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OSCILLATIONS WITH ONE DEGREE OF FREEDOM AND DISCONTINUOUS ENERGY

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ABSTRACT. In 1995 for a linear oscillator, Myshkis imposed a constant impulse to the velocity, each moment the energy reaches a certain level. The main feature of the resulting system is that it defines a nonlinear discontinuous semigroup. In this note we study the orbital stability of a one-parameter family of periodic solutions and state the existence of a period-doubling bifurcation of such solutions.

1. INTRODUCTION

The solutions of the damped linear oscillator

$$\ddot{x} + 2\alpha \dot{x} + \omega^2 x = 0, \quad \omega > \alpha > 0, \tag{1.1}$$

are supposed to undergo a fixed instantaneous increase of velocity whenever they reach a certain level $E_0 > 0$ of energy. More precisely, the following condition is imposed

$$\frac{1}{2}(\dot{x}^2(t) + \omega^2 x^2(t)) = E_0 \Rightarrow \lim_{s \to t+} \dot{x}(s) = \dot{x}(t) + \sigma, \quad \sigma > 0.$$

This note concerns the resulting discontinuous dynamical system in the plane $x\dot{x}$. Motivated by a pioneering work by Myshkis [10], we obtain the existence of orbitally asymptotically stable *simple* periodic solutions, i.e., solutions which have exactly one impulse in the period. We accomplish a period-doubling bifurcation for such solutions.

The main feature of the problem is to be autonomous; that is, besides the involved equation being autonomous, the moments of impulses are not previously known. Therefore the solution operator of the whole system defines a discontinuous semigroup.

Specific references to the subject are Myshkis [12] and Samoilenko-Perestyuk [14]. For a wider class of related poblems see [2, 3, 4, 5, 6, 7, 9, 11, 12, 13] and references therein.

Section 2 aims to build a context for the problem. In Section 3 we state elementary properties of positive simple periodic solutions. In Section 4 we prove

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the existence of orbitally unstable positive simple periodic solutions with small amplitude and of orbitally asymptotically stable with large amplitudes. Finally, in Section 5 we give a sufficient condition for a period-doubling bifurcation of such solutions.

2. Object of study and basic facts

By the time scaling $\tau = \omega t$ and the change of variables $\xi(\tau) = (\omega/\sqrt{2E_0})x(\tau/\omega)$ Equation (1.1) is written as $\xi'' + 2a\xi' + \xi = 0$, where $' = d/d\tau$, $a = \alpha/\omega \in (0, 1)$ and the locus of level E_0 of energy is taken to the circle $S: \xi^2 + {\xi'}^2 = 1$ in the plane $\xi\xi'$. Retrieving the original notation and formulating the problem in the $x\dot{x}$ plane we obtain

$$\begin{aligned} \dot{x} &= y, \\ \dot{y} &= -x - 2ay \end{aligned} \tag{2.1}$$

with the impulsive condition

$$(x(t), y(t)) \in S \implies (x(t+), y(t+)) = (x(t), y(t) + v).$$
(2.2)

Solutions of (2.1) will be denoted by z and $z(\cdot; t_0, z_0)$, if $z(t_0; t_0, z_0) = z_0$, or briefly $z(\cdot; z_0) = z(\cdot; 0, z_0)$. As the eigenvalues of (2.1) are $-a \pm \delta i$, with $\delta =$ $\sqrt{1-a^2} > 0$, the origin is a stable focus and the energy decreases strictly along nontrivial solutions, since

$$\dot{E}(z(t)) = -2a(y(t))^2, \quad t \in \mathbb{R}.$$
(2.3)

Let $a = \sin b, b \in (0, \pi/2)$, so that $\delta = \cos b$. If $\overline{z}(\cdot) = z(\cdot; (0, -1))$,

$$\bar{z}(t) = -\delta^{-1}e^{-at} (\sin \delta t, \cos(\delta t + b)), \quad t \in \mathbb{R}.$$
(2.4)

As $\bar{z}(\cdot)$ crosses the y axis at $(0, -\sigma) = (0, -e^{-2a\pi/\delta})$, completing a lap around the origin, if $\gamma = \bar{z}(\mathbb{R})$, the family $\{\mu\gamma\}_{\mu\in(\sigma,1]}$ describes all nontrivial orbits of (2.1). That is, the general nontrivial solution is

$$z(\cdot) = \mu \bar{z}(\cdot + \tau), \quad \tau \in \mathbb{R}, \quad \sigma < \mu \le 1$$

Definition 2.1. A solution of (2.1), (2.2) through $b_0 \in \mathbb{R}^2$ at $t = t_0$ is a function $\phi: [t_0,\infty) \to \mathbb{R}^2$ such that $\phi(t_0) = b_0$ and

- (1) $\phi(t-) = \phi(t)$, for all $t \in (t_0, \infty)$;
- (2) $\phi \in C^1$ and satisfies (2.1) in $(t, t + \epsilon_t)$, for all $t \in [t_0, \infty)$ and some $\epsilon_t > 0$.
- (3) ϕ is continuous in t if $\phi(t) \in \mathbb{R}^2 \setminus S$ and $\phi(t+) = \phi(t) + (0, v)$ if $\phi(t) \in S$.

Remark 2.2.

- **mark 2.2.** (1) ϕ is denoted by $\phi(\cdot; t_0, b_0)$ or $\phi(\cdot; b_0)$ if $t_0 = 0$. (2) A function $\psi: (\tau, \infty) \to \mathbb{R}^2$ is solution of (2.1), (2.2) in (τ, ∞) if $\psi|_{[t_0,\infty)} =$ $\phi(\cdot; t_0, \psi(t_0))$, for any $t_0 \in (\tau, \infty)$.
- (3) The solution $\phi(\cdot; t_0, b_0)$ is unique, but in general there is no uniqueness for backward continuations. If $|b_0| \ge 1$, $\phi(\cdot; t_0, b_0)$ has a continuation to $(-\infty,\infty)$. If $|b_0| < 1$, in general a maximal interval of existence to the left is bounded below.

EJDE-2015/275

3. Positive simple solutions

For the dynamics of (2.1), (2.2) the only relevant solutions are $\phi(\cdot; b)$ with $|b| \ge 1$, as they are the only that eventually undergo impulses. There is no loss of generality in taking |b| = 1 and we do so. We denote by \mathfrak{C} the class of such solutions.

Definition 3.1. Let $\phi(\cdot; b)$, |b| = 1, be a periodic solution of (2.1), (2.2) with minimal period $\omega > 0$. The point $\phi(0; b)$ is called *vertex* of $\gamma = \phi(\cdot; b)$. We say that $\phi(0; b)$ is simple if it has a unique impulse in $[0, \omega)$. If $\phi(\cdot; b) = (x(\cdot), y(\cdot))$, it is positive when x(t) > 0 for all t.

We close this section by setting some standing notations. A number β , identified to any $\beta' \equiv \beta \mod 2\pi$, indicates a point $(\cos \beta, \sin \beta) \in S$ or its arc length coordinate in S. The context will clarify the meaning in each case. For $\beta \in S$ we denote $\phi_{\beta} = \phi(\cdot; \beta)$ and, if $|\beta + (0, v)| > 1$, we set $t_1 = t_1(\beta) > 0$ such that $\phi_{\beta}(t_1) \in S$ and $\phi_{\beta}(t) \notin S$ for $0 < t < t_1$.

Definition 3.2. If $D = \{\beta \in S \mid |\beta + (0, v)| > 1\}$, we define the return map $\Phi_v : D \to S$ by $\Phi_v(\beta) = \phi_\beta(t_1(\beta))$ for all $\beta \in D$.

Clearly, if $\beta^* \in D$ is a fixed point of Φ_v , ϕ_{β^*} is a simple periodic solution whose period is $t_1(\beta^*)$ and β^* is the vertex of the simple cycle $\phi_{\beta^*}(\mathbb{R})$. If β^* is an attractor fixed point, ϕ_{β^*} is orbitally asymptotically stable and, if it is repelling, ϕ_{β^*} is orbitally unstable. Here the orbital stability must be in the sense of conditional stability relative to the class \mathfrak{C} , see [8], since if $\phi = \phi(\cdot; b)$, |b| = 1, there are points b' inside S arbitrarily close to b and therefore $\phi(t; b') \to (0, 0)$, as $t \to \infty$.

If $\beta \in S$, let s_{β} be the vertical line $s_{\beta} : x = \cos \beta$ and $t_{\beta} > 0$ such that $z(-t_{\beta}; \beta) = (\cos \beta, y_{\beta}) \in s_{\beta}$ and $z(t; \beta) \notin s_{\beta}$ for $-t_{\beta} < t < 0$. We set $v_{\beta} = y_{\beta} - \sin \beta$, so that ϕ_{β} is a positive simple periodic solution of (2.1), (2.2), $v_{\beta} > 0$. We denote by $\alpha = \alpha_{\beta}$ the polar angle of $z(-t_{\beta}; \beta)$, according to Figure 1.

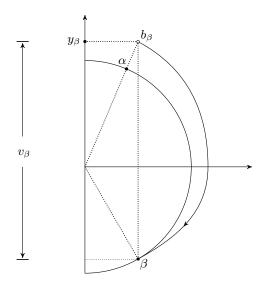


FIGURE 1. Positive simple cycle.

Remark 3.3. For any $v \in (0, e^{a\pi/\delta} + 1)$, there exists exactly one positive simple cycle of (2.1), (2.2) since $\beta \in (-\pi/2, 0) \mapsto v_{\beta} \in (0, e^{a\pi/\delta} + 1)$ is a continuous bijection.

4. Orbital stability

Now we show that, for some $\zeta > 0$, the solution ϕ_{β} of (2.1), (2.2) is orbitally unstable if $\beta \in (-\zeta, 0)$ and orbitally asymptotically stable if $\beta \in (-\pi/2, -\pi/2 + \zeta)$.

Lemma 4.1. $v_{\beta} = -2\beta + o(\beta)$ as $\beta \to 0-$.

Proof. Let $\beta \in (-\pi/2, 0)$. System (2.1) in polar coordinates,

$$\dot{r} = -(2a\sin^2\theta)r,$$

$$\dot{\theta} = -(1 + a\sin 2\theta),$$

yields

$$r' = \left(2a\sin^2\theta/(1+a\sin 2\theta)\right)r, \quad ('=d/d\theta). \tag{4.1}$$

and a parametrization of ϕ_{β} is

$$r_{\beta}(\theta) = e^{A_{\beta}(\theta)} = \exp\left[2a \int_{\beta}^{\theta} \frac{\sin^2 s}{1 + a \sin 2s} \, ds\right], \quad \theta \in \mathbb{R}.$$
 (4.2)

As the integrand in (4.2) will be a regular participant, we introduce the notation

$$q_a(s) = \frac{\sin^2 s}{1 + a \sin 2s}.$$

For any small $\epsilon > 0$ such that $\alpha = -(1 + \epsilon)\beta < \pi/2$, the inequality

$$A_{\beta}(\theta) \leq -\frac{2a(2+\epsilon)(1+\epsilon)^2}{1-a}\beta^3, \quad \theta \in [\beta, -(1+\epsilon)\beta],$$

yields

$$r_{\beta}(-(1+\epsilon)\beta) = e^{A_{\beta}(-(1+\epsilon)\beta)} = 1 + O(\beta^3)$$
 as $\beta \to 0-$

If $r^{\epsilon} = |p_{\epsilon}|$, p_{ϵ} being the intersection of the half lines $s_1 : \theta = -(1 + \epsilon)\beta$ and $s_2 : r(\theta) \cos \theta = \cos \beta$, $\theta \in (0, \pi/2)$, the similarity of the triangles mnO and $p_{\epsilon}qO$ seen in Figure 2 yields

$$r^{\epsilon} = \frac{\cos\beta}{\cos(1+\epsilon)\beta} = 1 + \frac{(2+\epsilon)\epsilon}{2!}\beta^2 + O(\beta^4) \text{ as } \beta \to 0-\epsilon$$

For $|\beta|$ small enough, the estimates above imply $r_{\beta}(-(1+\epsilon)\beta) < r^{\epsilon}$, so that $y_{\beta}/\cos\beta < -\tan(1+\epsilon)\beta$ and

$$1 < -\frac{y_{\beta}}{\sin\beta} < \frac{\tan(1+\epsilon)\beta}{\tan\beta}.$$

Taking limits as $\beta \to 0^-$,

$$1 \leq \liminf_{\beta \to 0-} -\frac{y_{\beta}}{\sin \beta} \leq \limsup_{\beta \to 0-} -\frac{y_{\beta}}{\sin \beta} \leq 1 + \epsilon,$$

so that $\lim_{\beta\to 0^-} y_\beta / \sin\beta = -1$. Therefore $y_\beta = -\beta + o(\beta)$ and hence $v_\beta = -2\beta + o(\beta)$, as $\beta \to 0^-$.

The theorem below in what concerns orbital instability is a result by Myshkis [10]. We give an alternative approach to extend it.

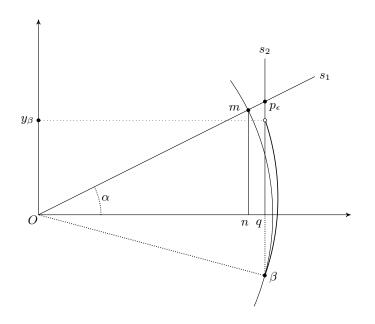


FIGURE 2. $v_{\beta} = -2\beta + o(\beta)$ as $\beta \to 0-$.

Theorem 4.2. There is a number $\zeta > 0$ such that if $\beta \in (-\zeta, 0)$, the simple periodic solution ϕ_{β} of (2.1), (2.2) is orbitally unstable and if $\beta \in (-\pi/2, -\pi/2 + \zeta)$, ϕ_{β} is orbitally asymptotically stable.

Proof. Let $\beta \in (-\pi/2, 0)$ and $\epsilon_1 \neq 0$ so that $\beta + \epsilon_1 = \beta_1 \in (-\pi/2, 0)$. We take $|\epsilon_1|$ smaller if necessary to assure the existence of $\Phi_{v_\beta}(\beta_1) = \beta + \epsilon_2 \in (-\pi/2, 0)$, as it is seen in Figure 3 for the case $\epsilon_1 < 0$.

Firstly we notice that ϵ_1 and σ are related by the equation

$$\frac{v_{\beta} + \sin(\beta + \epsilon_1)}{\cos(\beta + \epsilon_1)} = \tan(\alpha + \sigma)$$

therefore, the implicit function theorem about $(\epsilon_1, \sigma) = (0, 0)$ yields

$$\sigma = \frac{v_\beta \sin \beta + 1}{|b_\beta|^2} \epsilon_1 + o(\epsilon_1), \qquad (4.3)$$

as $\epsilon_1 \to 0$. By (4.2), if $b_1 = \beta_1 + (0, v_\beta)$, ϵ_2 must satisfy

$$|b_1| \exp\left[2a \int_{\alpha+\sigma}^{\beta+\epsilon_2} q_a(s) \, ds\right] = 1.$$

As $|b_1| = \sqrt{(v_\beta + \sin(\beta + \epsilon_1))^2 + \cos^2(\beta + \epsilon_1)}$, we have

$$\left(v_{\beta}^{2}+2v_{\beta}\sin(\beta+\epsilon_{1})+1\right)\exp\left[4a\int_{\alpha+\sigma(\epsilon_{1})}^{\beta+\epsilon_{2}}q_{a}(s)\,ds\right]=1$$

and the implicit function theorem leads to

$$\epsilon_2 = \frac{1}{q_a(\beta)|b_\beta|^2} \Big[q_a(\alpha)(1+v_\beta\sin\beta) - \frac{v_\beta\cos\beta}{2a} \Big] \epsilon_1 + o(\epsilon_1), \tag{4.4}$$

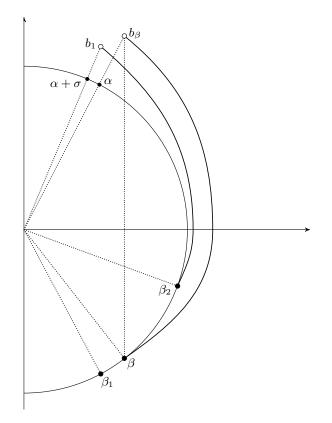


FIGURE 3. $\beta + \epsilon_2 = \Phi_{v_\beta}(\beta + \epsilon_1).$

as $\epsilon_1 \to 0$. Let

$$F(\beta) = \frac{1}{q_a(\beta)|b_\beta|^2} \Big[q_a(\alpha)(1+v_\beta\sin\beta) - \frac{v_\beta\cos\beta}{2a} \Big], \tag{4.5}$$

so that $F(\beta) < 0$ and (4.4) is $\epsilon_2 = F(\beta)\epsilon_1 + o(\epsilon_1)$, as $\epsilon_1 \to 0$, for short. Since $\lim_{\beta \to -\pi/2} |b_\beta| = \lim_{\beta \to -\pi/2} -(1 + v_\beta \sin \beta) = e^{a\pi/\delta}$,

$$|F(\beta)| \to e^{-a\pi/\delta} < 1, \quad \text{as } \beta \to -\pi/2.$$
 (4.6)

On the other hand, we have $|\sin\beta| < |\sin\alpha| < y_{\beta}$, see Figure 2, so that by Lemma 4.1, $q_a(\alpha)/q_a(\beta) \to 1$ and $v_{\beta} = O(\beta)$, as $\beta \to 0$, therefore recalling that $q_a(\beta) = O(\beta^2)$ as $\beta \to 0$,

$$|F(\beta)| \to \infty \quad \text{as } \beta \to 0.$$
 (4.7)

For some $\zeta > 0$, Eqs. (4.6) and (4.7) imply that $|F(\beta)| < 1$ if $\beta \in (-\pi/2, -\pi/2 + \zeta)$ and $|F(\beta)| > 1$ if $\beta \in (-\zeta, 0)$. In other words, any $\beta \in (-\pi/2, -\pi/2 + \zeta)$ is an attractor fixed point of the return map $\Phi_{v_{\beta}}$ and any $\beta \in (-\zeta, 0)$ is a repelling fixed point of $\Phi_{v_{\beta}}$.

 $\mathbf{6}$

EJDE-2015/275

5. Period doubling bifurcation

Solutions ϕ_{β} of (2.1), (2.2) change from stable to unstable when β varies over $(-\pi/2, 0)$ from left to the right. Therefore it is natural to expect a bifurcation in between. In this section we apply the theorem below [1, Theorem 12.7] to confirm that this indeed occurs at least for small dampings.

Theorem 5.1 (Period doubling bifurcation). Let $\{f_{\lambda}\}$ a one-parameter family of real functions and suppose that

(1) $f_{\lambda}(0) = 0$ for all λ in an interval about λ_0 ; (2) $f'_{\lambda_0}(0) = -1$; (3) $\frac{\partial (f_{\lambda}^2)'}{\partial \lambda}\Big|_{\lambda=\lambda_0}(0) \neq 0.$

Then there is an interval I about 0 and a function $p: I \to \mathbb{R}$ such that

$$f_{p(x)}(x) \neq x$$
 and $f_{p(x)}^2(x) = x$.

By the proof of Theorem 4.2 there is a $\beta_a^* \in (-\pi/2, 0), 0 < a < 1$, such that $F(\beta_a^*) = -1$. Now we show that such a β_a^* is a period doubling bifurcation point of the family of periodic solutions $\phi_{\beta}, -\pi/2 < \beta < 0$, at least if a is small enough.

Theorem 5.2. If $a \in (0,1)$ is sufficiently small, then any $\beta_a^* \in (-\pi/2,0)$ such that $F(\beta_a^*) = -1$ is a period doubling bifurcation point for the family $\phi_{\beta}, -\pi/2 < \beta < 0$.

Proof. Let us follow (4.4) to define the family of functions f_{β} , $-\pi/2 < \beta < 0$, in such a way that

$$\epsilon_2 = f_\beta(\epsilon_1) = F(\beta)\epsilon_1 + o(\epsilon_1),$$

as $\epsilon_1 \to 0$. Condition (1) of Theorem 5.1, $f_{\beta}(0) = 0$ for all $\beta \in (-\pi/2, 0)$, is immediate and, if ' denotes for a moment $d/d\epsilon_1$, Condition (2), $f'_{\beta^*_a}(0) = F(\beta^*_a) = -1$, follows from the definition of β^*_a .

Now it remains to show that

$$\Big[\frac{\partial (f_{\beta}^{2})'}{\partial \beta}\Big]_{\beta=\beta_{a}^{*}}(0) = \frac{\partial}{\partial \beta}\Big[\big(F(\beta)\big)^{2}\Big]_{\beta=\beta_{a}^{*}} \neq 0$$

for a small enough. Retaking the notation $' = d/d\beta$ this is equivalent to $F'(\beta_a^*) \neq 0$, since $F(\beta_a^*) \neq 0$. We note that if $\beta = \beta_a^*$,

$$q_a(\beta)|b_\beta|^2 = \frac{v_\beta \cos\beta}{2a} + q_a(\alpha)(-v_\beta \sin\beta - 1);$$

therefore,

$$F'(\beta_a^*) = \left[\frac{1}{q_a(\beta)|b_\beta|^2} \left(\frac{v_\beta \cos\beta}{2a} + q_a(\alpha)(-v_\beta \sin\beta - 1)\right)\right]'_{\beta=\beta_a^*}$$
$$\frac{1}{q_a(\beta_a^*)|b_{\beta_a^*}|^2} \left[q'_a(\beta)|b_\beta|^2 + 2q_a(\beta)|b_\beta||b_\beta|' + \frac{v'_\beta \cos\beta - v_\beta \sin\beta}{2a} + q'_a(\alpha)\alpha'(-v_\beta \sin\beta - 1) + q_a(\alpha)(-v'_\beta \sin\beta - v_\beta \cos\beta)\right]_{\beta=\beta_a^*}.$$
(5.1)

It suffices to show that the term in the brackets in the right side of (5.1) is nonzero.

Equation (4.2) implies $|b_{\beta}| = \exp\left[2a\int_{\beta}^{\alpha}q_a(s)ds\right] \to 1$ as $a \to 0$, uniformly in $\beta \in (-\pi/2, 0)$. This yields $y_{\beta} \to -\sin\beta$ and $\alpha \to -\beta$, as $a \to 0$, uniformly in

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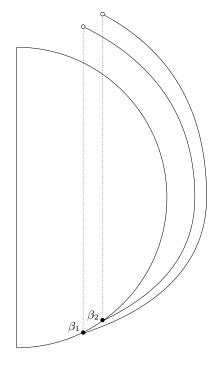


FIGURE 4. $\beta_1 = \Phi_v^2(\beta_1) \neq \Phi_v(\beta_1) = \beta_2.$

$$\beta \in (-\pi/2, 0)$$
. Moreover, the implicit function theorem applied to the equation

$$\exp\left[2a\int_{\beta}^{\alpha}q_a(s)ds\right]\cos\alpha = \cos\beta,$$

leads to

$$\alpha'(\beta) = \frac{\sin\beta(1 + a\sin 2\alpha)}{y_{\beta}(1 + a\sin 2\beta)}.$$

Thus $\alpha' \to -1$ as $a \to 0$, uniformly in $\beta \in (-\pi/2, 0)$. Finally, we note that the following limits, taken as $a \to 0$, are uniform in $\beta \in (-\pi/2, 0)$:

$$\lim q_a(\beta) = \sin^2 \beta,$$

$$\lim q'_a(\beta) = \sin 2\beta,$$

$$\lim v_\beta = -2\sin \beta,$$

$$\lim v'_\beta = -2\cos \beta,$$

$$\lim |b_\beta|' = 0.$$

Therefore, the limit, as $a \to 0$, of the term in the brackets in the right side of (5.1) is

$$\sin 2\beta + \lim_{a \to 0} \frac{v_{\beta}' \cos \beta - v_{\beta} \sin \beta}{2a} - \frac{\sin 4\beta}{2}.$$
 (5.2)

Since $\lim_{a\to 0} (v'_{\beta} \cos \beta - v_{\beta} \sin \beta) = -2 \cos 2\beta$, in order to assure the expression (5.2) is nonzero, β^*_a must be bounded away from $-\pi/4$ for *a* small enough. According to

8

EJDE-2015/275

(4.5) $\lim_{a\to 0} -F(-\pi/4) = \infty$; therefore, for some $\eta > 0$, $\beta_a^* \notin (-\pi/4 - \eta, -\pi/4 + \eta)$. That is, $F'(\beta_a^*) \neq 0$ for $a \in (0, 1)$ sufficiently small.

Figure 4 shows a typical positive periodic orbit emanating from β_a^* .

Final remarks. Smallness of a is a request of our proof of Theorem 5.2, possibly this hypothesis can be weakened or even discarded.

The larger is the coefficient $a \in (0,1)$, the larger is the region of stability in $(-\pi/2,0)$. In fact, by (4.2), $r_{-\pi/2}(\pi) = e^{a\pi/\delta} \to \infty$ as $a \to 1$. Therefore, for any fixed $\beta \in (-\pi/2,0)$, one has $|b_{\beta}| \to \infty$ as $a \to 1$, so that the number ϵ_2 in (4.4) satisfies $\epsilon_2 \to 0$, as $a \to 1$.

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