omega+$ $\left.t_{0} ; t_{0} ; x_{0}\right)$, here $x_{0}=\left(x_{1}\left(t_{0}\right), x_{2}\left(t_{0}\right), \ldots, x_{n}\left(t_{0}\right) ; y_{1}\left(t_{0}\right), y_{2}\left(t_{0}\right), \ldots, y_{m}\left(t_{0}\right)\right) \in R_{+}^{n+m}$. It is easy to know, if $P$ has a fixed point $x^{\star} \in R_{+}^{n+m}$, it is equivalent that system (1.1)-(1.2) at least have a $\omega$ period positive solution. For $K_{0}$ mentioned above, it is obvious that $K_{0} \subset R_{+}^{n+m}$ is a bounded closed convex set and a positive invariant set with system $M_{0}$.

Since the solution is continuous with the initial value, if $x_{0} \in K_{0}$, then $P$ is continuous with $x_{0}$ in $K_{0}$ and $P$ maps $K_{0}$ into itself. That is to say that if $x_{0} \in K_{0}$, then $x\left(t+t_{0} ; t_{0}, x_{0}\right) \in K_{0}\left(t \geq t_{0}\right)$. Let $t=\omega$, we have $x\left(\omega+t_{0} ; t_{0}, x_{0}\right) \in K_{0}$, i.e. $P K_{0} \subset K_{0}$. By Lemma 3.1 we know that $P$ at least have a fixed point $x^{\star}$, i.e. $P x^{\star}=x^{\star}$, and then the corresponding system $\sqrt{1.1}-(1.2)$ at least have a $\omega$ positive period solution.

## 4. Global Asymptotic Stability and Uniqueness of the Positive Period Solution

Without loss of generality, we assume $m \leq n, c_{i k}=0, k=m+1, \ldots, n, i=$ $1,2, \ldots, n$, let $p=\max _{1 \leq i \leq n}\left\{p_{i}\right\}, \alpha=\min _{1 \leq i \leq n}\left\{\alpha_{i}\right\}, q=\max _{1 \leq j \leq m}\left\{q_{j}\right\}$, and $\beta=\min _{1 \leq j \leq m}\left\{\beta_{j}\right\}$.

In the following, we assume that
(A) $q_{j}>0, \alpha_{i}>0$ and $\beta_{j}>0,(i=1,2, \ldots, n ; j=1,2, \ldots, m)$.
(B)

$$
\begin{gathered}
\alpha=\min \left\{a_{i i}(t)-\sum_{k=1, k \neq i}^{n}\left(a_{i k}(t)+\frac{c_{i k}(t)\left(f_{i k}(t)+p^{2}\right) q}{f_{i k}^{2}(t)}\right)-\sum_{j=1}^{m} \frac{2 d_{j i}(t) p}{f_{j i}(t)},\right. \\
\left.\frac{\alpha c_{j j}(t)}{f_{j j}(t)+p^{2}}-\sum_{k=1, k \neq j}^{n} \frac{\alpha c_{j k}(t)}{f_{j k}(t)+p^{2}}-\sum_{k=1}^{m} e_{j k}(t)\right\}>0 \\
(i=1,2, \ldots, n ; j=1,2, \ldots, m)
\end{gathered}
$$

Lemma 4.1 ([1]). Let $g$ be a nonnegative function defined on $[0,+\infty)$ such that $g$ is integrable on $[0,+\infty)$ and is uniformly continuous on $[0,+\infty)$. Then

$$
\lim _{t \rightarrow+\infty} g(t)=0
$$

Theorem 4.2. If system (1.1)-(1.2) satisfies the conditions $(\mathrm{A})$ and $(\mathrm{B})$, then system (1.1-(1.2) has a unique positive period solution which is globally asymptotically stable.

Proof. Let $G(t)=\left(u_{1}(t), u_{2}(t), \ldots, u_{n}(t), v_{1}(t), v_{2}(t), \ldots, v_{m}(t)\right) \in R_{+}^{n+m}$ be a positive periodic solution obtained in the proof of Theorem 3.2, and let $F(t)=$ $\left(x_{1}(t), x_{2}(t), \ldots, x_{n}(t), y_{1}(t), y_{2}(t), \ldots, y_{m}(t)\right) \in R_{+}^{n+m}$ be a solution of $1.1-1.2$ with $F(0)>0$. Since solution of system $\sqrt[1.1]{1.2}$ remains positive, we can set

$$
\begin{array}{cc}
U_{i}(t)=\ln u_{i}(t), \quad X_{i}(t)=\ln x_{i}(t) \quad(i=1,2, \ldots, n) \\
V_{j}(t)=\ln v_{j}(t), \quad Y_{j}(t)=\ln y_{j}(t) \quad(j=1,2, \ldots, m)
\end{array}
$$

Consider a Lyapunov function $V(t)=\sum_{i=1}^{n}\left|U_{i}(t)-X_{i}(t)\right|+\sum_{j=1}^{m}\left|V_{j}(t)-Y_{j}(t)\right|$. Now we calculate and estimate the upper right derivative of $V(t)$ along the solution
of system $1.1-(1.2)$ :

$$
\begin{aligned}
& D^{+} \\
& \leq V(t) \\
& \leq \sum_{i=1}^{n} \frac{U_{i}(t)-X_{i}(t)}{\left|U_{i}(t)-X_{i}(t)\right|}\left(\dot{U}_{i}(t)-\dot{X}_{i}(t)\right)+\sum_{j=1}^{m} \frac{V_{j}(t)-Y_{j}(t)}{\left|V_{j}(t)-Y_{j}(t)\right|}\left(\dot{V}_{j}(t)-\dot{Y}_{j}(t)\right) \\
& \leq \sum_{i=1}^{n} \frac{U_{i}(t)-X_{i}(t)}{\left|U_{i}(t)-X_{i}(t)\right|}\left[-\sum_{k=1}^{n} a_{i k}(t)\left(e^{U_{k}(t)}-e^{X_{k}(t)}\right)-\sum_{k=1}^{m} \frac{c_{i k}(t) u_{i}(t)\left(e^{V_{k}(t)}-e^{Y_{k}(t)}\right)}{f_{i k}(t)+u_{i}^{2}(t)}\right. \\
&+\sum_{k=1}^{m} \frac{c_{i k}(t) y_{k}(t)\left(-f_{i k}(t)+x_{i}(t) u_{i}(t)\right)\left(e^{U_{i}(t)}-e^{X_{i}(t)}\right)}{\left(f_{i k}(t)+u_{i}^{2}(t)\right)\left(f_{i k}(t)+x_{i}^{2}(t)\right)} \\
&+\sum_{j=1}^{m} \frac{V_{j}(t)-Y_{j}(t)}{\left|V_{j}(t)-Y_{j}(t)\right|}\left[-\sum_{k=1}^{m} e_{j k}(t)\left(e^{V_{k}(t)}-e^{Y_{k}(t)}\right)\right. \\
&+\sum_{k=1}^{n} \frac{d_{j k}(t) f_{j k}(t)\left(u_{k}(t)+x_{k}(t)\right)\left(e^{U_{k}(t)}-e^{X_{k}(t)}\right)}{\left(f_{j k}(t)+u_{k}^{2}(t)\right)\left(f_{j k}(t)+x_{k}^{2}(t)\right)} \\
& \leq \sum_{i=1}^{n}\left[\sum_{k=1, k \neq i}^{n}\left(a_{i k}(t)+\frac{c_{i k}(t)\left(f_{i k}(t)+p^{2}\right) q}{f_{i k}^{2}(t)}\right)+\sum_{j=1}^{m} \frac{2 d_{j i}(t) p}{f_{j i}(t)}-a_{i i}(t)\right]\left|e^{U_{i}(t)}-e^{X_{i}(t)}\right| \\
&+\sum_{j=1}^{m}\left[-\frac{\alpha c_{j j}(t)}{f_{j j}(t)+p^{2}}+\sum_{k=1, k \neq j}^{n} \frac{\alpha c_{j k}(t)}{f_{j k}(t)+p^{2}}+\sum_{k=1}^{m} e_{j k}(t)\right]\left|e^{V_{j}(t)}-e^{Y_{j}(t)}\right| \\
& \leq-\alpha\left[\sum_{i=1}^{n}\left|u_{i}(t)-x_{i}(t)\right|+\sum_{j=1}^{m}\left|v_{j}(t)-y_{j}(t)\right|\right] .
\end{aligned}
$$

An integration of the above inequality leads to

$$
V(t)+\alpha \int_{0}^{t}\left[\sum_{i=1}^{n}\left|u_{i}(t)-x_{i}(t)\right|+\sum_{j=1}^{m}\left|v_{j}(t)-y_{j}(t)\right|\right]<V(0)<+\infty
$$

Then

$$
\limsup _{t \rightarrow+\infty} \int_{0}^{t}\left[\sum_{i=1}^{n}\left|u_{i}(t)-x_{i}(t)\right|+\sum_{j=1}^{m}\left|v_{j}(t)-y_{j}(t)\right|\right] \leq \frac{V(0)}{\alpha}<+\infty
$$

Thus by Lemma 4.1 we have

$$
\begin{aligned}
\lim _{t \rightarrow+\infty}\left|u_{i}(t)-x_{i}(t)\right| & =0 \quad(i=1,2, \ldots, n) \\
\lim _{t \rightarrow+\infty}\left|v_{j}(t)-y_{j}(t)\right| & =0(j=1,2, \ldots, m)
\end{aligned}
$$

This implies that the positive $\omega$ periodic solution $G(t)$ is globally asymptotically stable, and then it is unique.

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Jiwei He
School of Mathematics and Physics, North China Electric Power University, Baoding, 071003, China

E-mail address: hejiwei313@163.com


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