# HOMOCLINIC SOLUTIONS FOR A CLASS OF SECOND-ORDER HAMILTONIAN SYSTEMS WITH LOCALLY DEFINED POTENTIALS 

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Abstract. In this article, we establish sufficient conditions for the existence of homoclinic solutions for a class of second-order Hamiltonian systems

$$
\ddot{u}(t)-L(t) u(t)+\nabla W(t, u(t))=f(t)
$$

where $L(t)$ is a positive definite symmetric matrix for all $t \in \mathbb{R}$. It is worth pointing out that the potential function $W(t, u)$ is locally defined and can be superquadratic or subquadratic with respect to $u$.

## 1. Introduction and statement of main results

The purpose of this article is to investigate the second-order Hamiltonian systems

$$
\begin{equation*}
\ddot{u}(t)-L(t) u(t)+\nabla W(t, u(t))=f(t) \tag{1.1}
\end{equation*}
$$

where $t \in \mathbb{R}, u \in \mathbb{R}^{n}, L \in C\left(\mathbb{R}, \mathbb{R}^{n \times n}\right)$ is a positive definite and symmetric matrix for all $t \in \mathbb{R}, W: \mathbb{R} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$ and $f: \mathbb{R} \rightarrow \mathbb{R}^{n}$. Here, we say that a solution $u(t)$ of (1.1) is nontrivial homoclinic (to 0 ) if $u \not \equiv 0$ and $u(t) \rightarrow 0$ as $t \rightarrow \pm \infty$. Moreover, $\nabla W(t, x)$ denotes the gradient with respect to $x,(\cdot, \cdot): \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}$ denotes the standard inner product in $\mathbb{R}^{n}$ and $|\cdot|$ is the induced norm.

If $f=0$, then (1.1) degenerates to the following second-order Hamiltonian system

$$
\begin{equation*}
\ddot{u}(t)-L(t) u(t)+\nabla W(t, u(t))=0 \tag{1.2}
\end{equation*}
$$

In physics, Hamiltonian systems describe the evolution equations of a physical system, which can present important insight about the dynamics, even if the analytical solution of the initial value problem cannot be obtained. It is well known that a homoclinic orbit lies in the intersection of the stable manifold and the unstable manifold of a saddle point, which is a fundamental tool in the study of chaos. In the past decades, there have been a lot of results about the existence and multiplicity of homoclinic orbits for Hamiltonian systems via critical point theory, see [1, 2, 3, $4,5,5,6,7,8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26$, and the references therein.

In the case that $L(t)$ and $W(t, x)$ are either independent of $t$ or periodic in $t$, it has been studied by many authors, see (1, 4, 7, 8, 9, 11, 17, 16, 18, 22). In particular, in [18, Rabinowitz has proved the existence of homoclinic orbits as a limit of $2 k T$-periodic solutions of (1.2). Motivated by the work of Rabinowitz,

[^0]applying the same procedure, the existence of homoclinic solutions of (1.1) or 1.2 was obtained as the limit of subharmonic solutions, see Izydorek and Janczewska [8, (9) and so on.

In the case that $L(t)$ and $W(t, x)$ are not periodic with respect to $t$, the problem of existence and multiplicity of homoclinic orbits for 1.1 will become much more difficult, due to the lack of compactness of the Sobolev embedding. In [20, Rabinowitz and Tanaka considered (1.2) without a periodicity assumption, both for $L$ and $W$. To deal with the case that the nonlinearity $W$ is superquadratic, they introduced the Ambrosetti-Rabinowitz growth condition, i.e., the following assumption (A1) and assumed that the smallest eigenvalue of $L(t)$ tends to $+\infty$ as $|t| \rightarrow \infty$. Using a variant of the Mountain Pass theorem without the Palais-Smale condition, they proved that (1.2) possesses a nontrivial homoclinic orbit.

For the next theorem we use the following assumptions:
(A1) $L(t)$ is positive definite symmetric matrix for all $t \in \mathbb{R}$ and there exists an $l \in C(\mathbb{R},(0, \infty))$ such that $l(t) \rightarrow+\infty$ as $|t| \rightarrow \infty$ and

$$
(L(t) x, x) \geq l(t)|x|^{2} \quad \text { for all } t \in \mathbb{R} \text { and } x \in \mathbb{R}^{n}
$$

(A2) $W \in C^{1}\left(\mathbb{R} \times \mathbb{R}^{n}, \mathbb{R}\right)$ and there is a constant $\mu>2$ such that

$$
0<\mu W(t, x) \leq(x, \nabla W(t, x)) \quad \text { for all } t \in \mathbb{R} \text { and } x \in \mathbb{R}^{n} \backslash\{0\}
$$

(A3) $|\nabla W(t, x)|=o(|x|)$ as $|x| \rightarrow 0$ uniformly with respect to $t \in \mathbb{R}$;
(A4) There is a $\bar{W} \in C\left(\mathbb{R}^{n}, \mathbb{R}\right)$ such that

$$
|W(t, x)|+|\nabla W(t, x)| \leq|\bar{W}(x)| \quad \text { for all } t \in \mathbb{R} \text { and } x \in \mathbb{R}^{n}
$$

Theorem 1.1 ([20]). Assume that $L$ and $W$ satisfy (A1)-(A4). Then $\sqrt[1.2]{ }$ possesses a nontrivial homoclinic solution.

Motivated by [11, 20, in this paper, we study the existence of Homoclinic solutions for 1.1, where we only give some local assumptions on $W(t, u)$ and $W(t, u)$ can be superquadratic or subquadratic with respect to $u$. Our main results are stated in the next theorem, under the following conditions:
(A5) $W \in C^{1}\left(\mathbb{R} \times \mathbb{R}^{n}, \mathbb{R}\right), W(t, 0) \equiv 0$ and $\nabla W(t, 0) \equiv 0$ for all $t \in \mathbb{R}$;
(A6) there exist $\rho>0$ and $a \in L^{\alpha}\left(\mathbb{R}, \mathbb{R}_{+}\right)$such that

$$
\begin{equation*}
W(t, x) \leq a(t)|x|^{\mu} \quad \text { for all } t \in \mathbb{R} \text { and }|x| \leq \rho, \tag{1.3}
\end{equation*}
$$

where $\alpha>1, \mu>1$ if $\frac{2(\alpha-1)}{\alpha} \leq 1$ or $\mu \geq \frac{2(\alpha-1)}{\alpha}$ if $\frac{2(\alpha-1)}{\alpha}>1$.
(A7) $f \not \equiv 0$ is a continuous and bounded function such that $\int_{\mathbb{R}}|f(t)|^{\beta} d t<\infty$ and

$$
\begin{equation*}
\frac{1 \wedge l_{*}}{4} \rho-\frac{M_{a}}{\sqrt[\alpha+]{2}} \rho^{\mu-1}-\frac{M_{f}}{\sqrt[\beta^{*}]{2}}>0 \tag{1.4}
\end{equation*}
$$

where $1<\beta \leq 2, \frac{1}{\alpha^{*}}+\frac{1}{\alpha}=1, \frac{1}{\beta^{*}}+\frac{1}{\beta}=1, l_{*}=\inf _{t \in \mathbb{R}} l(t)>0$,

$$
M_{a}=\left(\int_{\mathbb{R}}|a(t)|^{\alpha} d t\right)^{1 / \alpha} \quad \text { and } \quad M_{f}=\left(\int_{\mathbb{R}}|f(t)|^{\beta} d t\right)^{1 / \beta}
$$

Theorem 1.2. Assume that (A1), (A5)-(A7). Then 1.1 possesses a nontrivial homoclinic solution.

## 2. Proof of main Results

Motivated by [10, 13], we first consider the existence of the homoclinic solutions for 1.1, which can be obtained as the limit of periodic solutions for the following boundary-value problem

$$
\begin{gather*}
\ddot{u}(t)-L(t) u(t)+\nabla W(t, u(t))=f(t), \quad t \in[-T, T]  \tag{2.1}\\
u(-T)-u(T)=\dot{u}(-T)-\dot{u}(T)=0
\end{gather*}
$$

for all $T \in \mathbb{R}^{+}$.
Given any $T \in \mathbb{R}^{+}$, let

$$
\begin{aligned}
E_{T}:= & W^{1,2}\left([-T, T], \mathbb{R}^{n}\right) \\
= & \left\{u:[-T, T] \rightarrow \mathbb{R}^{n}: u\right. \text { is absolutely continuous, } \\
& \left.u(-T)=u(T) \text { and } \dot{u} \in L^{2}\left([-T, T], \mathbb{R}^{n}\right)\right\}
\end{aligned}
$$

and for $u \in E_{T}$, define

$$
\|u\|_{E_{T}}=\left\{\int_{-T}^{T}\left[|\dot{u}(t)|^{2}+|u(t)|^{2}\right] d t\right\}^{1 / 2}
$$

then $E_{T}$ is a Hilbert space endowed with the above norm.
Next, we define a functional $I_{T}: E_{T} \rightarrow \mathbb{R}$ by

$$
\begin{equation*}
I_{T}(u)=\int_{-T}^{T}\left[\frac{1}{2}|\dot{u}(t)|^{2}+\frac{1}{2}(L(t) u(t), u(t))-W(t, u(t))+(f(t), u(t))\right] d t \tag{2.2}
\end{equation*}
$$

We can easily see that $I_{T} \in C^{1}\left(E_{T}, \mathbb{R}\right)$ is weakly lower semi-continuous because it is the sum of a convex continuous function and of a weakly continuous one. By the direct calculation, it follows that

$$
\begin{align*}
\left\langle I_{T}^{\prime}(u), v\right\rangle= & \int_{-T}^{T}[(\dot{u}(t), \dot{v}(t))+(L(t) u(t), v(t))  \tag{2.3}\\
& -(\nabla W(t, u(t)), v(t))+(f(t), v(t))] d t
\end{align*}
$$

for all $u, v \in E_{T}$. Moreover, it is well known that the critical points of $I_{T}$ in $E_{T}$ are classical solutions of (2.1) (see [15, 19]).

To prove our main result, we apply a critical point theorem, which is stated precisely as follows.
Lemma 2.1 ( See [11). Let $X$ be a real reflexive Banach space and $\Omega \subset X$ be a closed bounded convex subset of $X$. Suppose that $\varphi: X \rightarrow \mathbb{R}$ is weakly lower semi-continuous. If there exists a point $x_{0} \in \Omega \backslash \partial \Omega$ such that

$$
\begin{equation*}
\varphi(x)>\varphi\left(x_{0}\right) \quad \text { for all } x \in \partial \Omega \tag{2.4}
\end{equation*}
$$

Then there exists a $x^{*} \in \Omega \backslash \partial \Omega$ such that

$$
\varphi\left(x^{*}\right)=\inf _{u \in \Omega} \varphi(u)
$$

Lemma 2.2 (See [8). Let $u: \mathbb{R} \rightarrow \mathbb{R}^{n}$ be a continuous mapping such that $\dot{u} \in$ $L_{\text {loc }}^{2}\left(\mathbb{R}, \mathbb{R}^{n}\right)$. Then for every $t \in \mathbb{R}$, we have

$$
\begin{equation*}
|u(t)| \leq \sqrt{2}\left[\int_{t-\frac{1}{2}}^{t+\frac{1}{2}}\left(|\dot{u}(s)|^{2}+|u(s)|^{2}\right) d s\right]^{1 / 2} \tag{2.5}
\end{equation*}
$$

Lemma 2.3. Let $u \in E_{T}$. It follows that

$$
\begin{equation*}
\|u\|_{L_{[-T, T]}^{\infty}} \leq\left(\int_{-T}^{T}|u(t)|^{2} d t\right)^{1 / 2}+\left(\int_{-T}^{T}|\dot{u}(t)|^{2} d t\right)^{1 / 2} \tag{2.6}
\end{equation*}
$$

Note that the above lemma is a special case of [22, Corollary 2.2].
Corollary 2.4. Let $u \in E_{T}$. It follows that

$$
\begin{equation*}
\|u\|_{L_{[-T, T]}^{\infty}} \leq \sqrt{2}\|u\|_{E_{T}}=\sqrt{2}\left\{\int_{-T}^{T}\left[|\dot{u}(t)|^{2}+|u(t)|^{2}\right] d t\right\}^{1 / 2} \tag{2.7}
\end{equation*}
$$

Proof. Combining (2.6) and the inequality $\sqrt{a}+\sqrt{b} \leq \sqrt{2}(a+b)^{1 / 2}$, it is obvious that 2.7 holds.

Lemma 2.5. Under the conditions of Theorem 1.2, the boundary-value problem (2.1) admits a solution $u_{T} \in E_{T}$ such that

$$
\begin{equation*}
\int_{-T}^{T}\left[\left|\dot{u}_{T}(t)\right|^{2}+\left|u_{T}(t)\right|^{2}\right] d t<\frac{1}{2} \rho^{2} \quad \text { for all } T \in \mathbb{R}_{+} \tag{2.8}
\end{equation*}
$$

Proof. Clearly, $I_{T}(0)=0$ by (A5) for all $T \in \mathbb{R}_{+}$. For the purpose of using Lemma 2.1, we first need to construct a closed bounded convex subset of $E_{T}$ for all $T \in \mathbb{R}_{+}$. Given any $T \in \mathbb{R}_{+}$, let $\Omega_{T}:=\left\{u \in E_{T}: \int_{-T}^{T}\left[|\dot{u}(t)|^{2} d t+|u(t)|^{2}\right] d t \leq \frac{1}{2} \rho^{2}\right\}$, where $\rho$ is the constant defined in (1.3). It is evident that $\Omega_{T}$ is a closed bounded convex subset of $E_{T}$ for all $T \in \mathbb{R}_{+}$.

For any $T \in \mathbb{R}_{+}$, we will prove that 2.8 holds. If $u \in \partial \Omega_{T}$, it follows that $\int_{T}^{T}\left[|\dot{u}(t)|^{2} d t+|u(t)|^{2}\right] d t=\frac{1}{2} \rho^{2}$. Applying Corollary 2.4, it is obvious that $\|u\|_{L_{[-T, T]}^{\infty}} \leq \rho$ for all $u \in \partial \Omega_{T}$. That is $|u(t)| \leq \rho$ for all $t \in[-T, T]$. Combining this inequality, (A1), (A6) and (A7), we get that $\mu \geq \frac{2}{\alpha^{*}}$ and

$$
\begin{aligned}
& I_{T}(u) \\
&= \int_{-T}^{T}\left[\frac{1}{2}|\dot{u}(t)|^{2}+\frac{1}{2}(L(t) u(t), u(t))-W(t, u(t))+(f(t), u(t))\right] d t \\
& \geq \frac{1}{2} \int_{-T}^{T}|\dot{u}(t)|^{2} d t+\frac{1}{2} \int_{-T}^{T} l(t)|u(t)|^{2} d t-\int_{-T}^{T} a(t)|u(t)|^{\mu} d t+\int_{-T}^{T}(f(t), u(t)) d t \\
& \geq \frac{1}{2} \int_{-T}^{T}|\dot{u}(t)|^{2} d t+\frac{l_{*}}{2} \int_{-T}^{T}|u(t)|^{2} d t-\left(\int_{-T}^{T}|a(t)|^{\alpha} d t\right)^{1 / \alpha}\left(\int_{-T}^{T}|u(t)|^{\mu \alpha^{*}} d t\right)^{1 / \alpha^{*}} \\
&-\left(\int_{-T}^{T}|f(t)|^{\beta} d t\right)^{1 / \beta}\left(\int_{-T}^{T}|u(t)|^{\beta^{*}} d t\right)^{1 / \beta^{*}} \\
& \geq \frac{1}{2} \int_{-T}^{T}|\dot{u}(t)|^{2} d t+\frac{l_{*}}{2} \int_{-T}^{T}|u(t)|^{2} d t-\|u\|_{L_{[-T, T]}^{\infty}}^{\mu-\frac{2}{\alpha^{*}}}\left(\int_{\mathbb{R}}|a(t)|^{\alpha} d t\right)^{1 / \alpha} \\
& \times\left(\int_{-T}^{T}|u(t)|^{2} d t\right)^{1 / \alpha^{*}}-\|u\|_{L_{[-T, T]}^{\infty}}^{1-\frac{2}{\beta^{*}}}\left(\int_{\mathbb{R}}|f(t)|^{\beta} d t\right)^{1 / \beta}\left(\int_{-T}^{T}|u(t)|^{2} d t\right)^{1 / \beta^{*}} \\
& \geq \frac{1 \wedge l_{*}}{4} \rho^{2}-\frac{M_{a}}{\alpha^{*} / 2} \rho^{\mu}-\frac{M_{f}}{\sqrt[\beta^{*}]{2}} \rho \\
&> 0=I_{T}(0)
\end{aligned}
$$

for all $u \in \partial \Omega_{T}$. Consequently, using Lemma 2.1, we can have that for all $T \in \mathbb{R}_{+}$, there exists $u_{T} \in \operatorname{int} \Omega_{T}$ such that

$$
I_{T}\left(u_{T}\right)=\inf _{u \in \Omega_{T}} I_{T}(u)
$$

where

$$
\operatorname{int} \Omega_{T}=\left\{u \in E_{T}: \int_{-T}^{T}\left[|\dot{u}(t)|^{2}+|u(t)|^{2}\right] d t<\frac{1}{2} \rho^{2}\right\}
$$

Furthermore, we note that int $\Omega_{T}$ is an open subset of $E_{T}$. This together with [15, Theorem 1.3] implies that

$$
I_{T}^{\prime}\left(u_{T}\right)=0
$$

That is, $u_{T}$ is the solution of the boundary-value problem 2.1 and

$$
\int_{-T}^{T}\left[\left|\dot{u}_{T}(t)\right|^{2}+\left|u_{T}(t)\right|^{2}\right] d t<\frac{1}{2} \rho^{2}
$$

The proof is complete.
Proof of Theorem 1.2. First, we can choose a sequence $T_{m} \rightarrow \infty$ and study the boundary-value problem (2.1) on the bounded closed interval $\left[-T_{m}, T_{m}\right]$ for all $m \in \mathbb{N}$. Using the result of Lemma 2.5 it follows that there exists a sequence of solutions $u_{m}$ such that $\left\|u_{m}\right\|_{E_{T_{m}}}$ is uniformly bounded with respect to $m \in \mathbb{N}$.

According to the inequality

$$
\left|u_{m}\left(t_{1}\right)-u_{m}\left(t_{2}\right)\right| \leq \int_{t_{1}}^{t_{2}}\left|\dot{u}_{m}(t)\right| d t \leq \sqrt{t_{2}-t_{1}}\left(\int_{t_{1}}^{t_{2}}\left|\dot{u}_{m}(t)\right|^{2} d t\right)^{1 / 2}
$$

we can assert that the sequence $\left\{u_{m}\right\}_{m \in \mathbb{N}}$ is equicontinuous and uniformly bounded on every bounded closed interval $\left[-T_{m}, T_{m}\right], m \in \mathbb{N}$. Therefore, we can select a subsequence $\left\{u_{m_{k}}\right\}_{k \in \mathbb{N}}$ such that it converges uniformly on any bounded closed interval to a continuous function $u$. Furthermore, using 2.1), it is clear that the sequence $\left\{\ddot{u}_{m_{k}}\right\}_{k \in \mathbb{N}}$ and so $\left\{\dot{u}_{m_{k}}\right\}_{k \in \mathbb{N}}$ converges uniformly on any bounded closed intervals. Noting that

$$
u_{m_{k}}(t)=\int_{0}^{t}(t-s) \ddot{u}_{m_{k}}(s) d s+t \dot{u}_{m_{k}}(0)+u_{m_{k}}(0)
$$

it is obvious that $u \in C^{2}\left(\mathbb{R}, \mathbb{R}^{n}\right)$ and $\ddot{u}_{m_{k}} \rightarrow \ddot{u}$ uniformly on any bounded closed intervals as $k \rightarrow \infty$. Consequently, we can first study the boundary-value problem (2.1) on bounded closed interval $\left[-T_{m}, T_{m}\right], m \in \mathbb{N}$. Next, using the diagonal process and let $m \rightarrow \infty$, we can easily see that $u$ is a classical solution of 1.1.

Since $\left\|u_{m}\right\|_{E_{T_{m}}}$ is uniformly bounded with respect to $m \in \mathbb{N}$, under the above analysis, it is evident that

$$
\begin{equation*}
\int_{\mathbb{R}}\left[|\dot{u}(t)|^{2}+|u(t)|^{2}\right] d t \leq \frac{1}{2} \rho^{2} \tag{2.9}
\end{equation*}
$$

By Lemma 2.2, we have

$$
|u(t)| \leq \sqrt{2}\left[\int_{t-\frac{1}{2}}^{t+\frac{1}{2}}\left(|\dot{u}(s)|^{2}+|u(s)|^{2}\right) d s\right]^{1 / 2} \quad \text { for all } t \in \mathbb{R}
$$

This together with 2.9 implies that the limit of $u(t)$ is zero as $|t| \rightarrow \infty$, i.e., $u( \pm \infty)=0$. Moreover, since $f \not \equiv 0$, it follows that $u$ is a nontrivial homoclinic orbit of 1.1 .

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