

## GLOBAL SOLVABILITY FOR INVOLUTIVE SYSTEMS ON THE TORUS

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ABSTRACT. In this article, we consider a class of involutive systems of  $n$  smooth vector fields on the torus of dimension  $n + 1$ . We prove that the global solvability of this class is related to an algebraic condition involving Liouville forms and the connectedness of all sublevel and superlevel sets of the primitive of a certain 1-form associated with the system.

### 1. INTRODUCTION

In this article we study the global solvability of a system of vector fields on  $\mathbb{T}^{n+1} \simeq (\mathbb{R}/2\pi\mathbb{Z})^{n+1}$  given by

$$L_j = \frac{\partial}{\partial t_j} + (a_j + ib_j)(t) \frac{\partial}{\partial x}, \quad j = 1, \dots, n, \quad (1.1)$$

where  $(t_1, \dots, t_n, x) = (t, x)$  denotes the coordinates on  $\mathbb{T}^{n+1}$ ,  $a_j, b_j \in C^\infty(\mathbb{T}^n; \mathbb{R})$  and for each  $j$  we consider  $a_j$  or  $b_j$  identically zero.

We assume that the system (1.1) is involutive (see [1, 12]) or equivalently that the 1-form  $c(t) = \sum_{j=1}^n (a_j + ib_j)(t) dt_j \in \wedge^1 C^\infty(\mathbb{T}_t^n)$  is closed.

When the 1-form  $c(t)$  is exact the problem was treated by Cardoso and Hounie in [9]. Here, we will consider that only the imaginary part of  $c(t)$  is exact, that is, the real 1-form  $b(t) = \sum_{j=1}^n b_j(t) dt_j$  is exact.

The system (1.1) gives rise to a complex of differential operators  $\mathbb{L}$  which at the first level acts in the following way

$$\mathbb{L}u = d_t u + c(t) \wedge \frac{\partial}{\partial x} u, \quad u \in C^\infty(\mathbb{T}^{n+1}) \quad \text{or} \quad \mathcal{D}'(\mathbb{T}^{n+1}), \quad (1.2)$$

where  $d_t$  denotes the exterior differential on the torus  $\mathbb{T}_t^n$ . Our aim is to carry out a study of the global solvability at the first level of this complex. In other words we study the global solvability of the equation  $\mathbb{L}u = f$  where  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$  and  $f \in C^\infty(\mathbb{T}_t^n \times \mathbb{T}_x^1; \wedge^{1,0})$ .

Note that if the equation  $\mathbb{L}u = f$  has a solution  $u$  then  $f$  must be of the form

$$f = \sum_{j=1}^n f_j(t, x) dt_j.$$

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The local solvability of this complex of operators was studied by Treves in his seminal work [11].

When each function  $b_j \equiv 0$ , the global solvability was treated by Bergamasco and Petronilho in [8]. In this case the system is globally solvable if and only if the real 1-form  $a(t) = \sum_{j=1}^n a_j(t)dt_j$  is either non-Liouville or rational (see definition in [2]).

When  $c(t)$  is exact the problem was solved by Cardoso and Hounie in [9]. In this case the 1-form  $c(t)$  has a global primitive  $C$  defined on  $\mathbb{T}^n$  and global solvability is equivalent to the connectedness of all sublevels and superlevels of the real function  $Im(C)$ .

We are interested in global solvability when at least one of the functions  $b_j \not\equiv 0$  and  $c(t)$  is not exact. Moreover, we suppose that  $Im(c)$  is exact and for each  $j$ ,  $a_j \equiv 0$  or  $b_j \equiv 0$ .

We prove that system (1.1) is globally solvable if and only if the real 1-form  $a(t)$  is either non-Liouville or rational and any primitive of the 1-form  $b(t)$  has only connected sublevels and superlevels on  $\mathbb{T}^n$  (see Theorem 2.2).

The articles [3, 4, 5, 6, 7, 10] deal with similar questions.

## 2. PRELIMINARIES AND STATEMENT OF THE MAIN RESULT

There are natural compatibility conditions on the 1-form  $f$  for the existence of a solution  $u$  to the equation  $\mathbb{L}u = f$ . We now move on to describing them.

If  $f \in C^\infty(\mathbb{T}_x^n \times \mathbb{T}_t^1; \wedge^{1,0})$  we consider the  $x$ -Fourier series

$$f(t, x) = \sum_{\xi \in \mathbb{Z}} \hat{f}(t, \xi) e^{i\xi x},$$

where  $\hat{f}(t, \xi) = \sum_{j=1}^n \hat{f}_j(t, \xi) dt_j$  and  $\hat{f}_j(t, \xi)$  denotes the Fourier transform with respect to  $x$ .

Since  $b$  is exact there exists a function  $B \in C^\infty(\mathbb{T}_t^n; \mathbb{R})$  such that  $d_t B = b$ . Moreover, we may write  $a = a_0 + d_t A$  where  $A \in C^\infty(\mathbb{T}_t^n; \mathbb{R})$  and  $a_0 \in \wedge^1 \mathbb{R}^n \simeq \mathbb{R}^n$ . Thus, we may write  $c(t) = a_0 + d_t C$  where  $C(t) = A(t) + iB(t)$ .

We will identify the 1-form  $a_0 \in \wedge^1 \mathbb{R}^n$  with the vector  $a_0 := (a_{10}, \dots, a_{n0})$  in  $\mathbb{R}^n$  consisting of the periods of the 1-form  $a$  given by

$$a_{j0} = \frac{1}{2\pi} \int_0^{2\pi} a_j(0, \dots, \tau_j, \dots, 0) d\tau_j.$$

Thus, if  $f \in C^\infty(\mathbb{T}_t^n \times \mathbb{T}_x^1; \wedge^{1,0})$  and if there exists  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$  such that  $\mathbb{L}u = f$  then, since  $\mathbb{L}$  defines a differential complex,  $\mathbb{L}f = 0$  or equivalently  $L_j f_k = L_k f_j$ ,  $j, k = 1, \dots, n$ ; also

$$\hat{f}(t, \xi) e^{i\xi(a_0 \cdot t + C(t))} \text{ is exact when } \xi a_0 \in \mathbb{Z}. \quad (2.1)$$

We define now the set

$$\mathbb{E} = \{f \in C^\infty(\mathbb{T}_t^n \times \mathbb{T}_x^1; \wedge^{1,0}); \mathbb{L}f = 0 \text{ and (2.1) holds}\}.$$

**Definition 2.1.** The operator  $\mathbb{L}$  is said to be globally solvable on  $\mathbb{T}^{n+1}$  if for each  $f \in \mathbb{E}$  there exists  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$  satisfying  $\mathbb{L}u = f$ .

Given  $\alpha \notin \mathbb{Q}^n$  we say that  $\alpha$  is *Liouville* when there exists a constant  $C > 0$  such that for each  $N \in \mathbb{N}$  the inequality

$$\max_{j=1,\dots,n} \left| \alpha_j - \frac{p_j}{q} \right| \leq \frac{C}{q^N},$$

has infinitely many solutions  $(p_1, \dots, p_n, q) \in \mathbb{Z}^n \times \mathbb{N}$ .

Let us consider the following two sets

$$J = \{j \in \{1, \dots, n\}; b_j \equiv 0\}, \quad K = \{k \in \{1, \dots, n\}; a_k \equiv 0\};$$

and we will write  $J = \{j_1, \dots, j_m\}$  and  $K = \{k_1, \dots, k_p\}$ . Under the above notation, the main result of this work is the following theorem.

**Theorem 2.2.** *Let  $B$  be a global primitive of the 1-form  $b$ . If  $J \cup K = \{1, \dots, n\}$  then the operator  $\mathbb{L}$  given in (1.2) is globally solvable if and only if one of the following two conditions holds:*

- (I)  $J \neq \emptyset$  and  $(a_{j_1 0}, \dots, a_{j_m 0}) \notin \mathbb{Q}^m$  is non-Liouville.
- (II) The sublevels  $\Omega_s = \{t \in \mathbb{T}^n, B(t) < s\}$  and superlevels  $\Omega^s = \{t \in \mathbb{T}^n, B(t) > s\}$  are connected for every  $s \in \mathbb{R}$  and  $(a_{j_1 0}, \dots, a_{j_m 0}) \in \mathbb{Q}^m$  if  $J \neq \emptyset$ .

Note that if  $J = \emptyset$  then  $K = \{1, \dots, n\}$  (since  $J \cup K = \{1, \dots, n\}$  by hypothesis). In this case each  $a_k \equiv 0$  and Theorem 2.2 says that  $\mathbb{L}$  is globally solvable if and only if all the sublevels and superlevels of  $B$  are connected in  $\mathbb{T}^n$ , which is according to [9].

When  $J = \{1, \dots, n\}$  we have that  $b = 0$ , hence any primitive of  $b$  has only connected sublevels and superlevels on  $\mathbb{T}^n$ . In this case Theorem 2.2 says that  $\mathbb{L}$  is globally solvable if and only if either  $a_0 \notin \mathbb{Q}^n$  is non-Liouville or  $a_0 \in \mathbb{Q}^n$ , which was proved in [8]. Thus, in order to prove Theorem 2.2 it suffices to consider the following situation  $\emptyset \neq J \neq \{1, \dots, n\}$ .

**Remark 2.3.** As in [8], the differential operator  $\mathbb{L}$  is globally solvable if and only if the differential operator

$$d_t + (a_0 + ib(t)) \wedge \frac{\partial}{\partial x} \tag{2.2}$$

is globally solvable.

Indeed, consider the automorphism

$$S : \mathcal{D}'(\mathbb{T}^{n+1}) \longrightarrow \mathcal{D}'(\mathbb{T}^{n+1})$$

$$\sum_{\xi \in \mathbb{Z}} \hat{u}(t, \xi) e^{i\xi x} \longmapsto \sum_{\xi \in \mathbb{Z}} \hat{u}(t, \xi) e^{i\xi A(t)} e^{i\xi x},$$

where  $A$  is the previous smooth real valued function satisfying  $d_t A = a(t) - a_0$ . Observe that following relation holds:

$$S\mathbb{L}S^{-1} = d_t + (a_0 + ib(t)) \wedge \frac{\partial}{\partial x},$$

which ensures the above statement.

Therefore, it is sufficient to prove Theorem 2.2 for the operator (2.2). For the rest of this article, we will denote by  $\mathbb{L}$  the operator (2.2); that is,

$$\mathbb{L} = d_t + (a_0 + ib(t)) \wedge \frac{\partial}{\partial x} \tag{2.3}$$

and by  $\mathbb{E}$  the corresponding space of compatibility conditions. The new operator  $\mathbb{L}$  is associated with the vector fields

$$L_j = \frac{\partial}{\partial t_j} + (a_{j0} + ib_j(t)) \frac{\partial}{\partial x}, \quad j = 1, \dots, n. \quad (2.4)$$

### 3. SUFFICIENCY PART OF THEOREM 2.2

First assume that  $(a_{j_1 0}, \dots, a_{j_m 0}) \notin \mathbb{Q}^m$  is non-Liouville where

$$J = \{j_1, \dots, j_m\} := \{j \in \{1, \dots, n\}, b_j \equiv 0\}.$$

Then, there exist a constant  $C > 0$  and an integer  $N > 1$  such that

$$\max_{j \in J} |\xi a_{j0} - \kappa_j| \geq \frac{C}{|\xi|^{N-1}}, \quad \forall (\kappa, \xi) \in \mathbb{Z}^m \times \mathbb{N}. \quad (3.1)$$

Consider the set  $I$  where  $I \cup J = \{1, \dots, n\}$  and  $I \cap J = \emptyset$ . Remember that  $\emptyset \neq J \neq \{1, \dots, n\}$  then  $I \neq \emptyset$  and  $b_\ell \neq 0$  if  $\ell \in I$ .

We denote by  $t_J$  the variables  $t_{j_1}, \dots, t_{j_m}$  and by  $t_I$  the other variables on  $\mathbb{T}_t^n$ . Let  $f(t, x) = \sum_{j=1}^n f_j(t, x) dt_j \in \mathbb{E}$ . Consider the  $(t_J, x)$ -Fourier series as follows

$$u(t, x) = \sum_{(\kappa, \xi) \in \mathbb{Z}^m \times \mathbb{Z}} \hat{u}(t_I, \kappa, \xi) e^{i(\kappa \cdot t_J + \xi x)} \quad (3.2)$$

and for each  $j = 1, \dots, n$ ,

$$f_j(t, x) = \sum_{(\kappa, \xi) \in \mathbb{Z}^m \times \mathbb{Z}} \hat{f}_j(t_I, \kappa, \xi) e^{i(\kappa \cdot t_J + \xi x)}, \quad (3.3)$$

where  $\kappa = (\kappa_{j_1}, \dots, \kappa_{j_m}) \in \mathbb{Z}^m$  and  $\hat{u}(t_I, \kappa, \xi)$  and  $\hat{f}_j(t_I, \kappa, \xi)$  denote the Fourier transform with respect to variables  $(t_{j_1}, \dots, t_{j_m}, x)$ .

Substituting the formal series (3.2) and (3.3) in the equations  $L_j u = f_j$ ,  $j \in J$ , we have for each  $(\kappa, \xi) \neq (0, 0)$

$$i(\kappa_j + \xi a_{j0}) \hat{u}(t_I, \kappa, \xi) = \hat{f}_j(t_I, \kappa, \xi), \quad j \in J.$$

Also, from the compatibility conditions  $L_j f_\ell = L_\ell f_j$ , for all  $j, \ell \in J$ , we obtain the equations

$$(\kappa_j + \xi a_{j0}) \hat{f}_\ell(t_I, \kappa, \xi) = (\kappa_\ell + \xi a_{\ell 0}) \hat{f}_j(t_I, \kappa, \xi), \quad j, \ell \in J.$$

By the preceding equations we have

$$\hat{u}(t_I, \kappa, \xi) = \frac{1}{i(\kappa_M + \xi a_{M0})} \hat{f}_M(t_I, \kappa, \xi), \quad (\kappa, \xi) \neq (0, 0), \quad (3.4)$$

where  $M \in J$ ,  $M = M(\xi)$  is such that

$$|\kappa_M + \xi a_{M0}| = \max_{j \in J} |\kappa_j + \xi a_{j0}| \neq 0.$$

If  $(\kappa, \xi) = (0, 0)$ , since  $\hat{f}(t_I, 0, 0)$  is exact, there exists  $v \in C^\infty(\mathbb{T}_{t_I}^{n-m})$  such that  $dv = \hat{f}(\cdot, 0, 0)$ . Thus, we choose  $\hat{u}(t_I, 0, 0) = v(t_I)$ .

Given  $\alpha \in \mathbb{Z}_+^{n-m}$  we obtain from (3.1) and (3.4) the inequality

$$|\partial^\alpha \hat{u}(t_I, \kappa, \xi)| \leq \frac{1}{C} |\xi|^{N-1} |\partial^\alpha \hat{f}_M(t_I, \kappa, \xi)|.$$

Since each  $f_j$  is a smooth function we conclude that

$$u(t, x) = \sum_{(\kappa, \xi) \in \mathbb{Z}^m \times \mathbb{Z}} \hat{u}(t_I, \kappa, \xi) e^{i(\kappa \cdot t_J + \xi x)} \in C^\infty(\mathbb{T}^{n+1}).$$

By construction  $u$  is a solution of

$$L_j u = f_j, \quad j \in J.$$

Now, we will prove that  $u$  is also a solution to the equations

$$L_\ell u = f_\ell, \quad \ell \in I.$$

Let  $\ell \in I$ . Given  $(\kappa, \xi) \neq (0, 0)$  by the compatibility condition  $L_M f_\ell = L_\ell f_M$  we have

$$i(\kappa_M + \xi a_{M0}) \hat{f}_\ell(t_I, \kappa, \xi) = \frac{\partial}{\partial t_\ell} \hat{f}_M(t_I, \kappa, \xi) - \xi b_\ell(t) \hat{f}_M(t_I, \kappa, \xi). \tag{3.5}$$

Therefore, (3.4) and (3.5) imply

$$\begin{aligned} & \frac{\partial}{\partial t_\ell} \hat{u}(t_I, \kappa, \xi) - \xi b_\ell(t) \hat{u}(t_I, \kappa, \xi) \\ &= \frac{1}{i(\kappa_M + \xi a_{M0})} \frac{\partial}{\partial t_\ell} \hat{f}_M(t_I, \kappa, \xi) - \xi b_\ell(t) \frac{1}{i(\kappa_M + \xi a_{M0})} \hat{f}_M(t_I, \kappa, \xi) \\ &= \frac{1}{i(\kappa_M + \xi a_{M0})} \left( \frac{\partial}{\partial t_\ell} \hat{f}_M(t_I, \kappa, \xi) - \xi b_\ell(t) \hat{f}_M(t_I, \kappa, \xi) \right) \\ &= \hat{f}_\ell(t_I, \kappa, \xi). \end{aligned}$$

If  $(\kappa, \xi) = (0, 0)$  then  $\frac{\partial}{\partial t_\ell} \hat{u}(t_I, 0, 0) = \hat{f}_\ell(t_I, 0, 0)$ .

We have thus proved that condition (I) implies global solvability.

Suppose now that the condition (II) holds. Let  $q_J$  be the smallest positive integer such that  $q_J(a_{j_1 0}, \dots, a_{j_m 0}) \in \mathbb{Z}^m$ .

We denote by  $\mathcal{A} := q_J \mathbb{Z}$  and  $\mathcal{B} := \mathbb{Z} \setminus \mathcal{A}$  and define

$$\mathcal{D}'_{\mathcal{A}}(\mathbb{T}^{n+1}) := \left\{ u \in \mathcal{D}'(\mathbb{T}^{n+1}); \quad u(t, x) = \sum_{\xi \in \mathcal{A}} \hat{u}(t, \xi) e^{i\xi x} \right\}.$$

Let  $\mathbb{L}_{\mathcal{A}}$  be the operator  $\mathbb{L}$  acting on  $\mathcal{D}'_{\mathcal{A}}(\mathbb{T}^{n+1})$ . Similarly, we define  $\mathcal{D}'_{\mathcal{B}}(\mathbb{T}^{n+1})$  and  $\mathbb{L}_{\mathcal{B}}$ .

Then  $\mathbb{L}$  is globally solvable if and only if  $\mathbb{L}_{\mathcal{A}}$  and  $\mathbb{L}_{\mathcal{B}}$  are globally solvable (see [3]).

**Lemma 3.1.** *The operator  $\mathbb{L}_{\mathcal{A}}$  is globally solvable.*

*Proof.* Since  $q_J a_0 \in \mathbb{Z}^n$ , we define

$$\begin{aligned} T : \mathcal{D}'_{\mathcal{A}}(\mathbb{T}^{n+1}) &\longrightarrow \mathcal{D}'_{\mathcal{A}}(\mathbb{T}^{n+1}) \\ \sum_{\xi \in \mathcal{A}} \hat{u}(t, \xi) e^{i\xi x} &\longmapsto \sum_{\xi \in \mathcal{A}} \hat{u}(t, \xi) e^{-i\xi a_0 t} e^{i\xi x}. \end{aligned}$$

Note that  $T$  is an automorphism of  $\mathcal{D}'_{\mathcal{A}}(\mathbb{T}^{n+1})$  (and of  $C^\infty_{\mathcal{A}}(\mathbb{T}^{n+1})$ ). Furthermore the following relation holds:

$$T^{-1} \mathbb{L}_{\mathcal{A}} T = \mathbb{L}_{0, \mathcal{A}}, \tag{3.6}$$

where  $\mathbb{L}_0 := d_t + ib(t) \wedge \frac{\partial}{\partial x}$ .

Let  $B$  be a global primitive of  $b$  on  $\mathbb{T}^n$ . Since all the sublevels and superlevels of  $B$  are connected in  $\mathbb{T}^n$ , by work [8] we have  $\mathbb{L}_0$  globally solvable, hence  $\mathbb{L}_{0, \mathcal{A}}$  is

globally solvable. Since  $T$  is an automorphism, from equality (3.6) we obtain that  $\mathbb{L}_{\mathcal{A}}$  is globally solvable.  $\square$

If  $q_J = 1$  then  $\mathcal{A} = \mathbb{Z}$  and the proof is complete. Otherwise we have:

**Lemma 3.2.** *The operator  $\mathbb{L}_{\mathcal{B}}$  is globally solvable.*

*Proof.* Let  $(\kappa, \xi) \in \mathbb{Z}^m \times \mathcal{B}$ . Since  $q_J$  is defined as the smallest natural such that  $q_J(a_{j_1 0}, \dots, a_{j_m 0}) \in \mathbb{Z}^m$ , there exists  $\ell \in J$  such that

$$\left| a_{\ell 0} - \frac{\kappa_{\ell}}{\xi} \right| \geq \frac{C}{|\xi|},$$

where  $C = 1/q_J$ . Therefore

$$\max_{j \in J} \left| a_{j 0} - \frac{\kappa_j}{\xi} \right| \geq \left| a_{\ell 0} - \frac{\kappa_{\ell}}{\xi} \right| \geq \frac{C}{|\xi|}, \quad (\kappa, \xi) \in \mathbb{Z}^m \times \mathcal{B}.$$

Note that if the denominators  $\xi \in \mathcal{B}$  then  $(a_{j_1 0}, \dots, a_{j_m 0})$  behaves as non-Liouville. Thus, the rest of the proof is analogous to the case where  $(a_{j_1 0}, \dots, a_{j_m 0})$  is non-Liouville.  $\square$

#### 4. NECESSITY PART OF THEOREM 2.2

Assume first that  $(a_{j_1 0}, \dots, a_{j_m 0}) \in \mathbb{Q}^m$  and the global primitive  $B : \mathbb{T}^n \rightarrow \mathbb{R}$  of  $b$  has a disconnected sublevel or superlevel on  $\mathbb{T}^n$ .

By Lemma 3.1 we have that  $\mathbb{L}_{\mathcal{A}}$  is globally solvable if and only if  $\mathbb{L}_{0, \mathcal{A}}$  is globally solvable, where  $\mathcal{A} = q_J \mathbb{Z}$  and  $\mathbb{L}_0 = d_t + ib(t) \wedge \frac{\partial}{\partial x}$ . Since  $B$  has a disconnected sublevel or superlevel, we have  $\mathbb{L}_{0, \mathcal{A}}$  not globally solvable by [9]. Therefore  $\mathbb{L}$  is not globally solvable.

Suppose now that  $(a_{j_1 0}, \dots, a_{j_m 0}) \notin \mathbb{Q}^m$  is Liouville. Therefore, by work [8] the involutive system  $\mathbb{L}_J$  generated by the vector fields

$$L_j = \frac{\partial}{\partial t_j} + a_{j 0} \frac{\partial}{\partial x}, \quad j \in J = \{j_1, \dots, j_m\}, \quad (4.1)$$

is not globally solvable on  $\mathbb{T}^{m+1}$ .

As in the sufficiency part, we will consider the set  $I$  such that  $J \cup I = \{1, \dots, n\}$  and  $J \cap I = \emptyset$ .

Consider the space of compatibility conditions  $\mathbb{E}_J$  associated to  $\mathbb{L}_J$ . Since (4.1) is not globally solvable on  $\mathbb{T}^{m+1}$  there exists  $g(t_J, x) = \sum_{j \in J} g_j(t_J, x) dt_j \in \mathbb{E}_J$  such that

$$\mathbb{L}_J v = g$$

has no solution  $v \in \mathcal{D}'(\mathbb{T}^{m+1})$ .

Now, we define smooth functions  $f_1, \dots, f_n$  on  $\mathbb{T}^{n+1}$  such that  $f = \sum_{j=1}^n f_j dt_j \in \mathbb{E}$  and  $\mathbb{L}u = f$  has no solution  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$ .

Let  $B$  be a primitive of the 1-form  $b$ . Thus, we have  $\frac{\partial}{\partial t_j} B = b_j$ . Since for each  $j \in J$  the function  $b_j \equiv 0$  then  $B$  depends only on the variables  $t_I$ ; that is,  $B = B(t_I)$ .

For  $\ell \in I$  we choose  $f_{\ell} \equiv 0$  and for  $j \in J$  we define

$$f_j(t, x) := \sum_{\xi \in \mathbb{Z}} \hat{f}_j(t, \xi) e^{i\xi x},$$

where

$$\hat{f}_j(t, \xi) := \begin{cases} \hat{g}_j(t_J, \xi)e^{\xi(B(t_I)-M)} & \text{if } \xi \geq 0 \\ \hat{g}_j(t_J, \xi)e^{\xi(B(t_I)-\mu)} & \text{if } \xi < 0, \end{cases}$$

where  $M$  and  $\mu$  are, respectively, the maximum and minimum of  $B$  over  $\mathbb{T}^n$ .

Given  $\alpha \in \mathbb{Z}_+^n$ , for each  $j \in J$  we obtain

$$\partial^\alpha \hat{f}_j(t, \xi) = [\partial^{\alpha_J} g_j(t_J, \xi)] \xi^{|\alpha_I|} [\partial^{\alpha_I} B(t_I)] e^{\xi(B(t_I)-M)}, \quad \xi \geq 0,$$

and

$$\partial^\alpha \hat{f}_j(t, \xi) = [\partial^{\alpha_J} g_j(t_J, \xi)] \xi^{|\alpha_I|} [\partial^{\alpha_I} B(t_I)] e^{\xi(B(t_I)-\mu)}, \quad \xi < 0,$$

where  $|\alpha_I| := \sum_{i \in I} \alpha_i$ . Since the derivatives of  $B$  are bounded on  $\mathbb{T}^n$  then, there exists a constant  $C_\alpha > 0$  such that  $|\partial^{\alpha_I} B(t_I)| \leq C_\alpha$  for all  $t_I \in \mathbb{T}_{t_I}^{n-m}$ . Therefore,

$$|\partial^\alpha \hat{f}_j(t, \xi)| \leq C_\alpha |\xi|^{|\alpha_I|} |\partial^{\alpha_J} g_j(t_J, \xi)|, \quad \xi \in \mathbb{Z}.$$

Since  $g_j$  are smooth functions it is possible to conclude by the above inequality that  $f_j, j \in J$ , are smooth functions. Moreover, it is easy to check that  $f = \sum_{j=1}^n f_j dt_j \in \mathbb{E}$ .

Suppose that there exists  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$  such that  $\mathbb{L}u = f$ . Then, if  $u(t, x) = \sum_{\xi \in \mathbb{Z}} \hat{u}(t, \xi) e^{i\xi x}$ , for each  $\xi \in \mathbb{Z}$  we have

$$\frac{\partial}{\partial t_j} \hat{u}(t, \xi) + i\xi a_{j0} \hat{u}(t, \xi) = \hat{f}_j(t, \xi), \quad j \in J \tag{4.2}$$

and

$$\frac{\partial}{\partial t_\ell} \hat{u}(t, \xi) - \xi b_\ell(t) \hat{u}(t, \xi) = 0, \quad \ell \in I \tag{4.3}$$

Thus, for each  $\ell \in I$  we may write (4.3) as follows

$$\begin{aligned} \frac{\partial}{\partial t_\ell} (\hat{u}(t, \xi) e^{-\xi(B(t_I)-M)}) &= 0, \quad \text{if } \xi \geq 0, \\ \frac{\partial}{\partial t_\ell} (\hat{u}(t, \xi) e^{-\xi(B(t_I)-\mu)}) &= 0, \quad \text{if } \xi < 0. \end{aligned}$$

Therefore,

$$\begin{aligned} \hat{u}(t, \xi) e^{-\xi(B(t_I)-M)} &:= \varphi_\xi(t_J), \quad \xi \geq 0, \\ \hat{u}(t, \xi) e^{-\xi(B(t_I)-\mu)} &:= \varphi_\xi(t_J), \quad \xi < 0. \end{aligned} \tag{4.4}$$

Let  $t_I^*$  and  $t_{I*}$  such that  $B(t_I^*) = M$  and  $B(t_{I*}) = \mu$ . Thus,  $\varphi_\xi(t_J) = \hat{u}(t_J, t_I^*, \xi)$  if  $\xi \geq 0$  and  $\varphi_\xi(t_J) = \hat{u}(t_J, t_{I*}, \xi)$  if  $\xi < 0$  for all  $t_J$ . Since  $u \in \mathcal{D}'(\mathbb{T}^{n+1})$  we have

$$v(t_J, x) := \sum_{\xi \in \mathbb{Z}} \varphi_\xi(t_J) e^{i\xi x} \in \mathcal{D}'(\mathbb{T}^{m+1}). \tag{4.5}$$

On the other hand, by (4.2) and (4.4) we have for each  $j \in J$

$$\begin{aligned} \frac{\partial}{\partial t_j} (\varphi_\xi(t_J) e^{\xi(B(t_I)-M)}) + i\xi a_{j0} (\varphi_\xi(t_J) e^{\xi(B(t_I)-M)}) &= \hat{f}_j(t, \xi), \quad \xi \geq 0, \\ \frac{\partial}{\partial t_j} (\varphi_\xi(t_J) e^{\xi(B(t_I)-\mu)}) + i\xi a_{j0} (\varphi_\xi(t_J) e^{\xi(B(t_I)-\mu)}) &= \hat{f}_j(t, \xi), \quad \xi < 0, \end{aligned}$$

thus

$$\frac{\partial}{\partial t_j} \varphi_\xi(t_J) + i\xi a_{j0} \varphi_\xi(t_J) = \hat{g}_j(t_J, \xi), \quad \xi \in \mathbb{Z}, j \in J.$$

We conclude that the  $v$  given by (4.5) is a solution of  $\mathbb{L}_J v = g$ , which is a contradiction.

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