

STABILIZATION OF SOLUTIONS FOR SEMILINEAR PARABOLIC SYSTEMS AS $|x| \rightarrow \infty$

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ABSTRACT. We prove that solutions of the Cauchy problem for semilinear parabolic systems converge to solutions of the Cauchy problem for a corresponding systems of ordinary differential equations, as $|x| \rightarrow \infty$.

1. INTRODUCTION

In this paper we consider the Cauchy problem for the system of semilinear parabolic equations

$$\begin{aligned} u_{1t} &= a_1^2 \Delta u_1 + f_1(x, t, u_1, \dots, u_k), \\ &\dots \\ u_{kt} &= a_k^2 \Delta u_k + f_k(x, t, u_1, \dots, u_k), \end{aligned} \tag{1.1}$$

subject to the initial conditions

$$u_1(x, 0) = \varphi_1(x), \dots, u_k(x, 0) = \varphi_k(x), \tag{1.2}$$

where $x \in \mathbb{R}^n$, $n \geq 1$, $0 < t < T_0$, $T_0 \leq \infty$. Put $S_T = \mathbb{R}^n \times [0, T)$, $\mathbb{R}_+^k = \{x \in \mathbb{R}^k : x_i \geq 0, i = 1, \dots, k\}$. We assume that the data of problem (1.1)-(1.2) satisfy the following conditions:

$$f_i(x, t, u_1, \dots, u_k), i = 1, \dots, k \text{ are defined and locally Hölder continuous functions in } \mathbb{R}^n \times [0, T_0) \times \mathbb{R}_+^k \text{ and } \varphi_i(x), i = 1, \dots, k \text{ are continuous functions in } \mathbb{R}^n; \tag{1.3}$$

$$f_i(x, t, u_1, \dots, u_k), i = 1, \dots, k \text{ do not decrease in } u_1, \dots, u_k; \tag{1.4}$$

$$f_i(x, t, u_1, \dots, u_k) \rightarrow \bar{f}_i(t, u_1, \dots, u_k), i = 1, \dots, k, \text{ as } |x| \rightarrow \infty \text{ uniformly on any bounded subset of } [0, T_0) \times \mathbb{R}_+^k; \tag{1.5}$$

$$0 \leq f_i(x, t, u_1, \dots, u_k) \leq \bar{f}_i(t, u_1, \dots, u_k), i = 1, \dots, k; \tag{1.6}$$

$$0 \leq \varphi_i(x) \leq c_i, \lim_{|x| \rightarrow \infty} \varphi_i(x) = c_i, c_i \geq 0, i = 1, \dots, k. \tag{1.7}$$

The above assumptions are satisfied, in particular, for large class problems (1.1)-(1.2), whose solutions exist only on a finite time interval. Note also that the solution of (1.1)-(1.2) may not be unique.

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Let us consider the Cauchy problem for the system of ordinary differential equations

$$\begin{aligned} g_1' &= \bar{f}_1(t, g_1, \dots, g_k), \\ &\dots \\ g_k' &= \bar{f}_k(t, g_1, \dots, g_k), \end{aligned} \quad (1.8)$$

subject to the initial conditions

$$g_1(0) = c_1, \dots, g_k(0) = c_k. \quad (1.9)$$

We suppose that the minimal nonnegative solution $g_i(t)$, $i = 1, \dots, k$, of (1.8)-(1.9) exists on $[0, T_0)$. The main result of the paper is the following theorem.

Theorem 1.1. *Let $u_i(x, t)$ be the minimal nonnegative solution of the problem (1.1)-(1.2). Then*

$$u_i(x, t) \rightarrow g_i(t), \quad i = 1, \dots, k, \quad \text{as } |x| \rightarrow \infty \quad (1.10)$$

uniformly for $t \in [0, T]$, ($T < T_0$).

The behavior of solutions of parabolic equations as $|x| \rightarrow \infty$ has been investigated by several authors. The case of one semilinear parabolic equation on half line has been considered in [1, 5] for nonlinearities $f(x, t, u) = u^p$ and $f(x, t, u) = \exp u$. The same problem with general nonlinearity $f(x, t, u)$ has been investigated in [4]. The behavior of solutions of nonlinear parabolic equations for the Cauchy problem as $|x| \rightarrow \infty$ has been analyzed in [2, 3, 6, 7].

The plan of this paper is as follows. In the next section, the existence of a minimal solution for the problem (1.1)-(1.2) is proved. The proof of Theorem 1.1 is given in Section 3.

2. EXISTENCE OF A MINIMAL SOLUTION

We prove the existence of a minimal solution for (1.1)-(1.2). It is well known that (1.1)-(1.2) is equivalent to the system

$$\begin{aligned} u_1(x, t) &= \int_{\mathbb{R}^n} E_1(x - y, t) \varphi_1(y) dy \\ &\quad + \int_0^t \int_{\mathbb{R}^n} E_1(x - y, t - \tau) f_1(y, \tau, u_1, \dots, u_k) dy d\tau, \\ &\quad \dots \\ u_k(x, t) &= \int_{\mathbb{R}^n} E_k(x - y, t) \varphi_k(y) dy \\ &\quad + \int_0^t \int_{\mathbb{R}^n} E_k(x - y, t - \tau) f_k(y, \tau, u_1, \dots, u_k) dy d\tau, \end{aligned} \quad (2.1)$$

where $E_i(x, t) = (2a_i\sqrt{\pi t})^{-n} \exp(-|x|^2/[4a_i^2t])$, $i = 1, \dots, k$, are the fundamental solutions of the correspondent heat equations.

Let $u_{i0}(x, t) \equiv 0$, $i = 1, \dots, k$. We define sequences of functions $u_{im}(x, t)$, $i = 1, \dots, k$, $m \in \mathbb{N}$, the following way

$$\begin{aligned} u_{im}(x, t) &= \int_{\mathbb{R}^n} E_i(x - y, t) \varphi_i(y) dy \\ &\quad + \int_0^t \int_{\mathbb{R}^n} E_i(x - y, t - \tau) f_i(y, \tau, u_{1(m-1)}, \dots, u_{k(m-1)}) dy d\tau. \end{aligned} \quad (2.2)$$

Obviously, the functions $g_i(t)$, $i = 1, \dots, k$, satisfy the integral equations

$$g_i(t) = \int_{\mathbb{R}^n} E_i(x-y, t) c_i dy + \int_0^t \int_{\mathbb{R}^n} E_i(x-y, t-\tau) \bar{f}_i(\tau, g_1, \dots, g_k) dy d\tau. \quad (2.3)$$

Using (1.4), (1.6), (2.2) and (2.3), we have

$$0 \leq u_{i(m-1)}(x, t) \leq u_{im}(x, t) \leq g_i(t), \quad i = 1, \dots, k, \quad m \in \mathbb{N}. \quad (2.4)$$

By the Lebesgue theorem, and from (2.2) and (2.4), we obtain that the sequences $u_{im}(x, t)$ converge to functions $u_i(x, t)$ that satisfy (2.1), which means, ones satisfy the problem (1.1)-(1.2). Let $v_i(x, t)$, $i = 1, \dots, k$, be any other solution of (1.1)-(1.2). By induction on m it is easy to prove that $u_{im}(x, t) \leq v_i(x, t)$, $i = 1, \dots, k$, $m \in \mathbb{N}$. Therefore, $u_i(x, t)$, $i = 1, \dots, k$, is the minimal nonnegative solution of this problem. We have proved the following statement.

Theorem 2.1. *There exists a minimal nonnegative solution $u_i(x, t)$, $i = 1, \dots, k$, of the problem (1.1)-(1.2) in S_{T_0} that satisfies the inequalities*

$$0 \leq u_{im}(x, t) \leq u_i(x, t) \leq g_i(t), \quad (x, t) \in S_{T_0}, \quad i = 1, \dots, k, \quad m \in \mathbb{N}. \quad (2.5)$$

3. BEHAVIOR OF A MINIMAL SOLUTION AS $|x| \rightarrow \infty$

We show that for the minimal nonnegative solution of (1.1)-(1.2), property (1.10) is satisfied. We define sequences of functions $g_{im}(t)$, $i = 1, \dots, k$, $m = 0, 1, \dots$, as follows

$$g_{i0}(t) \equiv 0, \quad g_{im}(t) = \int_0^t \bar{f}_i(\tau, g_{1(m-1)}, \dots, g_{k(m-1)}) d\tau + c_i, \quad i = 1, \dots, k, \quad m \in \mathbb{N}. \quad (3.1)$$

Obviously, the sequences $g_{im}(t)$ are monotonically nondecreasing, converging to the minimal nonnegative solution $g_i(t)$, $i = 1, \dots, k$, of problem (1.8)-(1.9) on any interval $[0, T]$, ($T < T_0$), and

$$g_{im}(t) \leq g_i(t), \quad i = 1, \dots, k, \quad m \in \mathbb{N}. \quad (3.2)$$

According to the Dini criterion on uniform convergence of functional sequences, we have

$$g_{im}(t) \rightarrow g_i(t), \quad i = 1, \dots, k, \quad \text{as } m \rightarrow \infty \text{ uniformly on } [0, T]. \quad (3.3)$$

It is easy to prove that $g_{im}(t)$, $i = 1, \dots, k$, $m \in \mathbb{N}$, satisfy the following equations

$$g_{im}(t) = \int_0^t \int_{\mathbb{R}^n} E_i(x-y, t-\tau) \bar{f}_i(\tau, g_{1(m-1)}, \dots, g_{k(m-1)}) dy d\tau + c_i. \quad (3.4)$$

Now we prove an auxiliary lemma.

Lemma 3.1. *For any $\delta > 0$, $0 < T < T_0$, $i = 1, \dots, k$, and $m \geq 0$ there exists a constant p such that if $|x| > p$ and $0 \leq t \leq T$, then*

$$|u_{im}(x, t) - g_{im}(x, t)| < \delta. \quad (3.5)$$

Proof. We use induction on m . It is obviously that $u_{i0}(x, t) - g_{i0}(t) = 0$, $i = 1, \dots, k$. We assume that (3.5) holds for $m = l$, and we shall prove the inequality for $m = l+1$. By the induction assumption, for any $\varepsilon_1 > 0$ and $0 < T < T_0$ there exists p_1 such that

$$|u_{il}(x, t) - g_{il}(t)| < \varepsilon_1, \quad i = 1, \dots, k, \quad (3.6)$$

if $|x| > p_1$ and $0 \leq t \leq T$. Put $B(q) = \{x \in \mathbb{R}^n : |x| \leq q\}$. From (2.2) and (3.4), we have

$$\begin{aligned}
 & |u_{i(t+1)} - g_{i(t+1)}| \\
 & \leq \left| \int_0^t \int_{B(q)} E_i(x-y, t-\tau) (f_i(y, \tau, u_{1l}, \dots, u_{kl}) - \bar{f}_i(\tau, g_{1l}, \dots, g_{kl})) dy d\tau \right| \\
 & \quad + \left| \int_0^t \int_{\mathbb{R}^n \setminus B(q)} E_i(x-y, t-\tau) (f_i(y, \tau, u_{1l}, \dots, u_{kl}) - \bar{f}_i(\tau, u_{1l}, \dots, u_{kl})) dy d\tau \right| \\
 & \quad + \left| \int_0^t \int_{\mathbb{R}^n \setminus B(q)} E_i(x-y, t-\tau) (\bar{f}_i(\tau, u_{1l}, \dots, u_{kl}) - \bar{f}_i(\tau, g_{1l}, \dots, g_{kl})) dy d\tau \right| \\
 & \quad + \left| \int_{B(q)} E_i(x-y, t) (\varphi_i(y) - c_i) dy \right| + \left| \int_{\mathbb{R}^n \setminus B(q)} E_i(x-y, t) (\varphi_i(y) - c_i) dy \right|,
 \end{aligned} \tag{3.7}$$

where q will be choose later. We denote by I_j , $j = 1, \dots, 5$ the integrals from the right-hand side of (3.7), respectively. Obviously, $\bar{f}_i(t, u_1, \dots, u_k)$, $i = 1, \dots, k$, are uniformly continuous on any compact subset of $[0, T] \times \mathbb{R}_+^k$. Using this and (1.5), (1.7), (2.4), (3.2), (3.6) for suitable ε_1 and q , we get

$$|I_2| + |I_3| + |I_5| < \delta/2 \quad \text{if } |x| > p_2 \tag{3.8}$$

for some p_2 . Since $E_i(x-y, t) \rightarrow 0$ as $|x| \rightarrow \infty$ uniformly on $[0, T] \times B(q)$, we have

$$|I_1| + |I_4| < \delta/2 \quad \text{if } |x| > p_3 \tag{3.9}$$

for some p_3 . Now (3.5) follows from (3.8), (3.9). \square

Proof of Theorem 1.1. We fix a positive ε . From Lemma 3.1 and (3.3), for suitable m and q , we have

$$|u_{im}(x, t) - g_i(t)| \leq |u_{im}(x, t) - g_{im}(t)| + |g_{im}(t) - g_i(t)| < \varepsilon, \quad i = 1, \dots, k, \tag{3.10}$$

if $|x| > q$ and $0 \leq t \leq T$. From (2.5) and (3.10) we obtain

$$g_i(t) - \varepsilon \leq u_{im}(x, t) \leq u_i(x, t) \leq g_i(t), \quad i = 1, \dots, k,$$

for $|x| > q$ and $0 \leq t \leq T$. The statement of the theorem follows immediately from these arguments. \square

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