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# EXISTENCE OF SOLUTIONS FOR NONCONVEX FUNCTIONAL DIFFERENTIAL INCLUSIONS 

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#### Abstract

We prove the existence of solutions for the functional differential inclusion $x^{\prime} \in F(T(t) x)$, where $F$ is upper semi-continuous, compact-valued multifunction such that $F(T(t) x) \subset \partial V(x(t))$ on $[0, T], V$ is a proper convex and lower semicontinuous function, and $(T(t) x)(s)=x(t+s)$.


## 1. Introduction

Let $\mathbb{R}^{m}$ be the $m$-dimensional Euclidean space with the norm $\|\cdot\|$ and the scalar product $\langle\cdot, \cdot\rangle$. When $I$ is a segment in $\mathbb{R}$, we denote by $\mathcal{C}\left(I, \mathbb{R}^{m}\right)$ the Banach space of continuous functions from $I$ to $\mathbb{R}^{m}$ with the norm $\|x(.)\|_{\infty}:=\sup \{\|x(t)\| ; t \in I\}$. When $\sigma$ is a positive number, we put $\mathcal{C}_{\sigma}:=\mathcal{C}\left([-\sigma, 0], \mathbb{R}^{m}\right)$ and for any $t \in[0, T]$, $T>0$, we define the operator $T(t)$ from $\mathcal{C}\left([-\sigma, T], \mathbb{R}^{m}\right)$ to $\mathcal{C}_{\sigma}$ as $(T(t) x)(s):=$ $x(t+s), s \in[-\sigma, 0]$.

Let $\Omega$ be a nonempty subset in $\mathcal{C}_{\sigma}$. For a given multifunction $F: \Omega \rightarrow 2^{\mathbb{R}^{m}}$ we consider the following functional differential inclusion:

$$
\begin{equation*}
x^{\prime} \in F(T(t) x) . \tag{1.1}
\end{equation*}
$$

We recall that a continuous function $x():.[-\sigma, T] \rightarrow \mathbb{R}^{m}$ is said to be a solution of (1.1) if $x($.$) is absolutely continuous on [0, T], T(t) x \in \Omega$ for all $t \in[0, T]$ and $x^{\prime}(t) \in F(T(t) x)$ for almost all $t \in[0, T]$; see 8].

The functional differential equation (1.1) with $F$ single-valued, has been studied by many authors; for results, references, and applications, see for example (9, 10.

The existence of solutions for the functional differential inclusion (1.1) was proved by Haddad [8] when $F$ is upper semicontinuous with convex compact values. The nonconvex case in Banach space has been studied by Benchohra and Ntouyas [2]. The case when $F$ is lower semicontinuous with compact value has been studied by Fryszkowski [7].

In this paper we prove the existence of solutions for functional differential inclusion 1.1 when $F$ is upper semicontinuous, compact valued multifunction such that $F(\psi) \subset \partial V(\psi(0))$ for every $\psi \in \Omega$ and $V$ is a proper convex and lower semicontinuous function. Our existence result contains Peano's existence theorem as a

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particular case. On the other hand, our result may be considered as an extension of the previous result of Bressan, Cellina and Colombo [3].

## 2. Preliminaries and statement of the main result

For $x \in \mathbb{R}^{m}$ and $r>0$ let $B(x, r):=\left\{y \in \mathbb{R}^{m} ;\|y-x\|<r\right\}$ be the open ball centered at $x$ with radius $r$, and let $\bar{B}(x, r)$ be its closure. For $\varphi \in \mathcal{C}_{\sigma}$ let $B_{\sigma}(\varphi, r):=\left\{\psi \in \mathcal{C}_{\sigma} ;\|\psi-\varphi\|_{\infty}<r\right\}$ and $\bar{B}_{\sigma}(\varphi, r):=\left\{\psi \in \mathcal{C}_{\sigma} ;\|\psi-\varphi\|_{\infty} \leq r\right\}$. For $x \in \mathbb{R}^{m}$ and for a closed subset $A \subset \mathbb{R}^{m}$ we denote by $d(x, A)$ the distance from $x$ to $A$ given by $d(x, A):=\inf \{\|y-x\| ; y \in A\}$. Given a function $V: \mathbb{R}^{m} \rightarrow \mathbb{R} \cup\{+\infty\}$ let

$$
D(V):=\left\{x \in \mathbb{R}^{m}: V(x)<+\infty\right\}
$$

be its effective domain. We say that $V$ is proper function if $D(V)$ is nonempty.
Let $V: \mathbb{R}^{m} \rightarrow \mathbb{R}$ be a proper convex and lower semicontinuous function. The multifunction $\partial V: \mathbb{R}^{m} \rightarrow 2^{\mathbb{R}^{m}}$, defined by

$$
\begin{equation*}
\partial V(x):=\left\{\xi \in \mathbb{R}^{m} ; V(y)-V(x) \geq\langle\xi, y-x\rangle, \quad \forall y \in \mathbb{R}^{m}\right\} \tag{2.1}
\end{equation*}
$$

is called subdifferential (in the sense of convex analysis) of the function $V$.
We say that a multifunction $F: \Omega \subset \mathcal{C}_{\sigma} \rightarrow 2^{\mathbb{R}^{m}}$ is upper semicontinuous if for every $\varphi \in \Omega$ and for every $\varepsilon>0$ there exists $\delta>0$ such that

$$
F(\psi) \subset F(\varphi)+B(0, \varepsilon), \quad \forall \psi \in \Omega \cap B_{\sigma}(\varphi, \delta)
$$

The definition of the upper semicontinuous multifunctions is the same as [6, Definition 1.2].

For a multifunction $F: \Omega \rightarrow 2^{\mathbb{R}^{m}}$ we consider the functional differential inclusion (1.1) under the following assumptions:
(H1) $\Omega \subset \mathcal{C}_{\sigma}$ is an open set and $F$ is upper semicontinuous with compact values;
(H2) There exists a a proper convex and lower semicontinuous function $V: \mathbb{R}^{m} \rightarrow$ $\mathbb{R}$ such that

$$
\begin{equation*}
F(\psi) \subset \partial V(\psi(0)) \text { for every } \psi \in \Omega \tag{2.2}
\end{equation*}
$$

Remark. A convex function $V: \mathbb{R}^{m} \rightarrow \mathbb{R}$ is continuous in the whole space $\mathbb{R}^{m}$ [11, Corollary 10.1.1] and almost everywhere differentiable [11, Theorem 25.5]. Therefore, (H2) restricts strongly the multivaluedness of $F$.

Our main result is the following:
Theorem 2.1. If $F: \Omega \rightarrow 2^{\mathbb{R}^{m}}$ and $V: \mathbb{R}^{m} \rightarrow \mathbb{R}$ satisfy assumptions (H1) and (H2) then for every $\varphi \in \Omega$ there exists $T>0$ and $x():.[-\sigma, T] \rightarrow \mathbb{R}^{m}$ a solution of the functional differential inclusion (1.1) such that $T(0) x=\varphi$ on $[-\sigma, 0]$.

## 3. Proof of the main result

Let $\varphi \in \Omega$ be arbitrarily fixed. Since the multifunction $x \rightarrow \partial V(x)$ is locally bounded [4, Proposition 2.9], there exists $r>0$ and $M>0$ such that $V$ is Lipschitz continuous with constant $M$ on $B(\varphi(0), r)$. Since $\Omega$ is an open set we can choose $r$ such that $\bar{B}_{\sigma}(\varphi, r) \subset \Omega$. Moreover, by [1, Proposition 1.1.3], $F$ is locally bounded; therefore, we can assume that

$$
\begin{equation*}
\sup \{\|y\|: y \in F(\psi), \psi \in B(\varphi, r)\} \leq M \tag{3.1}
\end{equation*}
$$

Since $\varphi$ is continuous on $[-\sigma, 0]$ we can choose $\eta>0$ such that

$$
\begin{equation*}
\|\varphi(t)-\varphi(s)\|<r / 4 \text { for all } t, s \in[-\sigma, 0] \text { with }|t-s|<\eta . \tag{3.2}
\end{equation*}
$$

Let $0<T \leq \min \{\eta, r / 4 M\}$. We shall prove the existence of a solution of 1.1 . defined on the interval $[-\sigma, T]$. For this, we define a family of approximate solutions and we prove that a subsequence converges to a solution of (1.1).

First, for a fixed $n \in \mathbb{N}^{*}$, we set

$$
\begin{equation*}
x_{n}(t)=\varphi(t), t \in[-\sigma, 0] . \tag{3.3}
\end{equation*}
$$

Furthermore, we partition $[0, T]$ by points $t_{n}^{j}:=\frac{j T}{n}, j=0,1, \ldots, n$, and, for every $t \in\left[t_{n}^{j}, t_{n}^{j+1}\right]$, we define

$$
\begin{equation*}
x_{n}(t):=x_{n}^{j}+\left(t-t_{n}^{j}\right) y_{n}^{j} \tag{3.4}
\end{equation*}
$$

where $x_{n}^{0}=x_{n}(0):=\varphi(0)$ and

$$
\begin{gather*}
x_{n}^{j}=x_{n}^{j-1}+\frac{T}{n} y_{n}^{j-1}  \tag{3.5}\\
y_{n}^{j} \in F\left(T\left(t_{n}^{j}\right) x_{n}\right) \tag{3.6}
\end{gather*}
$$

for every $j \in\{1,2, \ldots, n\}$. It is easy to see that for every $j \in\{1,2, \ldots, n\}$ we have

$$
\begin{equation*}
x_{n}^{j}=\varphi(0)+\frac{T}{n}\left(y_{n}^{0}+y_{n}^{1}+\cdots+y_{n}^{j-1}\right) \tag{3.7}
\end{equation*}
$$

By (3.1) and (3.7) we infer $\left\|x_{n}^{j}-\varphi(0)\right\| \leq \frac{j T}{n} M<r / 4$, proving that

$$
\begin{equation*}
x_{n}\left(t_{n}^{j}\right)=x_{n}^{j} \in B(\varphi(0), r / 4) \tag{3.8}
\end{equation*}
$$

for every $j \in\{1,2, \ldots, n\}$.
By (3.1) and (3.4) we have that

$$
\begin{equation*}
\left\|x_{n}(t)-x_{n}\left(t_{n}^{j}\right)\right\|=\left\|x_{n}(t)-x_{n}^{j}\right\| \leq \frac{j T}{n} M<\frac{r}{4} \tag{3.9}
\end{equation*}
$$

for every $j \in\{0,1, \ldots, n\}$. Hence, from (3.8) and (3.9) we deduce that

$$
\left\|x_{n}(t)-\varphi(0)\right\| \leq\left\|x_{n}(t)-x_{n}\left(t_{n}^{j}\right)\right\|+\left\|x_{n}\left(t_{n}^{j}\right)-\varphi(0)\right\|<\frac{r}{2}
$$

and so

$$
\begin{equation*}
x_{n}(t) \in B\left(\varphi(0), \frac{r}{2}\right), \text { for every } t \in[0, T] \tag{3.10}
\end{equation*}
$$

Moreover, by (3.1), (3.4) and (3.6), we have $\left\|x_{n}^{\prime}(t)\right\| \leq M$ for every $t \in[0, T]$ and so the sequence $\left(x_{n}^{\prime}\right)$ is bounded in $L^{2}\left([0, T], \mathbb{R}^{m}\right)$.

For $t, s \in[0, T]$, we have

$$
\left\|x_{n}(t)-x_{n}(s)\right\| \leq\left|\int_{s}^{t}\left\|x_{n}^{\prime}(\tau)\right\| d \tau\right| \leq M|t-s|
$$

so that the sequence $\left(x_{n}\right)$ is equiuniformly continuous. Hence, by Theorem 0.3.4 in [1], there exists a subsequence, still denoted by $\left(x_{n}\right)$, and an absolute continuous function $x:[0, T] \rightarrow \mathbb{R}^{m}$ such that:
(i) $\left(x_{n}\right)$ converges uniformly on $[0, T]$ to $x$;
(ii) $\left(x_{n}^{\prime}\right)$ converges weakly in $L^{2}\left([0, T], \mathbb{R}^{m}\right)$ to $x^{\prime}$.

Moreover, since by (3.3) all functions $x_{n}$ agree with $\varphi$ on $[-\sigma, 0]$, we can obviously say that $x_{n} \rightarrow x$ on $[-\sigma, T]$, if we extend $x$ in such a way that $x \equiv \varphi$ on $[-\sigma, 0]$. Also, it is clearly that $T(0) x=\varphi$ on $[-\sigma, 0]$.

Further on, if we define $\theta_{n}(t)=t_{n}^{j}$ for all $t \in\left[t_{n}^{j}, t_{n}^{j+1}\right]$ then, by (3.4) and (3.6), we have

$$
\begin{equation*}
x_{n}^{\prime}(t) \in F\left(T\left(\theta_{n}(t)\right) x_{n}\right), \text { a.e. on }[0, T] . \tag{3.11}
\end{equation*}
$$

and, by (3.8),

$$
\begin{equation*}
x_{n}\left(\theta_{n}(t)\right) \in B\left(\varphi(0), \frac{r}{4}\right), \text { for every } t \in[0, T] . \tag{3.12}
\end{equation*}
$$

Also, since $\left|\theta_{n}(t)-t\right| \leq \frac{T}{n}$ for every $t \in[0, T]$, then $\theta_{n}(t) \rightarrow t$ uniformly on $[0, T]$. Moreover, by the uniformly converges of $\left(x_{n}\right)$ and $\left(\theta_{n}\right)$, we deduce that $x_{n}\left(\theta_{n}(t)\right) \rightarrow x(t)$ uniformly on $[0, T]$.

Now, we have to estimate $\left\|\left(T\left(\theta_{n}(t)\right) x_{n}\right)(s)-\varphi(s)\right\|$ for each $s \in[-\sigma, 0]$. If $-\theta_{n}(t) \leq s \leq 0$, then $\theta_{n}(t)+s \geq 0$ and so there exists $j \in\{0,1, \ldots, n-1\}$ such that $\theta_{n}(t)+s \in\left[t_{n}^{j}, t_{n}^{j+1}\right]$. Thus, by (3.2), (3.10) and by the fact that $\left|\theta_{n}(t)-t\right| \leq T$ and $|s| \leq T$, we have

$$
\begin{aligned}
\left\|\left(T\left(\theta_{n}(t)\right) x_{n}\right)(s)-\varphi(s)\right\| & =\left\|x_{n}\left(\theta_{n}(t)+s\right)-\varphi(s)\right\| \\
& \leq\left\|x_{n}\left(\theta_{n}(t)+s\right)-\varphi(0)\right\|+\|\varphi(s)-\varphi(0)\| \\
& <\frac{3 r}{4}<r
\end{aligned}
$$

If $-\sigma \leq s \leq-\theta_{n}(t)$ then $s+\theta_{n}(t) \leq 0$ and by 3.2 we have

$$
\left\|\left(T\left(\theta_{n}(t)\right) x_{n}\right)(s)-\varphi(s)\right\|=\left\|\varphi\left(\theta_{n}(t)+s\right)-\varphi(s)\right\| \leq \frac{r}{4}<r
$$

Therefore,

$$
\begin{equation*}
T\left(\theta_{n}(t)\right) x_{n} \in B(\varphi, r), \quad \text { for every } t \in[0, T] \tag{3.13}
\end{equation*}
$$

Let us denote the modulus continuity of a function $\psi$ defined on interval $I$ of $\mathbb{R}$ by

$$
\omega(\psi, I, \varepsilon):=\sup \{\|\psi(t)-\psi(s)\| ; s, t \in I,|s-t|<\varepsilon\}, \varepsilon>0
$$

Then we have:

$$
\begin{aligned}
\left\|T\left(\theta_{n}(t)\right) x_{n}-T(t) x_{n}\right\|_{\infty} & =\sup _{-\sigma \leq s \leq 0}\left\|x_{n}\left(\theta_{n}(t)+s\right)-x_{n}(t+s)\right\| \\
& \leq \omega\left(x_{n},[-\sigma, T], \frac{T}{n}\right) \\
& \leq \omega\left(\varphi,[-\sigma, 0], \frac{T}{n}\right)+\omega\left(x_{n},[0, T], \frac{T}{n}\right) \\
& \leq \omega\left(\varphi,[-\sigma, 0], \frac{T}{n}\right)+\frac{T}{n} M
\end{aligned}
$$

hence

$$
\begin{equation*}
\left\|T\left(\theta_{n}(t)\right) x_{n}-T(t) x_{n}\right\|_{\infty} \leq \delta_{n} \quad \text { for every } t \in[0, T] \tag{3.14}
\end{equation*}
$$

where $\delta_{n}:=\omega\left(\varphi,[-\sigma, 0], \frac{T}{n}\right)+\frac{T}{n} M$. Thus, by continuity of $\varphi$, we have $\delta_{n} \rightarrow 0$ as $n \rightarrow \infty$ and hence

$$
\left\|T\left(\theta_{n}(t)\right) x_{n}-T(t) x_{n}\right\|_{\infty} \rightarrow 0 \text { as } n \rightarrow \infty
$$

Therefore, since the uniform convergence of $x_{n}$ to $x$ on $[-\sigma, T]$ implies

$$
\begin{equation*}
T(t) x_{n} \rightarrow T(t) x \quad \text { uniformly on }[-\sigma, 0] \tag{3.15}
\end{equation*}
$$

we deduce that

$$
\begin{equation*}
T\left(\theta_{n}(t)\right) x_{n} \rightarrow T(t) x \quad \text { in } \mathcal{C}_{\sigma} \tag{3.16}
\end{equation*}
$$

Moreover, by (3.13) and (3.16), we have that $T(t) x \in \bar{B}_{\sigma}(\varphi, r) \subset \Omega$. Also, by 3.11) and (3.14), we have

$$
\begin{equation*}
d\left(\left(T(t) x_{n}, x_{n}^{\prime}(t)\right), \operatorname{graph}(F)\right) \leq \delta_{n} \quad \text { for every } t \in[0 . T] \tag{3.17}
\end{equation*}
$$

By (H2), (ii), 3.16) and [1, Theorem 1.4.1], we obtain

$$
\begin{equation*}
x^{\prime}(t) \in \operatorname{coF}(T(t) x) \subset \partial V(x(t)) \quad \text { a.e. on }[0, T] \tag{3.18}
\end{equation*}
$$

where co stands for the closed convex hull.
Since the functions $t \rightarrow x(t)$ and $t \rightarrow V(x(t))$ are absolutely continuous, we obtain from [4, Lemma 3.3] and (3.18) that

$$
\frac{d}{d t} V(x(t))=\left\|x^{\prime}(t)\right\|^{2} \quad \text { a.e. on }[0, T]
$$

therefore,

$$
\begin{equation*}
V(x(T))-V(x(0))=\int_{0}^{T}\left\|x^{\prime}(t)\right\|^{2} d t \tag{3.19}
\end{equation*}
$$

On the other hand, since

$$
x_{n}^{\prime}(t)=y_{n}^{j} \in F\left(T\left(t_{n}^{j}\right) x_{n}\right) \subset \partial V\left(x_{n}\left(t_{n}^{j}\right)\right)
$$

for every $t \in\left[t_{n}^{j}, t_{n}^{j+1}\right]$ and for every $j \in\{0,1, \ldots, n-1\}$, it follows that

$$
\begin{aligned}
V\left(x_{n}\left(t_{n}^{j+1}\right)\right)-V\left(x_{n}\left(t_{n}^{j}\right)\right) & \geq\left\langle x_{n}^{\prime}(t), x_{n}\left(t_{n}^{j+1}\right)-x_{n}\left(t_{n}^{j}\right)\right\rangle \\
& =\left\langle x_{n}^{\prime}(t), \int_{t_{n}^{j}}^{t_{n}^{j+1}} x_{n}^{\prime}(t) d t\right\rangle=\int_{t_{n}^{j}}^{t_{n}^{j+1}}\left\|x^{\prime}(t)\right\|^{2} d t .
\end{aligned}
$$

By adding the $n$ inequalities above, we obtain

$$
V\left(x_{n}(T)\right)-V(x(0)) \geq \int_{0}^{T}\left\|x_{n}^{\prime}(t)\right\|^{2} d t
$$

and passing to the limit as $n \rightarrow \infty$, we obtain

$$
\begin{equation*}
V(x(T))-V(x(0)) \geq \limsup _{n \rightarrow \infty} \int_{0}^{T}\left\|x_{n}^{\prime}(t)\right\|^{2} d t \tag{3.20}
\end{equation*}
$$

Therefore, by b3.19 and 3.20,

$$
\int_{0}^{T}\left\|x^{\prime}(t)\right\|^{2} d t \geq \limsup _{n \rightarrow \infty} \int_{0}^{T}\left\|x_{n}^{\prime}(t)\right\|^{2} d t
$$

and, since $\left(x_{n}^{\prime}\right)$ converges weakly in $L^{2}\left([0, T], \mathbb{R}^{m}\right)$ to $x^{\prime}$, by applying [5, Proposition III.30], we obtain that $\left(x_{n}^{\prime}\right)$ converges strongly in $L^{2}\left([0, T], \mathbb{R}^{m}\right)$. Hence there exists a subsequence, still denote by $\left(x_{n}^{\prime}\right)$, which converges pointwiese a.e. to $x^{\prime}$.

Since, by (H1), the graph of $F$ is closed [1, Proposition 1.1.2], by (3.17),

$$
\lim _{n \rightarrow \infty} d\left(\left(T(t) x_{n}, x_{n}^{\prime}(t)\right), \operatorname{graph}(F)\right)=0
$$

we obtain

$$
x^{\prime}(t) \in F(T(t) x) \quad \text { a.e. on }[0, T] .
$$

Therefore, the functional differential inclusion (1.1) has solutions.

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