

## SOLVABILITY OF NONLOCAL PROBLEMS FOR SEMILINEAR ONE-DIMENSIONAL WAVE EQUATIONS

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ABSTRACT. In this article, we prove theorems on existence, uniqueness, and nonexistence of solutions for nonlocal problems of a semilinear wave equations in one space variable.

### 1. INTRODUCTION

In a domain  $\Omega : 0 < x < l, 0 < t < l$ , we consider the question of finding a solution  $u(x, t)$  to the nonlocal problem

$$L_\lambda u := u_{tt} - u_{xx} + \lambda f(x, t, u) = F(x, t), \quad (x, t) \in \Omega, \quad (1.1)$$

satisfying the homogeneous boundary conditions

$$u(0, t) = 0, \quad u(l, t) = 0, \quad 0 \leq t \leq l, \quad (1.2)$$

the initial condition

$$u(x, 0) = \varphi(x), \quad 0 \leq x \leq l, \quad (1.3)$$

and the nonlocal condition

$$K_\mu u_t := u_t(x, 0) - \mu u_t(x, l) = \psi(x), \quad 0 \leq x \leq l, \quad (1.4)$$

where  $f, F, \varphi, \psi$  are given continuous functions;  $\lambda$  and  $\mu$  are given nonzero constants. The agreement conditions:  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ ,  $-\varphi''(0) + \lambda f(0, 0, 0) = F(0, 0)$ ,  $-\varphi''(l) + \lambda f(l, 0, 0) = F(l, 0)$  represent necessary conditions for the solvability of (1.1)-(1.4).

There are many articles devoted to the study nonlocal problems for partial differential equations. In the case of abstract evolution equations and hyperbolic differential equations we refer the reader to [1, 2, 3, 5, 6, 7, 8, 10, 12, 13, 14, 15, 16, 17, 20].

**Definition 1.1.** Let  $f \in C(\overline{\Omega} \times \mathbb{R})$ ,  $F \in C(\overline{\Omega})$  and functions  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$  satisfy the agreement conditions  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ . Let  $\Gamma = \Gamma_1 \cup \Gamma_2$ , where  $\Gamma_1 : x = 0, 0 \leq t \leq l$ ,  $\Gamma_2 : x = l, 0 \leq t \leq l$ . We call function  $u$  a strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$ , if  $u \in C^0(\overline{\Omega}, \Gamma) := \{u \in C(\overline{\Omega}), u|_\Gamma = 0\}$  and there exists a sequence of functions  $u_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$ , such that  $u_n \rightarrow u$  and  $L_\lambda u_n \rightarrow F$  in the space  $C(\overline{\Omega})$ ,  $u_n|_{t=0} \rightarrow \varphi$  in the space  $C^1([0, l])$ , and  $K_\mu u_{nt} \rightarrow \psi$  in the space  $C([0, l])$ .

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2000 *Mathematics Subject Classification.* 35L05, 35L20, 35L71.

*Key words and phrases.* Nonlocal problem; semilinear wave equation; existence and nonexistence of solutions.

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Submitted November 14, 2011. Published February 15, 2012.

**Remark 1.2.** Note that a classical solution of (1.1)-(1.4) in the space  $C^2(\overline{\Omega})$  represents a strong generalized solution of this problem of class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1. In turn, if the generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  belongs to the space  $C^2(\overline{\Omega})$ , then it will be also a classical solution of this problem. Note that a strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  satisfies the conditions (1.2), (1.3) in the ordinary classical sense.

**Remark 1.3.** Even in the linear case; i.e., for  $\lambda = 0$ , problem (1.1)-(1.4) is not always well-posed. For example, when  $\lambda = 0$  and  $|\mu| = 1$ , the corresponding to (1.1)-(1.4) homogeneous problem has infinite set of linearly independent solutions (see the Lemma 3.3).

This work is organized as follows. In the Section 2 we study semilinear equation (1.1), when for  $|\mu| < 1$  a priori estimate is valid for the strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1. In the Section 3 we reduce problem (1.1)-(1.4) to an equivalent nonlinear integral equation. In the Section 4, base on the results obtained in previous sections, we prove theorems on existence and uniqueness of a solution of (1.1)-(1.4). Finally, in the Section 5, using the method of test-functions [18], we show that when the conditions of nonlinear term of (1.1), introduced in the Section 2, are violated then problem (1.1)-(1.4) may not have solution.

## 2. A PRIORI ESTIMATE FOR THE SOLUTION OF (1.1)-(1.4)

Let

$$g(x, t, u) = \int_0^u f(x, t, s) ds, \quad (x, t, u) \in \overline{\Omega} \times \mathbb{R}. \quad (2.1)$$

Consider the following conditions imposed on function  $g = g(x, t, u)$ :

$$g(x, t, u) \geq -M_1, \quad (x, t, u) \in \overline{\Omega} \times \mathbb{R}, \quad (2.2)$$

$$g_t \in C(\overline{\Omega} \times \mathbb{R}), \quad g_t(x, t, u) \leq M_2, \quad (x, t, u) \in \overline{\Omega} \times \mathbb{R}, \quad (2.3)$$

where  $M_i$  is a non-negative constant for  $i = 1, 2$ .

**Lemma 2.1.** *Let  $\lambda > 0$ ,  $|\mu| < 1$ ,  $f \in C(\overline{\Omega} \times \mathbb{R})$ ,  $F \in C(\overline{\Omega})$ ,  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$ ,  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ , and the conditions (2.2), (2.3) be fulfilled. Then for the strong generalized solution  $u = u(x, t)$  of (1.1)-(1.4) in class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1, following a priori estimate is valid:*

$$\begin{aligned} \|u\|_{C(\overline{\Omega})} \leq & c_1 \|F\|_{C(\overline{\Omega})} + c_2 \|g(x, 0, \varphi(x))\|_{C([0, l])}^{1/2} + c_3 \|\varphi\|_{C^1([0, l])} \\ & + c_4 \|\psi\|_{C([0, l])} + c_5 \end{aligned} \quad (2.4)$$

with nonnegative constants  $c_i = c_i(\lambda, \mu, l, M_1, M_2)$  independent of  $u, F, \varphi, \psi$ , and  $c_i > 0$  for  $i < 5$ .

*Proof.* Let  $u$  be a strong generalized solution of (1.1)-(1.4) of class  $C$  in the domain  $\Omega$ . In view of Definition 1.1 there exists a sequence of the functions  $u_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  such that

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{C(\overline{\Omega})} = 0, \quad \lim_{n \rightarrow \infty} \|L_\lambda u_n - F\|_{C(\overline{\Omega})} = 0, \quad (2.5)$$

$$\lim_{n \rightarrow \infty} \|u_n|_{t=0} - \varphi\|_{C^1([0, l])} = 0, \quad \lim_{n \rightarrow \infty} \|K_\mu u_{nt} - F\|_{C([0, l])} = 0, \quad (2.6)$$

and therefore

$$\lim_{n \rightarrow \infty} \|f(\cdot, \cdot, u_n(\cdot, \cdot)) - f(\cdot, \cdot, u(\cdot, \cdot))\|_{C(\bar{\Omega})} = 0.$$

Consider function  $u_n \in C^2(\bar{\Omega}) \cap C^0(\bar{\Omega}, \Gamma)$  as a solution of the problem

$$L_\lambda u_n = F_n, \quad (2.7)$$

$$u_n(0, t) = 0, u_n(l, t) = 0, 0 \leq t \leq l, \quad (2.8)$$

$$u_n(x, 0) = \varphi_n(x), 0 \leq x \leq l, \quad (2.9)$$

$$K_\mu u_{nt} = \psi_n(x), 0 \leq x \leq l. \quad (2.10)$$

Here

$$F_n := L_\lambda u_n, \varphi_n := u_n|_{t=0}, \psi_n(x) := K_\mu u_{nt}. \quad (2.11)$$

Multiplying both sides of the equation (2.7) by  $u_{nt}$  and integrating in the domain  $\Omega_\tau := \{(x, t) \in \Omega : t < \tau\}$ ,  $0 < \tau \leq l$ , due to the (2.1), we have

$$\begin{aligned} & \frac{1}{2} \int_{\Omega_\tau} \frac{\partial}{\partial t} \left( \frac{\partial u_n}{\partial t} \right)^2 dx dt - \int_{\Omega_\tau} \frac{\partial^2 u_n}{\partial x^2} \frac{\partial u_n}{\partial t} dx dt \\ & + \lambda \int_{\Omega_\tau} \frac{d}{dt} (g(x, t, u_n(x, t))) dx dt - \lambda \int_{\Omega_\tau} g_t(x, t, u_n(x, t)) dx dt \\ & = \int_{\Omega_\tau} F_n \frac{\partial u_n}{\partial t} dx dt. \end{aligned} \quad (2.12)$$

Let  $\omega_\tau : 0 < x < l, t = \tau; 0 \leq \tau \leq l$  and denote by  $\nu := (\nu_x, \nu_t)$  the unit vector of the outer normal to  $\partial\Omega_\tau$ . Since

$$\nu_x|_{\omega_\tau \cup \omega_0} = 0, \quad \nu_x|_{\Gamma_1} = -1, \quad \nu_x|_{\Gamma_2} = 1, \quad \nu_t|_\Gamma = 0, \quad \nu_t|_{\omega_\tau} = 1, \quad \nu_t|_{\omega_0} = -1,$$

taking into account the equalities (2.8) and integrating by parts, we obtain

$$\frac{1}{2} \int_{\Omega_\tau} \frac{\partial}{\partial t} \left( \frac{\partial u_n}{\partial t} \right)^2 dx dt = \frac{1}{2} \int_{\partial\Omega_\tau} \left( \frac{\partial u_n}{\partial t} \right)^2 \nu_t ds = \frac{1}{2} \int_{\omega_\tau} u_{nt}^2 dx - \frac{1}{2} \int_{\omega_0} u_{nt}^2 dx, \quad (2.13)$$

$$\begin{aligned} - \int_{\Omega_\tau} \frac{\partial^2 u_n}{\partial x^2} \frac{\partial u_n}{\partial t} dx dt &= \int_{\Omega_\tau} \left[ \frac{1}{2} (u_{nx}^2)_t - (u_{nx} u_{nt})_x \right] dx dt \\ &= \frac{1}{2} \int_{\omega_\tau} u_{nx}^2 dx - \frac{1}{2} \int_{\omega_0} u_{nx}^2 dx, \end{aligned} \quad (2.14)$$

$$\begin{aligned} & \lambda \int_{\Omega_\tau} \frac{d}{dt} (g(x, t, u_n(x, t))) dx dt \\ &= \lambda \int_{\partial\Omega_\tau} g(x, t, u_n(x, t)) \nu_t ds \\ &= \lambda \int_{\omega_\tau} g(x, t, u_n(x, t)) dx - \lambda \int_{\omega_0} g(x, t, u_n(x, t)) dx. \end{aligned} \quad (2.15)$$

In view of (2.13), (2.14), (2.15) from (2.12) we obtain

$$\begin{aligned} & \int_{\omega_\tau} [u_{nt}^2 + u_{nx}^2] dx \\ &= \int_{\omega_0} [u_{nt}^2 + u_{nx}^2] dx - 2\lambda \int_{\omega_\tau} g(x, t, u_n(x, t)) dx + 2\lambda \int_{\omega_0} g(x, t, u_n(x, t)) dx \\ & \quad + 2\lambda \int_{\Omega_\tau} g_t(x, t, u_n(x, t)) dx dt + 2 \int_{\Omega_\tau} F_n u_{nt} dx dt. \end{aligned} \quad (2.16)$$

Since  $g \in C(\overline{\Omega} \times \mathbb{R})$ , then due to (2.6), for any  $\epsilon > 0$  there exists the number  $N = N(\epsilon) > 0$  such that

$$\|g(x, 0, u_n(x, 0))\|_{C([0, l])} \leq \|g(x, 0, \varphi(x))\|_{C([0, l])} + \epsilon, \quad n > N. \quad (2.17)$$

Below we assume that  $n > N$ . Let

$$w_n(\tau) := \int_{\omega_\tau} [u_{nt}^2 + u_{nx}^2] dx. \quad (2.18)$$

Since  $2F_n u_{nt} \leq \epsilon_1^{-1} F_n^2 + \epsilon_1 u_{nt}^2$  for any  $\epsilon_1 = \text{const} > 0$ , then due to (2.2), (2.3), (2.17) and (2.18) from (2.16) it follows that

$$\begin{aligned} w_n(\tau) &\leq w_n(0) + 2\lambda M_1 + 2\lambda (\|g(x, 0, \varphi(x))\|_{C([0, l])} + \epsilon) \\ &\quad + 2\lambda M_2 + \epsilon_1 \int_{\Omega_\tau} u_{nt}^2 dx dt + \epsilon_1^{-1} \int_{\Omega_\tau} F_n^2 dx dt. \end{aligned} \quad (2.19)$$

Taking into account that

$$\int_{\Omega_\tau} u_{nt}^2 dx dt = \int_0^\tau \left[ \int_{\omega_s} u_{nt}^2 dx \right] ds \leq \int_0^\tau \left[ \int_{\omega_s} [u_{nt}^2 + u_{nx}^2] dx \right] ds = \int_0^\tau w_n(s) ds,$$

from (2.19) we obtain

$$\begin{aligned} w_n(\tau) &\leq \epsilon_1 \int_0^\tau w_n(s) ds + w_n(0) + 2\lambda [M_1 + M_2 + \|g(x, 0, \varphi(x))\|_{C([0, l])} + \epsilon] \\ &\quad + \epsilon_1^{-1} \int_{\Omega_\tau} F_n^2 dx dt, \quad 0 < \tau \leq l. \end{aligned} \quad (2.20)$$

Because  $\Omega_\tau \subset \Omega$ , by the Gronwall's Lemma [11, p. 13], from (2.20) it follows that for  $0 < \tau \leq l$ ,

$$\begin{aligned} w_n(\tau) &\leq \left[ w_n(0) + 2\lambda (M_1 + M_2 + \|g(x, 0, \varphi(x))\|_{C([0, l])} + \epsilon) \right. \\ &\quad \left. + \epsilon_1^{-1} l^2 \|F_n\|_{C(\overline{\Omega})}^2 \right] e^{\epsilon_1 \tau}, \end{aligned} \quad (2.21)$$

Using the inequality

$$|a + b|^2 = a^2 + b^2 + 2ab \leq a^2 + b^2 + \epsilon_2 a^2 + \epsilon_2^{-1} b^2 = (1 + \epsilon_2) a^2 + (1 + \epsilon_2^{-1}) b^2 \quad \forall \epsilon_2 > 0,$$

from (2.10), we have

$$|u_{nt}(x, 0)|^2 = |\mu u_{nt}(x, l) + \psi_n(x)|^2 \leq |\mu|^2 (1 + \epsilon_2) u_{nt}^2(x, l) + (1 + \epsilon_2^{-1}) \psi_n(x)^2. \quad (2.22)$$

From which we obtain

$$\begin{aligned} \int_{\omega_0} u_{nt}^2 dx &= \int_0^l |u_{nt}(x, 0)|^2 dx \\ &\leq |\mu|^2 (1 + \epsilon_2) \int_0^l u_{nt}^2(x, l) dx + (1 + \epsilon_2^{-1}) \int_0^l \psi_n^2(x) dx \\ &= |\mu|^2 (1 + \epsilon_2) \int_{\omega_l} u_{nt}^2 dx + (1 + \epsilon_2^{-1}) l \|\psi_n\|_{C([0, l])}^2. \end{aligned} \quad (2.23)$$

In view of (2.18) from (2.21), we have

$$\int_{\omega_l} u_{nt}^2 dx \leq w_n(l) \leq \left[ \int_{\omega_0} \varphi_{nx}^2 dx + \int_{\omega_0} u_{nt}^2 dx + M_3 \right] e^{\epsilon_1 l}, \quad (2.24)$$

where

$$M_3 = 2\lambda(M_1 + M_2 + \|g(x, 0, \varphi(x))\|_{C([0,l])} + \epsilon) + \epsilon_1^{-1}l^2\|F_n\|_{C(\bar{\Omega})}^2. \quad (2.25)$$

From (2.23) and (2.24) it follows that

$$\begin{aligned} \int_{\omega_0} u_{nt}^2 dx &\leq |\mu|^2(1 + \epsilon_2) \left[ \int_{\omega_0} \varphi_{nx}^2 dx + \int_{\omega_0} u_{nt}^2 dx + M_3 \right] e^{\epsilon_1 l} \\ &\quad + (1 + \epsilon_2^{-1})l\|\psi_n\|_{C([0,l])}^2. \end{aligned} \quad (2.26)$$

Because  $|\mu| < 1$ , then positive constants  $\epsilon_1$  and  $\epsilon_2$  can be chosen so small that

$$\mu_1 = |\mu|^2(1 + \epsilon_2)e^{\epsilon_1 l} < 1. \quad (2.27)$$

Due to (2.27), from (2.26) we obtain

$$\begin{aligned} \int_{\omega_0} u_{nt}^2 dx &\leq (1 - \mu_1)^{-1} \left[ |\mu|^2(1 + \epsilon_2) \left( \int_{\omega_0} \varphi_{nx}^2 dx + M_3 \right) e^{\epsilon_1 l} \right. \\ &\quad \left. + (1 + \epsilon_2^{-1})l\|\psi_n\|_{C([0,l])}^2 \right]. \end{aligned} \quad (2.28)$$

From (2.9) and (2.28) it follows that

$$\begin{aligned} w_n(0) &= \int_{\omega_0} [u_{nx}^2 + u_{nt}^2] dx \\ &\leq \int_{\omega_0} \varphi_{nx}^2 dx + (1 - \mu_1)^{-1} \left[ |\mu|^2(1 + \epsilon_2) \left( \int_{\omega_0} \varphi_{nx}^2 dx + M_3 \right) e^{\epsilon_1 l} \right. \\ &\quad \left. + (1 + \epsilon_2^{-1})l\|\psi_n\|_{C([0,l])}^2 \right] \\ &\leq l\|\varphi_n\|_{C^1([0,l])}^2 + (1 - \mu_1)^{-1} \left[ |\mu|^2(1 + \epsilon_2) \left( l\|\varphi_n\|_{C^1([0,l])}^2 + M_3 \right) e^{\epsilon_1 l} \right. \\ &\quad \left. + (1 + \epsilon_2^{-1})l\|\psi_n\|_{C([0,l])}^2 \right]. \end{aligned} \quad (2.29)$$

In view of (2.25) and (2.29), from (2.21) we obtain

$$\begin{aligned} w_n(\tau) &\leq \left[ l\|\varphi_n\|_{C^1([0,l])}^2 + (1 - \mu_1)^{-1} \left\{ |\mu|^2(1 + \epsilon_2) \left( l\|\varphi_n\|_{C^1([0,l])}^2 + M_3 \right) e^{\epsilon_1 l} \right. \right. \\ &\quad \left. \left. + (1 + \epsilon_2^{-1})l\|\psi_n\|_{C([0,l])}^2 \right\} + M_3 \right] e^{\epsilon_1 \tau}, \quad 0 < \tau \leq l. \end{aligned} \quad (2.30)$$

In view of (2.8), (2.18), using the Schwartz inequality, for any  $(x, \tau) \in \Omega$  we have

$$\begin{aligned} |u_n(x, \tau)|^2 &= \left( \int_0^x u_{nx}(\xi, \tau) d\xi \right)^2 \leq \int_0^x 1^2 d\xi \int_0^x u_{nx}^2(\xi, \tau) d\xi \\ &\leq l \int_0^l u_{nx}^2(\xi, \tau) d\xi = l \int_{\omega_\tau} u_{nx}^2 dx \leq lw_n(\tau), \end{aligned}$$

from which it follows that

$$|u_n(x, \tau)| \leq [lw_n(\tau)]^{1/2} \quad \forall (x, \tau) \in \Omega. \quad (2.31)$$

Using the inequality

$$\left( \sum_{i=1}^n a_i^2 \right)^{1/2} \leq \sum_{i=1}^n |a_i|$$

and taking into account (2.25), from (2.30) and (2.31), we obtain

$$|u_n(x, \tau)| \leq c_1 \|F_n\|_{C(\bar{\Omega})} + c_2 \|g(x, 0, \varphi(x))\|_{C([0, l])}^{1/2} + c_3 \|\varphi_n\|_{C^1([0, l])} + c_4 \|\psi_n\|_{C([0, l])} + \tilde{c}_5(\epsilon) \quad \forall (x, \tau) \in \Omega. \quad (2.32)$$

Here

$$c_1 = \epsilon_1^{-\frac{1}{2}} l^{3/2} \alpha_1^{1/2}, \quad c_2 = (2\lambda\alpha_1)^{1/2} l, \quad \alpha_1 = (1 - \mu_1)^{-1} \mu^2 (1 + \epsilon_2) e^{2\epsilon_1 l} + e^{\epsilon_1 l}, \quad (2.33)$$

$$c_3 = l^{1/2} [l + (1 - \mu_1)^{-1} |\mu|^2 l (1 + \epsilon_2) e^{\epsilon_1 l}]^{1/2} e^{\frac{1}{2}\epsilon_1 l}, \quad (2.34)$$

$$c_4 = (1 - \mu_1)^{-\frac{1}{2}} (1 + \epsilon_2^{-1})^{1/2} l e^{\frac{1}{2}\epsilon_1 l}, \quad \tilde{c}_5(\epsilon) = l(2\lambda\alpha_1)^{1/2} (M_1 + M_2 + \epsilon)^{1/2}, \quad (2.35)$$

where positive constants  $\epsilon_1, \epsilon_2, \mu_1$  satisfy (2.27), and  $M_1, M_2$  are from (2.2) and (2.3).

Since (2.32) is valid for any  $\epsilon = \text{const} > 0$  and natural number  $n > N(\epsilon)$ , then, passing in the (2.32) to the limit for  $n \rightarrow \infty$ , in view of (2.5) and (2.6), we obtain a priori estimate (2.4) with constants  $c_1, c_2, c_3$  and  $c_4$  from (2.33)-(2.35), and for  $c_5$  we have

$$c_5 := \lim_{\epsilon \rightarrow 0} \tilde{c}_5(\epsilon) = l(2\lambda\alpha_1)^{1/2} (M_1 + M_2)^{1/2}. \quad (2.36)$$

This completes the proof.  $\square$

### 3. REDUCTION OF (1.1)-(1.4) TO A NONLINEAR INTEGRAL EQUATION

First let us consider in the domain  $\Omega : 0 < x, t < l$  the linear mixed problem

$$u_{tt} - u_{xx} = F(x, t), \quad (x, t) \in \Omega, \quad (3.1)$$

$$u(x, 0) = u_0(x), \quad u_t(x, 0) = u_1(x), \quad 0 \leq x \leq l, \quad (3.2)$$

$$u(0, t) = 0, \quad u(l, t) = 0, \quad 0 \leq t \leq l, \quad (3.3)$$

where  $F \in C^1(\bar{\Omega}), u_0 \in C^2([0, l]), u_1 \in C^1([0, l])$  are given functions, satisfying the agreement conditions

$$u_0(0) = u_0(l) = u_1(0) = u_1(l) = 0, \quad -u_0''(0) = F(0, 0), \quad -u_0''(l) = F(l, 0).$$

For obtaining the solution  $u \in C^2(\bar{\Omega})$  of (3.1)-(3.3) in convenient form we divide the domain  $\Omega$ , being a quadrate with vertices in points  $O(0, 0), A(0, l), B(l, l)$  and  $C(l, 0)$ , into four right triangles  $\Delta_1 = \triangle OO_1C, \Delta_2 = \triangle OO_1A, \Delta_3 = \triangle CO_1B$  and  $\Delta_4 = \triangle O_1AB$ , where point  $O_1(l/2, l/2)$  is the center of quadrate  $\Omega$ . In the triangle  $\Delta_1 = \triangle OO_1C$  the solution of (3.1)-(3.3), as it is known, is given by the formula [4, p. 67]

$$u(x, t) = \frac{1}{2} [u_0(x+t) + u_0(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} u_1(\tau) d\tau + \frac{1}{2} \int_{\Omega_{x,t}^1} F(\xi, \tau) d\xi d\tau, \quad (x, t) \in \Delta_1, \quad (3.4)$$

where  $\Omega_{x,t}^1$  is a triangle with vertices in points  $(x, t), (t-x, 0)$  and  $(t+x, 0)$ .

For obtaining the solution of (3.1)-(3.3) in the other triangles  $\Delta_2, \Delta_3$  and  $\Delta_4$ , we use the equality [4, p. 66]

$$u(P) = u(P_1) + u(P_2) - u(P_3) + \frac{1}{2} \int_{PP_1P_2P_3} F(\xi, \tau) d\xi d\tau, \quad (3.5)$$

which is valid for any rectangle  $PP_1P_2P_3 \subset \bar{\Omega}$  characteristic for (3.1), where  $P, P_3$  and  $P_1, P_2$  are opposite vertices of this rectangle, besides, the ordinate of point  $P$  is greater than the ordinates of other points. Indeed, if point  $(x, t) \in \Delta_2$ , then, using the equality (3.5) for characteristic rectangle with vertices in points  $P(x, t), P_1(0, t-x), P_2(t, x), P_3(t-x, 0)$  and the formula (3.4) for point  $P_2(t, x) \in \Delta_1$ , and taking into account (3.3), we obtain

$$\begin{aligned} u(x, t) &= u(P_1) + u(P_2) - u(P_3) + \frac{1}{2} \int_{PP_1P_2P_3} F(\xi, \tau) d\xi d\tau \\ &= -u_0(t-x) + \frac{1}{2}[u_0(t-x) + u_0(t+x)] + \frac{1}{2} \int_{t-x}^{t+x} u_1(\tau) d\tau \\ &\quad + \frac{1}{2} \int_{\Omega_{t,x}^1} F(\xi, \tau) d\xi d\tau + \frac{1}{2} \int_{PP_1P_2P_3} F(\xi, \tau) d\xi d\tau \\ &= \frac{1}{2}[u_0(t+x) - u_0(t-x)] + \frac{1}{2} \int_{t-x}^{t+x} u_1(\tau) d\tau \\ &\quad + \frac{1}{2} \int_{\Omega_{x,t}^2} F(\xi, \tau) d\xi d\tau, \quad (x, t) \in \Delta_2. \end{aligned} \quad (3.6)$$

Here  $\Omega_{x,t}^2$  is a quadrangle  $PP_1\tilde{P}_2P_3$ , where  $\tilde{P}_2 = \tilde{P}_2(t+x, 0)$ . Analogously,

$$\begin{aligned} u(x, t) &= \frac{1}{2}[u_0(x-t) - u_0(2l-t-x)] + \frac{1}{2} \int_{x-t}^{2l-t-x} u_1(\tau) d\tau \\ &\quad + \frac{1}{2} \int_{\Omega_{x,t}^3} F(\xi, \tau) d\xi d\tau, \quad (x, t) \in \Delta_3, \end{aligned} \quad (3.7)$$

$$\begin{aligned} u(x, t) &= -\frac{1}{2}[u_0(t-x) + u_0(2l-t-x)] + \frac{1}{2} \int_{t-x}^{2l-t-x} u_1(\tau) d\tau \\ &\quad + \frac{1}{2} \int_{\Omega_{x,t}^4} F(\xi, \tau) d\xi d\tau, \quad (x, t) \in \Delta_4. \end{aligned} \quad (3.8)$$

Here  $\Omega_{x,t}^3$  is a quadrangle with vertices  $P^3(x, t), P_1^3(l, t+x-l), P_2^3(x-t, 0)$  and  $P_3^3(2l-t-x, 0)$ , while  $\Omega_{x,t}^4$  is a pentagon with vertices  $P^4(x, t), P_1^4(0, t-x), P_2^4(t-x, 0), P_3^4(2l-t-x, 0)$  and  $P_4^4(l, t+x-l)$ .

**Remark 3.1.** Note that for  $F \in C(\bar{\Omega}), u_0 \in C^1([0, l]), u_1 \in C([0, l])$ , satisfying the agreement conditions  $u_0(0) = u_0(l) = u_1(0) = u_1(l) = 0$ , the function  $u \in C^1(\bar{\Omega})$  represented in  $\Omega$  by formulas (3.4), (3.6)-(3.8) is a generalized solution of (3.1)-(3.3) of the class  $C^1$ .

Further, using formulas (3.4), (3.6)-(3.8) let us solve a linear problem corresponding to (1.1)-(1.4); i.e., when in (1.1) the parameter  $\lambda = 0$  and the problem has the form

$$L_0 u := u_{tt} - u_{xx} = F(x, t), \quad (x, t) \in \Omega, \quad (3.9)$$

$$u(0, t) = 0, u(l, t) = 0, \quad 0 \leq t \leq l, \quad (3.10)$$

$$u(x, 0) = \varphi(x), \quad 0 \leq x \leq l, \quad (3.11)$$

$$K_\mu u_t := u_t(x, 0) - \mu u_t(x, l) = \psi(x), \quad 0 \leq x \leq l. \quad (3.12)$$

Indeed, differentiating the equality (3.8) on  $t$ , we have

$$\begin{aligned} u_t(x, t) = & -\frac{1}{2}[u'_0(t-x) - u'_0(2l-t-x)] \\ & -\frac{1}{2}[u_1(2l-t-x) + u_1(t-x)] + F_1(x, t), \end{aligned} \quad (3.13)$$

where

$$F_1(x, t) := \frac{\partial}{\partial t} \left[ \frac{1}{2} \int_{\Omega_{x,t}^4} F(\xi, \tau) d\xi d\tau \right]. \quad (3.14)$$

From (3.13) for  $t = l$  we obtain

$$u_t(x, l) = -u_1(l-x) + F_1(x, l), \quad 0 \leq x \leq l. \quad (3.15)$$

Substituting (3.15) in (3.12), with respect to unknown function  $u_1(x) = u_t(x, 0)$ , we obtain the functional equation

$$u_1(x) + \mu u_1(l-x) = \psi_1(x), \quad 0 \leq x \leq l. \quad (3.16)$$

Here

$$\psi_1(x) := \psi(x) + \mu F_1(x, l), \quad 0 \leq x \leq l. \quad (3.17)$$

Putting in (3.16) the value  $l-x$  instead of  $x$  we obtain

$$\mu u_1(x) + u_1(l-x) = \psi_1(l-x), \quad 0 \leq x \leq l. \quad (3.18)$$

For  $|\mu| \neq 1$ , eliminating  $u_1(l-x)$  from the system (3.16), (3.18), we have

$$u_1(x) = (1 - \mu^2)^{-1}(\psi_1(x) - \mu\psi_1(l-x)), \quad (3.19)$$

Substituting in (3.4), (3.6)-(3.8) the function  $\varphi(x)$  from (3.11) instead the function  $u_0(x)$ , and the right side part of (3.19) instead of the function  $u_1(x)$ , fulfilling the certain conditions of smoothness and agreement imposed on the functions  $F$ ,  $\varphi$  and  $\psi$ , we obtain a unique solution  $u = u(x, t)$  of (3.9)-(3.12).

**Remark 3.2.** It is easy to see that for  $|\mu| = 1$  the homogeneous equation, corresponding to (3.18), has an infinite set of linearly independent solutions, which for  $\mu = 1$  are arbitrary odd functions  $u_1^0$  with respect to point  $x = l/2$ ; i.e.,  $u_1^0(l/2 + \xi) = -u_1^0(l/2 - \xi)$ ,  $|\xi| \leq l/2$ , while for  $\mu = -1$  they are arbitrary even functions  $u_1^0$  with respect to point  $x = l/2$ ; i.e.,  $u_1^0(l/2 + \xi) = u_1^0(l/2 - \xi)$ ,  $|\xi| \leq l/2$ .

Due to (3.4), (3.6)-(3.8), (3.19) and Remark 3.2 the following lemma is valid.

**Lemma 3.3.** *Let  $F \in C^1(\overline{\Omega})$ ,  $\varphi \in C^2([0, l])$ ,  $\psi \in C^1([0, l])$  and the agreement conditions  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ ,  $-\varphi''(0) = F(0, 0)$ ,  $-\varphi''(l) = F(l, 0)$  be fulfilled. Then for  $|\mu| \neq 1$ , problem (3.9)-(3.12) has an unique solution  $u \in C^2(\overline{\Omega})$ , which is given by formulas (3.4), (3.6)-(3.8), where instead of  $u_0(x)$  must be put  $\varphi(x)$  from (3.11) and instead of the function  $u_1(x)$  must be put the function from (3.19). These formulas, when  $|\mu| \neq 1$  and  $F \in C(\overline{\Omega})$ ,  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$  with the agreement conditions  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ , give the function  $u \in C^1(\overline{\Omega})$ , being a generalized solution of (3.9)-(3.12) of the class  $C^1$ . Finally, for  $|\mu| = 1$  the homogeneous problem, corresponding to (3.9)-(3.12), has an infinite set of linearly independent solutions of the class  $C^2(\overline{\Omega})$ , which are given by formulas (3.4), (3.6)-(3.8), where  $F = 0$ ,  $u_0 = 0$ , and  $u_1 \in C^1([0, l])$ ,  $u_1(0) = u_1(l) = 0$  is an arbitrary odd (even) function with respect to point  $x = l/2$  in the case  $\mu = 1$  ( $\mu = -1$ ).*



**Remark 3.4.** In view of Lemma 3.3 and formulas (3.4), (3.6)-(3.8), (3.14), (3.17) and (3.19), it is easy to see that for  $|\mu| \neq 1$  a unique solution  $u \in C^2(\overline{\Omega})$  of (3.9)-(3.12) can be represented in the form

$$u(x, t) = (l_0^{-1}(\varphi, \psi))(x, t) + (L_0^{-1}F)(x, t), \quad (x, t) \in \overline{\Omega}, \quad (3.20)$$

where  $l_0^{-1}(\varphi, \psi)$  represents a solution of (3.9)-(3.12) for  $F = 0$ , and  $L_0^{-1}F$  is also a solution to this problem for  $\varphi = 0, \psi = 0$ . Note that for  $\varphi \in C^1([0, l]), \psi \in C([0, l])$  and  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$  the function  $l_0^{-1}(\varphi, \psi)$  is a generalized solution of (3.9)-(3.12) of the class  $C^1(\overline{\Omega})$  for  $F = 0$ , and when  $F \in C(\overline{\Omega})$  the function  $L_0^{-1}F$  is a generalized solution of this problem of the class  $C^1(\overline{\Omega})$  for  $\varphi = 0, \psi = 0$ . In this case the linear operator  $l_0^{-1} : C^{01}([0, l]) \times C^0([0, l]) \rightarrow C(\overline{\Omega})$  is continuous, where  $C^{0k}([0, l]) := \{\chi \in C^k([0, l]) : \chi(0) = \chi(l) = 0\}$ ; i.e.,

$$\|l_0^{-1}(\varphi, \psi)\|_{C(\overline{\Omega})} \leq \tilde{c}\|(\varphi, \psi)\|_{C^{01}([0, l]) \times C^0([0, l])} \quad (3.21)$$

for all  $(\varphi, \psi) \in C^{01}([0, l]) \times C^0([0, l])$  with positive constant  $\tilde{c}$ , not depending on  $(\varphi, \psi)$ .

**Remark 3.5.** Using standard reasoning one may show that the operator  $L_0^{-1}$  from (3.20), being a linear integral operator, acts continuously from the space  $C(\overline{\Omega})$  into the space  $C^1(\overline{\Omega})$ ; i.e.,

$$\|L_0^{-1}F\|_{C^1(\overline{\Omega})} \leq c_0\|F\|_{C(\overline{\Omega})} \quad \forall F \in C(\overline{\Omega}) \quad (3.22)$$

with positive constant  $c_0$ , not depending on  $F$ .

**Remark 3.6.** Since the space  $C^1(\overline{\Omega})$  is compactly embedded into the space  $C(\overline{\Omega})$  [9, p. 135], in view of (3.22) the operator  $L_0^{-1} : C(\overline{\Omega}) \rightarrow C(\overline{\Omega})$  from (3.20) is a linear compact operator. One may come to the same conclusion noting that the continuous operator  $L_0^{-1} : C(\overline{\Omega}) \rightarrow C(\overline{\Omega})$  maps bounded in  $C(\overline{\Omega})$  sets into equicontinuous sets, and further using the criterium of precompactness of a set in the space  $C(\overline{\Omega})$  [19, p. 414].

**Remark 3.7.** If  $u \in C^2(\overline{\Omega})$  is a classical solution of (1.1)-(1.4), then due to the representation (3.20) it will satisfy the nonlinear integral equation

$$\begin{aligned} & u(x, t) + \lambda(L_0^{-1}f|_{u=u(x,t)})(x, t) \\ &= (l_0^{-1}(\varphi, \psi))(x, t) + (L_0^{-1}F)(x, t), \quad (x, t) \in \overline{\Omega}. \end{aligned} \quad (3.23)$$

**Lemma 3.8.** Let  $f \in C^1(\overline{\Omega} \times \mathbb{R})$ . A function  $u \in C(\overline{\Omega})$  is a strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1 if and only if it is a continuous solution of the nonlinear integral equation (3.23).

*Proof.* Let  $u \in C(\overline{\Omega})$  be a solution of (3.23). Since  $F \in C(\overline{\Omega})$  ( $\varphi \in C^1([0, l]), \psi \in C([0, l]), \varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ ), and the space  $C^2(\overline{\Omega})$  ( $C^k([0, l])$ ) is dense in  $C(\overline{\Omega})$  ( $C^{k_1}([0, l]), k_1 < k$ ) [21, p. 37], then there exist the sequences of functions  $F_n \in C^2(\overline{\Omega}), \varphi_n \in C^2([0, l])$  and  $\psi_n \in C^1([0, l])$  such that  $\varphi_n(0) = \varphi_n(l) = \psi_n(0) = \psi_n(l) = 0, -\varphi_n''(0) + \lambda f(0, 0, 0) = F_n(0, 0), -\varphi_n''(l) + \lambda f(l, 0, 0) = F_n(l, 0)$ , and

$$\begin{aligned} \lim_{n \rightarrow \infty} \|F_n - F\|_{C(\overline{\Omega})} &= 0, \quad \lim_{n \rightarrow \infty} \|\varphi_n - \varphi\|_{C^1([0, l])} = 0, \\ \lim_{n \rightarrow \infty} \|\psi_n - \psi\|_{C([0, l])} &= 0. \end{aligned} \quad (3.24)$$

Since  $u \in C(\overline{\Omega})$  represents a solution of the integral equation (3.23), as it is easy to verify  $u|_{\Gamma} = 0$ ; i.e.,  $u \in C^0(\overline{\Omega}, \Gamma)$ , and therefore there exists the sequence of functions  $w_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  such that

$$\lim_{n \rightarrow \infty} \|w_n - u\|_{C(\overline{\Omega})} = 0. \tag{3.25}$$

Let

$$u_n = -\lambda L_0^{-1} f|_{u=w_n} + l_0^{-1}(\varphi_n, \psi_n) + L_0^{-1} F_n. \tag{3.26}$$

Since  $w_n|_{\Gamma} = 0$ ,  $-\varphi_n''(0) + \lambda f(0, 0, 0) = F_n(0, 0)$ ,  $-\varphi_n''(l) + \lambda f(l, 0, 0) = F_n(l, 0)$ , it is obvious that  $-\varphi_n''(0) = (-\lambda f|_{u=w_n} + F_n)(0, 0)$  and  $-\varphi_n''(l) = (-\lambda f|_{u=w_n} + F_n)(l, 0)$ . Therefore, since  $f \in C^1(\overline{\Omega} \times \mathbb{R})$ ,  $w_n \in C^2(\overline{\Omega})$ ,  $F_n \in C^2(\overline{\Omega})$  and  $(-\lambda f|_{u=w_n} + F_n) \in C^1(\overline{\Omega})$ , then in view of Remark 3.4 the function  $u_n$  from (3.26) belongs to the space  $C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$ , and

$$u_n|_{t=0} = \varphi_n, K_{\mu} u_n = \psi_n. \tag{3.27}$$

From (3.21), (3.22), (3.24)-(3.27) it follows immediately that

$$u_n(x, t) \rightarrow \left[ -\lambda(L_0^{-1} f|_{u=u(x,t)})(x, t) + (l_0^{-1}(\varphi, \psi))(x, t) + (L_0^{-1} F)(x, t) \right]$$

in the space  $C(\overline{\Omega})$ . Also, from (3.23) it follows that

$$-\lambda(L_0^{-1} f|_{u=u(x,t)})(x, t) + (l_0^{-1}(\varphi, \psi))(x, t) + (L_0^{-1} F)(x, t) = u(x, t).$$

Therefore,

$$\lim_{n \rightarrow \infty} \|u_n - u\|_{C(\overline{\Omega})} = 0. \tag{3.28}$$

Due to Remark 3.4, from (3.26) it follows that  $L_0 u_n = -\lambda f|_{u=w_n} + F_n$  and, therefore,

$$\begin{aligned} L_{\lambda} u_n &= L_0 u_n + \lambda f|_{u=u_n} = -\lambda f|_{u=w_n} + F_n + \lambda f|_{u=u_n} \\ &= -\lambda(f(\cdot, w_n) - f(\cdot, u)) + \lambda(f(\cdot, u_n) - f(\cdot, u)) + F_n. \end{aligned} \tag{3.29}$$

Since  $f \in C(\overline{\Omega} \times \mathbb{R})$ , in view of (3.25), (3.28) from (3.29), we have

$$\lim_{n \rightarrow \infty} \|L_{\lambda} u_n - F_n\|_{C(\overline{\Omega})} = 0. \tag{3.30}$$

Due to (3.24) and (3.27), we have

$$\lim_{n \rightarrow \infty} \|u_n|_{t=0} - \varphi\|_{C^1([0,l])} = 0, \quad \lim_{n \rightarrow \infty} \|K_{\mu} u_n - \psi\|_{C([0,l])} = 0. \tag{3.31}$$

Therefore, from (3.28), (3.30) and (3.21) we conclude that a continuous solution  $u \in C(\overline{\Omega})$  of the nonlinear integral equation (3.23) is also a strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1. The inverse is obvious.  $\square$

#### 4. EXISTENCE AND UNIQUENESS OF THE SOLUTION TO (1.1) - (1.4)

Rewrite the equation (3.23) in the form

$$u = Tu := -\lambda \left( L_0^{-1} f|_{u=u(x,t)} \right) (x, t) + l_0^{-1}(\varphi, \psi) + L_0^{-1} F, \tag{4.1}$$

where operator  $T : C(\overline{\Omega}) \rightarrow C(\overline{\Omega})$  is continuous and compact, since the operator  $N : C(\overline{\Omega}) \rightarrow C(\overline{\Omega})$ , acting according to the formula  $Nu := -\lambda f(x, t, u)$  is bounded and continuous, and the linear operator  $L_0^{-1} : C(\overline{\Omega}) \rightarrow C(\overline{\Omega})$  due to Remark 3.6, it is compact. Here we take into account that the component  $T_1 u := l_0^{-1}(\varphi, \psi) + L_0^{-1} F$  of the operator  $T$  from (4.1) is constant, and therefore, continuous and compact

operator, acting in the space  $C(\overline{\Omega})$ . At the same time, according to Lemmas 2.1 and 3.8, and also (2.2), (2.3), (2.33)-(2.36) for any parameter  $\tau \in [0, 1]$  and every solution  $u \in C(\overline{\Omega})$  of the equation  $u = \tau Tu$  it is valid a priori estimate (2.4) with the same constants  $c_i$ ,  $i = 1, \dots, 5$ , not depending on  $u, F, \varphi, \psi$  and  $\tau$ . Therefore, according to the Leray-Schauder theorem [22, p. 375], the equation (4.1) for the conditions of the Lemmas 2.1 and 3.8 has at least one solution  $u \in C(\overline{\Omega})$ . In this way, due to the Lemmas 2.1, 3.8 and also Remark 3.6, we have proved the following theorem.

**Theorem 4.1.** *Let  $\lambda > 0$ ,  $|\mu| < 1$ ,  $f \in C^1(\overline{\Omega} \times \mathbb{R})$ ,  $F \in C(\overline{\Omega})$ ,  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$ ,  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$  and the conditions (2.2), (2.3) be fulfilled. Then (1.1)-(1.4) has at least one strong generalized solution of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1.*

**Remark 4.2.** Since (3.23) can be rewritten in the form of (3.20):

$$u(x, t) = (L_0^{-1}(\varphi, \psi))(x, t) + (L_0^{-1}(-\lambda f|_{u=u(x,t)} + F))(x, t), \quad (x, t) \in \overline{\Omega},$$

in view of Lemma 3.3 and Remark 3.4, the generalized solution  $u$  of the class  $C$ , the existence of which is asserted in the Theorem 4.1, belongs to the class  $C^1(\overline{\Omega})$ . Moreover, if we require in addition that  $F \in C^1(\overline{\Omega})$ ,  $\varphi \in C^2([0, l])$ ,  $\psi \in C^1([0, l])$  and  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ ,  $-\varphi''(0) + \lambda f(0, 0, 0) = F(0, 0)$ ,  $-\varphi''(l) + \lambda f(l, 0, 0) = F(l, 0)$ , then this solution will belong to the class  $C^2(\overline{\Omega})$ ; i.e., it will be a classical solution of (1.1)-(1.4).

**Remark 4.3.** Let us consider some classes of functions  $f = f(x, t, u)$  frequently encountered in applications and which satisfy the conditions (2.2), (2.3):

1.  $f(x, t, u) = f_0(x, t)\psi(u)$ , where  $f_0, \frac{\partial}{\partial t}f_0 \in C(\overline{\Omega})$  and  $\psi \in C(\mathbb{R})$ . In this case  $g(x, t, u) = f_0(x, t) \int_0^u \psi(s)ds$  and when  $f_0 \geq 0$ ,  $\frac{\partial}{\partial t}f_0 \leq 0$ ,  $\int_0^u \psi(s)ds \geq -M$ ,  $M$  is a non-negative constant, the conditions (2.2), (2.3) will be fulfilled.

2.  $f(x, t, u) = f_0(x, t)|u|^\alpha \operatorname{sgn} u$ , where  $f_0, \frac{\partial}{\partial t}f_0 \in C(\overline{\Omega})$  and  $\alpha > 1$ . In this case  $g(x, t, u) = f_0(x, t) \frac{|u|^{\alpha+1}}{\alpha+1}$  and when  $f_0 \geq 0$ ,  $\frac{\partial}{\partial t}f_0 \leq 0$ , the conditions (2.2), (2.3) will be fulfilled.

3.  $f(x, t, u) = f_0(x, t)e^u$ , where  $f_0, \frac{\partial}{\partial t}f_0 \in C(\overline{\Omega})$ . In this case  $g(x, t, u) = f(x, t, u)$  and when  $f_0 \geq 0$ ,  $\frac{\partial}{\partial t}f_0 \leq 0$ , the conditions (2.2), (2.3) will be also fulfilled.

Therefore, if function  $f \in C^1(\overline{\Omega} \times \mathbb{R})$  belongs to the one of the classes considered above, then according to the Theorem 4.1, problem (1.1)-(1.4) is solvable in the class  $C$  in the sense of Definition 1.1.

**Remark 4.4.** Let us consider the example of the function  $f$ , which is also often encountered in applications, when at least one of the conditions (2.2) and (2.3) is violated. Such function is

$$f(x, t, u) = f_0(x, t)|u|^\alpha, \quad \alpha > 1, \quad (4.2)$$

where  $f_0, \frac{\partial}{\partial t}f_0 \in C(\overline{\Omega})$  and  $f_0 \neq 0$ . In this case due to (2.1) we have  $g(x, t, u) = f_0(x, t) \frac{|u|^{\alpha+1}}{\alpha+1}$ , and since  $\alpha > 1$  and  $f_0 \neq 0$ , then the condition (2.2) will be violated. If  $\frac{\partial}{\partial t}f_0 \neq 0$ , then the condition (2.3) will be also violated. Below we show that when (2.2) and (2.3) are violated then the problem (1.1)-(1.4) may be insoluble.

Let us consider the uniqueness of the solution of (1.1)-(1.4). Let the function  $f$  satisfy the Lipschitz local condition on the set  $\overline{\Omega} \times \mathbb{R}$  with respect to variable  $u$ ; i.e.,

$$|f(x, t, u_2) - f(x, t, u_1)| \leq M(R)|u_2 - u_1|, \quad (x, t) \in \overline{\Omega}, \quad |u_i| \leq R, \quad i = 1, 2, \quad (4.3)$$

where  $M = M(R)$  is a non-negative constant, it is nondecreasing function of variable  $R$ .

**Theorem 4.5.** *Let  $|\mu| < 1$ ,  $F \in C(\overline{\Omega})$ ;  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$ ,  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ , function  $f \in C(\overline{\Omega} \times \mathbb{R})$  and satisfy the condition (4.3). Then there exists a positive number  $\lambda_0 = \lambda_0(F, f, \varphi, \mu, l)$  such that for  $0 < \lambda < \lambda_0$ , problem (1.1)-(1.4) can not have more than one strong generalized solution of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1.*

*Proof.* Suppose that (1.1)-(1.4) has two strong generalized solutions  $u_1$  and  $u_2$  of the class  $C$  in the domain  $\Omega$ . According to Definition 1.1 there exists a sequence of functions  $u_{jn} \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  such that

$$\lim_{n \rightarrow \infty} \|u_{jn} - u_j\|_{C(\overline{\Omega})} = 0, \quad \lim_{n \rightarrow \infty} \|L_\lambda u_{jn} - F\|_{C(\overline{\Omega})} = 0, \quad (4.4)$$

$$\lim_{n \rightarrow \infty} \|u_{jn}|_{t=0} - \varphi\|_{C^1([0, l])} = 0, \quad \lim_{n \rightarrow \infty} \|K_\mu u_{jnt} - \psi\|_{C([0, l])} = 0, \quad (4.5)$$

for  $j = 1, 2$ . Let  $v_n := u_{2n} - u_{1n}$ . It is easy to see that the function  $v_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  represents a classical solution of the problem

$$\left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2}\right)v_n = (F_n + g_n)(x, t), \quad (x, t) \in \Omega, \quad (4.6)$$

$$v_n(0, t) = 0, v_n(l, t) = 0, 0 \leq t \leq l, \quad (4.7)$$

$$v_n(x, 0) = \varphi_n(x), 0 \leq x \leq l, \quad (4.8)$$

$$K_\mu v_{nt} := v_{nt}(x, 0) - \mu v_{nt}(x, l) = \psi_n(x), 0 \leq x \leq l. \quad (4.9)$$

Here

$$g_n := \lambda(f(x, t, u_{1n}) - f(x, t, u_{2n})), \quad (4.10)$$

$$F_n := L_\lambda u_{2n} - L_\lambda u_{1n}, \quad (4.11)$$

$$\varphi_n := v_n|_{t=0}, \quad (4.12)$$

$$\psi_n := K_\mu v_{nt}. \quad (4.13)$$

From the proof of Lemma 2.1 it follows easily that a priori estimate (2.4) is valid in the linear case too; i.e., when in (1.1) the parameter  $\lambda = 0$ . In this case due to (2.33)-(2.36), determining the constants  $c_i$ , we have  $c_2 = c_5 = 0$  and the estimate (2.4) takes the form

$$\|u\|_{C(\overline{\Omega})} \leq c_1 \|F\|_{C(\overline{\Omega})} + c_3 \|\varphi\|_{C^1([0, l])} + c_4 \|\psi\|_{C([0, l])}, \quad (4.14)$$

where the constants  $c_1, c_3$  and  $c_4$  do not depend on the parameter  $\lambda$  and the functions  $u, F, \varphi, \psi$ .

In view of (4.14) for the solution  $v_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  of (4.6)-(4.9), the following estimate is valid

$$\|v_n\|_{C(\overline{\Omega})} \leq c_1 \|F_n + g_n\|_{C(\overline{\Omega})} + c_3 \|\varphi_n\|_{C^1([0, l])} + c_4 \|\psi_n\|_{C([0, l])}. \quad (4.15)$$

From (4.4), (4.5) and (4.11)-(4.13) it follows that

$$\lim_{n \rightarrow \infty} \|F_n\|_{C(\overline{\Omega})} = 0, \quad \lim_{n \rightarrow \infty} \|\varphi_n\|_{C^1([0, l])} = 0, \quad \lim_{n \rightarrow \infty} \|\psi_n\|_{C([0, l])} = 0. \quad (4.16)$$

Due to a priori estimate (2.4) for the solutions  $u_1$  and  $u_2$  of (1.1)-(1.4), we have

$$\|u_j\|_{C(\overline{\Omega})} \leq m_3 + \lambda^{1/2} m_4, \quad j = 1, 2, \quad (4.17)$$

where according to (2.33)-(2.36) positive constants  $m_i = m_i(\mu, l, M_1, M_2, F, \varphi, \psi)$ ,  $i = 3, 4$ , do not depend on  $\lambda$ .

Let us fix arbitrarily the number  $\lambda_1 > 0$  and put  $M_0 = M(m_3 + \lambda_1^{1/2}m_4 + 1)$ , where  $M = M(R)$  is nondecreasing function from (4.3). In view of (4.4) for any  $\epsilon > 0$  there exists number  $N > 0$  such that  $\|u_{jn}\|_{C(\bar{\Omega})} \leq \|u_j\|_{C(\bar{\Omega})} + \epsilon$ ,  $j = 1, 2$ , for  $n > N$ , and, therefore, for  $0 < \lambda < \lambda_1$ , taking into account (4.17), we have

$$\|u_{jn}\|_{C(\bar{\Omega})} \leq m_3 + \lambda^{1/2}m_4 + \epsilon \leq m_3 + \lambda_1^{1/2}m_4 + \epsilon, \quad j = 1, 2; n > N. \quad (4.18)$$

From (4.3), (4.10) and (4.18) for  $0 < \lambda < \lambda_1$  and  $\epsilon = 1$  it follows that

$$\|g_n\|_{C(\bar{\Omega})} \leq \lambda \|f(x, t, u_{1n}) - f(x, t, u_{2n})\|_{C(\bar{\Omega})} \leq \lambda M_0 \|v_n\|_{C(\bar{\Omega})}, \quad (4.19)$$

for  $n > N$ . Due to (4.15) and (4.19) we have

$$\|v_n\|_{C(\bar{\Omega})} \leq c_1 \|F_n\|_{C(\bar{\Omega})} + \lambda c_1 M_0 \|v_n\|_{C(\bar{\Omega})} + c_3 \|\varphi_n\|_{C^1([0, l])} + c_4 \|\psi_n\|_{C([0, l])},$$

for  $n > N$ , whence for  $\lambda_0 := \min(\lambda_1, \frac{1}{c_1 M_0})$  and  $0 < \lambda < \lambda_0$  it follows that

$$\|v_n\|_{C(\bar{\Omega})} \leq (1 - \lambda c_1 M_0)^{-1} [c_1 \|F_n\|_{C(\bar{\Omega})} + c_3 \|\varphi_n\|_{C^1([0, l])} + c_4 \|\psi_n\|_{C([0, l])}], \quad (4.20)$$

for  $n > N$ . From (4.4) we find that

$$\lim_{n \rightarrow \infty} \|v_n\|_{C(\bar{\Omega})} = \|u_2 - u_1\|_{C(\bar{\Omega})}.$$

Also, in view of (4.16) and (4.20) we have

$$\lim_{n \rightarrow \infty} \|v_n\|_{C(\bar{\Omega})} = 0.$$

Thus  $\|u_2 - u_1\|_{C(\bar{\Omega})} = 0$ ; i.e.,  $u_2 = u_1$ , which leads to contradiction, the proof is complete.  $\square$

Since the function  $f \in C^1(\bar{\Omega} \times \mathbb{R})$  satisfies condition (4.3), then from theorems 4.1 and 4.5, we have the following theorem.

**Theorem 4.6.** *Let  $|\mu| < 1$ ,  $f \in C^1(\bar{\Omega} \times \mathbb{R})$ ,  $F \in C(\bar{\Omega})$ ,  $\varphi \in C^1([0, l])$ ,  $\psi \in C([0, l])$ ,  $\varphi(0) = \varphi(l) = \psi(0) = \psi(l) = 0$ , and the conditions (2.2), (2.3) be fulfilled. Then there exists a positive number  $\lambda_0 = \lambda_0(F, \varphi, \psi, \mu, l)$  such that for  $0 < \lambda < \lambda_0$  the problem (1.1)-(1.4) has a unique strong generalized solution of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1.*

## 5. CASES OF NONEXISTENCE OF SOLUTIONS TO (1.1)-(1.4)

Below, using the method of test-functions [18], we show that when condition (2.2) or (2.3) is violated, problem (1.1)-(1.4) may have no strong generalized solution of the class  $C$  in the domain  $\Omega$ , in the sense of Definition 1.1.

**Lemma 5.1.** *Let  $u$  is a strong generalized solution of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1. Then the integral equation*

$$\int_{\Omega} u \square v \, dx \, dt = -\lambda \int_{\Omega} f(x, t, u)v \, dx \, dt + \int_{\Omega} Fv \, dx \, dt \quad (5.1)$$

is valid for any test function  $v$  such that

$$v \in C^2(\bar{\Omega}), v|_{\partial\Omega} = v_t|_{\partial\Omega} = v_x|_{\partial\Omega} = 0, \quad (5.2)$$

where  $\square := \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2}$ .

*Proof.* According to the definition of a strong generalized solution  $u$  of (1.1)-(1.4) of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1 there exists a sequence of functions  $u_n \in C^2(\overline{\Omega}) \cap C^0(\overline{\Omega}, \Gamma)$  such that the equalities (2.5), (2.6) are valid and also, as an implication, the equality

$$\lim_{n \rightarrow \infty} \|f(x, t, u_n) - f(x, t, u)\|_{C(\overline{\Omega})} = 0. \quad (5.3)$$

Let  $F_n := L_\lambda u_n$ . Multiply both parts of the equality  $L_\lambda u_n = F_n$  by the function  $v$  and integrate the received equality in the domain  $\Omega$ . By integration by parts of the left side of this equality and due to (5.2) we have

$$\int_{\Omega} u_n \square v \, dx \, dt + \lambda \int_{\Omega} f(x, t, u_n) v \, dx \, dt = \int_{\Omega} F_n v \, dx \, dt. \quad (5.4)$$

In view of (2.5) and (5.3), passing in the equality (5.4) to the limit for  $n \rightarrow \infty$ , we obtain (5.1). The proof is complete.  $\square$

Consider the following condition imposed on function  $f$ :

$$f(x, t, u) \leq -|u|^{\alpha+1}, \quad (x, t, u) \in \overline{\Omega} \times \mathbb{R}, \quad (5.5)$$

where  $\alpha$  is a positive constant. It is easy to verify that when (5.5) is fulfilled, condition (2.2) is violated.

Let us introduce a function  $v_0 = v_0(x, t)$  such that

$$v_0 \in C^2(\overline{\Omega}), v_0|_{\Omega} > 0, v_0|_{\partial\Omega} = v_{0x}|_{\partial\Omega} = v_{0t}|_{\partial\Omega} = 0 \quad (5.6)$$

and

$$\varkappa_0 = \int_{\Omega} \frac{|\square v_0|^{p'}}{|v_0|^{p'-1}} \, dx \, dt < +\infty, \quad p' = 1 + \frac{1}{\alpha}. \quad (5.7)$$

Simple verification shows that for function  $v_0$ , satisfying conditions (5.6) and (5.7), can be chosen as

$$v_0(x, t) = [xt(l-x)(l-t)]^k, \quad (x, t) \in \Omega,$$

for  $k$  a sufficiently large constant.

Due to (5.5) and (5.6) from (5.1), where instead of  $v$  is chosen  $v_0$ , in the case  $\lambda > 0$ , we have

$$\lambda \int_{\Omega} |u|^p v_0 \, dx \, dt \leq \int_{\Omega} |u| |\square v_0| \, dx \, dt - \int_{\Omega} F v_0 \, dx \, dt, \quad p = \alpha + 1. \quad (5.8)$$

**Theorem 5.2.** *Let  $f \in C(\overline{\Omega} \times \mathbb{R})$  satisfy (5.5), and  $F = \gamma F^0$ , where  $F^0 \in C(\overline{\Omega})$ ,  $F^0 \geq 0$  and  $F^0 \neq 0$ . The functions  $\varphi, \psi$  satisfy the conditions from Definition 1.1. Then for  $\lambda > 0$  there exists the number  $\gamma_0 = \gamma_0(F^0, \alpha, \lambda) > 0$ , such that for  $\gamma > \gamma_0$ , problem (1.1)-(1.4) does not have a strong generalized solution of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1.*

*Proof.* If in the Young's inequality with the parameter  $\epsilon > 0$ ,

$$ab < \frac{\epsilon}{p} a^p + \frac{1}{p' \epsilon^{p'-1}} b^{p'}; \quad a, b \geq 0, \frac{1}{p} + \frac{1}{p'} = 1, p = \alpha + 1 > 1$$

we take  $a = |u| v_0^{\frac{1}{p}}$ ,  $b = \frac{|\square v_0|}{v_0^{\frac{1}{p'}}$ , then, since  $\frac{p'}{p} = p' - 1$ , we obtain

$$|u| |\square v_0| = |u| v_0^{\frac{1}{p}} \frac{|\square v_0|}{v_0^{\frac{1}{p'}}} \leq \frac{\epsilon}{p} |u|^p v_0 + \frac{1}{p' \epsilon^{p'-1}} \frac{|\square v_0|^{p'}}{v_0^{p'-1}}. \quad (5.9)$$

Since  $F = \gamma F^0$  and due to (5.9), from (5.8) it follows that

$$\left(\lambda - \frac{\epsilon}{p}\right) \int_{\Omega} |u|^p v_0 \, dx \, dt \leq \frac{1}{p' \epsilon^{p'-1}} \int_{\Omega} \frac{|\square v_0|^{p'}}{v_0^{p'-1}} \, dx \, dt - \gamma \int_{\Omega} F^0 v_0 \, dx \, dt,$$

whence for  $\epsilon < \lambda p$ , we obtain

$$\int_{\Omega} |u|^p v_0 \, dx \, dt \leq \frac{p}{(\lambda p - \epsilon) p' \epsilon^{p'-1}} \int_{\Omega} \frac{|\square v_0|^{p'}}{v_0^{p'-1}} \, dx \, dt - \frac{p\gamma}{\lambda p - \epsilon} \int_{\Omega} F^0 v_0 \, dx \, dt. \quad (5.10)$$

Taking into account that  $p' = \frac{p}{p-1}$ ,  $p = \frac{p'}{p'-1}$  and

$$\min_{0 < \epsilon < \lambda p} \frac{p}{(\lambda p - \epsilon) p' \epsilon^{p'-1}} = \frac{1}{\lambda p},$$

which is achieved at  $\epsilon = \lambda$ , from (5.10) it follows that

$$\int_{\Omega} |u|^p v_0 \, dx \, dt \leq \frac{1}{\lambda p'} \int_{\Omega} \frac{|\square v_0|^{p'}}{v_0^{p'-1}} \, dx \, dt - \frac{p'\gamma}{\lambda} \int_{\Omega} F^0 v_0 \, dx \, dt. \quad (5.11)$$

In view of the conditions imposed on function  $F^0$  and  $v_0|_{\Omega} > 0$  we have

$$0 < \mathfrak{a}_1 := \int_{\Omega} F^0 v_0 \, dx \, dt < +\infty. \quad (5.12)$$

Denoting the right part of the inequality (5.11) by  $\chi = \chi(\gamma)$ , which is a linear function with respect to the parameter  $\gamma$ , from (5.7) and (5.12) we have

$$\chi(\gamma) \begin{cases} < 0 & \text{for } \gamma > \gamma_0 \\ > 0 & \text{for } \gamma < \gamma_0, \end{cases} \quad (5.13)$$

where

$$\chi(\gamma) = \frac{\mathfrak{a}_0}{\lambda p'} - \frac{p'\gamma}{\lambda} \mathfrak{a}_1, \quad \gamma_0 = \frac{\lambda \mathfrak{a}_0}{\lambda p' p' \mathfrak{a}_1}.$$

There remains only to note that the left-hand side of (5.11) is nonnegative, whereas the right-hand side, due to (5.13), is negative for  $\gamma > \gamma_0$ . Thus, for  $\gamma > \gamma_0$ , problem (1.1)-(1.4) does not have a strong generalized solution of the class  $C$  in the domain  $\Omega$  in the sense of Definition 1.1. The proof is complete.  $\square$

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