

**SOLVABILITY OF CHARACTERISTIC BOUNDARY-VALUE  
PROBLEMS FOR NONLINEAR EQUATIONS WITH ITERATED  
WAVE OPERATOR IN THE PRINCIPAL PART**

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ABSTRACT. A characteristic boundary-value problem for a hyperbolic equation with power nonlinearity and iterated wave operator in the principal part is considered in a conical domain. Depending on the exponent of nonlinearity and spatial dimensionality of the equation, the existence and uniqueness of the solution of a boundary-value problem is established. The non-solvability of this problem is also considered here.

1. INTRODUCTION

In the Euclidean space  $\mathbb{R}^{n+1}$  of independent variables  $x_1, x_2, \dots, x_n, t$ , consider the nonlinear equation

$$L_\lambda u := \square^2 u = \lambda f(u) + F, \quad (1.1)$$

where  $\lambda$  is a given real constant,  $f: \mathbb{R} \rightarrow \mathbb{R}$  is a given continuous nonlinear function,  $f(0) = 0$ ,  $F$  is a given, and  $u$  is an unknown real functions, and for  $n \geq 2$ ,

$$\square = \frac{\partial^2}{\partial t^2} - \sum_{i=1}^n \frac{\partial^2}{\partial x_i^2}.$$

Let  $D_T: |x| < t < T - |x|$  be a domain, which is the intersection of the light cone of future  $K_O^+: t > |x|$  with the apex in the origin  $O(0, 0, \dots, 0)$  and light cone of past  $K_A^-: t < T - |x|$  with apex in point  $A(0, \dots, 0, T)$ ,  $T = \text{const} > 0$ .

For equation (1.1) consider the boundary-value problem on determination of its solution  $u(x_1, \dots, x_n, t)$  in domain  $D_T$  with the boundary condition

$$u|_{\partial D_T} = 0. \quad (1.2)$$

It should be noted that for nonlinear hyperbolic equations the local or global solvability of the Cauchy problem with initial conditions for  $t = 0$  and mixed problems has been studied in numerous publications; see, [2, 4, 5, 8, 9, 12, 13, 14, 15, 16, 17, 18, 25, 27, 28, 29, 30, 32, 33, 34].

Regarding the nonlinear wave equation  $\square u = \lambda f(u) + F$ , we have the following results: The characteristic problem in the light cone of future  $K_O^+: t > |x|$ , with

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boundary condition  $u|_{\partial K_O^+} = g$ , in the linear case with  $\lambda = 0$ , is well-posed and has global solvability in some appropriate function spaces; see [1, 3, 6, 10, 26]. Meanwhile, the nonlinear case, when  $f(u)$  has exponential nature and  $\lambda \neq 0$ , has been considered in [19, 20, 21].

Assume  $\dot{C}^k(\bar{D}_T, \partial D_T) = \{u \in C^k(\bar{D}_T) : u|_{\partial D_T} = 0\}$ ,  $k \geq 1$ . Let  $u \in \dot{C}^4(\bar{D}_T, \partial D_T)$  be a classical solution of problem (1.1)-(1.2). Multiplying the both parts of (1.1) by an arbitrary function  $\phi \in \dot{C}^2(\bar{D}_T, \partial D_T)$  and integrating obtained equation by parts in domain  $D_T$  we obtain

$$\int_{D_T} \square u \square \phi \, dx \, dt = \lambda \int_{D_T} f(u) \phi \, dx \, dt + \int_{D_T} F \phi \, dx \, dt. \quad (1.3)$$

Here we used the equality

$$\int_{D_T} \square u \square \phi \, dx \, dt = \int_{\partial D_T} \frac{\partial \phi}{\partial N} \square u \, ds - \int_{\partial D_T} \phi \frac{\partial}{\partial N} \square u \, ds + \int_{D_T} \phi \square^2 u \, dx \, dt$$

and the fact that since  $\partial D_T$  is characteristic manifold, then derivative on the conormal

$$\frac{\partial}{\partial N} = \gamma_{n+1} \frac{\partial}{\partial t} - \sum_{i=1}^n \gamma_i \frac{\partial}{\partial x_i},$$

where  $\gamma = (\gamma_1, \dots, \gamma_n, \gamma_{n+1})$  is the unit vector of external normal relative to  $\partial D_T$ , is an inner differential operator on characteristic manifold  $\partial D_T$  and, thus, if  $v \in \dot{C}^1(\bar{D}_T, \partial D_T)$ , then  $\frac{\partial v}{\partial N}|_{\partial D_T} = 0$ .

Let us introduce the Hilbert space  $\dot{W}_{2,\square}^1(D_T)$  as a completion with respect to the norm

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 = \int_{D_T} [u^2 + (\frac{\partial u}{\partial t})^2 + \sum_{i=1}^n (\frac{\partial u}{\partial x_i})^2 + (\square u)^2] \, dx \, dt \quad (1.4)$$

of classical space  $\dot{C}^2(\bar{D}_T, \partial D_T)$ . It follows from (1.4) that if  $u \in \dot{W}_{2,\square}^1(D_T)$ , then  $u \in \dot{W}_2^1(D_T)$  and  $\square u \in L_2(D_T)$ . Here  $W_2^1(D_T)$  is the known Sobolev space [24, p. 56], consisting of elements from  $L_2(D_T)$ , which have first order generalized derivatives in  $L_2(D_T)$ , and  $\dot{W}_2^1(D_T) = \{u \in W_2^1(D_T) : u|_{\partial D_T} = 0\}$ , where equality  $u|_{\partial D_T} = 0$  should be understood in the sense of the theory of trace [24, p. 70].

Let us assume (1.3) as the basis of determination of generalized solution of problem (1.1)-(1.2).

**Definition 1.1.** Let  $F \in L_2(D_T)$ . We call function  $u \in \dot{W}_{2,\square}^1(D_T)$  a weak generalized solution of problem (1.1)-(1.2) if  $f(u) \in L_2(D_T)$  and for any function  $\phi \in \dot{W}_{2,\square}^1(D_T)$  it is valid integral equality (1.3); i.e.

$$\int_{D_T} \square u \square \phi \, dx \, dt = \lambda \int_{D_T} f(u) \phi \, dx \, dt + \int_{D_T} F \phi \, dx \, dt \quad \forall \phi \in \dot{W}_{2,\square}^1(D_T). \quad (1.5)$$

It is easy to verify that if the solution  $u$  of problem (1.1)-(1.2) in the sense of the above definition belongs to the class  $C^4(\bar{D}_T)$ , then it will be a classical solution of this problem.

2. SOLVABILITY OF (1.1)-(1.2) WITH  $f(u) = |u|^\alpha \operatorname{sgn} u$ 

Assume that for a positive constant  $\alpha \neq 1$ , the nonlinear function  $f$  in (1.1) has the form

$$f(u) = |u|^\alpha \operatorname{sgn} u. \quad (2.1)$$

Then in accordance to (2.1), equation (1.1) and (1.5) take the form

$$L_\lambda u := \square^2 u = \lambda |u|^\alpha \operatorname{sgn} u + F \quad (2.2)$$

and

$$\int_{D_T} \square u \square \phi \, dx \, dt = \lambda \int_{D_T} \phi |u|^\alpha \operatorname{sgn} u \, dx \, dt + \int_{D_T} F \phi \, dx \, dt, \quad \forall \phi \in \dot{W}_{2,\square}^1(D_T). \quad (2.3)$$

**Lemma 2.1.** *With the norm of the space  $\dot{W}_{2,\square}^1(D_T)$  given in (1.4),*

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)} \leq c \|\square u\|_{L_2(D_T)} \quad \forall u \in \dot{W}_{2,\square}^1(D_T) \quad (2.4)$$

where  $c$  is positive constant independent on  $u$ .

*Proof.* Since the space  $\dot{C}^2(\overline{D}_T, \partial D_T)$  is the dense subspace of space  $\dot{W}_{2,\square}^1(D_T)$  it is sufficient to prove that for all  $u \in \text{mathaccent"7017}C^2(\overline{D}_T, \partial D_T)$ ,

$$\|u\|_{W_{2,\square}^1(D_{T/2}^+)}^2 \leq c^2 \|\square u\|_{L_2(D_{T/2}^+)}^2, \quad \|u\|_{W_{2,\square}^1(D_{T/2}^-)}^2 \leq c^2 \|\square u\|_{L_2(D_{T/2}^-)}^2, \quad (2.5)$$

where  $D_{T/2}^+ = D_T \cap \{t < T/2\}$ ,  $D_{T/2}^- = D_T \cap \{t > T/2\}$  and the norm  $\|\cdot\|_{W_{2,\square}^1(D_{T/2}^\pm)}$  is given by (1.4) with  $D_{T/2}^\pm$  instead of  $D_T$ .

Let us prove the first inequality of (2.5), the second inequality can be proved in the same way. Assume  $\Omega_\tau := \overline{D}_{T/2}^+ \cap \{t = \tau\}$ ,  $D_\tau^+ = D_{T/2}^+ \cap \{t < \tau\}$ ,  $S_\tau^+ = \{(x, t) \in \partial D_\tau^+ : t = |x|\}$ ,  $0 < \tau \leq T/2$  and  $\gamma = (\gamma_1, \dots, \gamma_n, \gamma_{n+1})$  be the unit vector of outer normal relative to  $\partial D_\tau^+$ . For  $u \in C^{2,0}(\overline{D}_T, \partial D_T)$ , taking into account equalities  $u|_{S_\tau^+} = 0$ ,  $\Omega_\tau = \partial D_\tau^+ \cap \{t = \tau\}$  and  $\gamma|_{\Omega_\tau} = (0, \dots, 0, 1)$ , integrating by parts it is easy to obtain

$$\begin{aligned} \int_{D_\tau^+} \frac{\partial^2 u}{\partial t^2} \frac{\partial u}{\partial t} \, dx \, dt &= \frac{1}{2} \int_{D_\tau^+} \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial t} \right)^2 \, dx \, dt = \frac{1}{2} \int_{\partial D_\tau^+} \left( \frac{\partial u}{\partial t} \right)^2 \gamma_{n+1} \, ds \\ &= \frac{1}{2} \int_{\Omega_\tau} \left( \frac{\partial u}{\partial t} \right)^2 \, dx + \frac{1}{2} \int_{S_\tau^+} \left( \frac{\partial u}{\partial t} \right)^2 \gamma_{n+1} \, ds, \quad \tau \leq T/2, \end{aligned} \quad (2.6)$$

$$\begin{aligned} \int_{D_\tau^+} \frac{\partial^2 u}{\partial x_i^2} \frac{\partial u}{\partial t} \, dx \, dt &= \int_{\partial D_\tau^+} \frac{\partial u}{\partial x_i} \frac{\partial u}{\partial t} \gamma_i \, ds - \frac{1}{2} \int_{D_\tau^+} \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial x_i} \right)^2 \, dx \, dt \\ &= \int_{\partial D_\tau^+} \frac{\partial u}{\partial x_i} \frac{\partial u}{\partial t} \gamma_i \, ds - \frac{1}{2} \int_{\partial D_\tau^+} \left( \frac{\partial u}{\partial x_i} \right)^2 \gamma_{n+1} \, ds \\ &= \int_{\partial D_\tau^+} \frac{\partial u}{\partial x_i} \frac{\partial u}{\partial t} \gamma_i \, ds - \frac{1}{2} \int_{S_\tau^+} \left( \frac{\partial u}{\partial x_i} \right)^2 \gamma_{n+1} \, ds - \frac{1}{2} \int_{\Omega_\tau} \left( \frac{\partial u}{\partial x_i} \right)^2 \, dx, \end{aligned} \quad (2.7)$$

with  $\tau \leq T/2$ . It follows from (2.6) and (2.7) that

$$\begin{aligned} & \int_{D_\tau^+} \square u \frac{\partial u}{\partial t} dx dt \\ &= \int_{S_\tau^+} \frac{1}{2\gamma_{n+1}} \left[ \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \gamma_{n+1} - \frac{\partial u}{\partial t} \gamma_i \right)^2 + \left( \frac{\partial u}{\partial t} \right)^2 \left( \gamma_{n+1}^2 - \sum_{j=1}^n \gamma_j^2 \right) \right] ds \\ &+ \frac{1}{2} \int_{\Omega_\tau} \left[ \left( \frac{\partial u}{\partial t} \right)^2 + \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \right)^2 \right] dx, \quad \tau \leq T. \end{aligned} \quad (2.8)$$

Since  $u|_{S_\tau^+} = 0$  and operator  $(\gamma_{n+1} \frac{\partial}{\partial x_i} - \gamma_i \frac{\partial}{\partial t})$ ,  $1 \leq i \leq n$ , is an inner differential operator on  $S_\tau^+$ , then we have the equalities

$$\left( \frac{\partial u}{\partial x_i} \gamma_{n+1} - \frac{\partial u}{\partial t} \gamma_i \right) \Big|_{S_\tau^+} = 0, \quad i = 1, \dots, n. \quad (2.9)$$

Therefore, taking into account that  $\gamma_{n+1}^2 - \sum_{j=1}^n \gamma_j^2 = 0$  on the characteristic manifold  $S_\tau^+$ , in view of (2.8) and (2.9), we have

$$\int_{\Omega_\tau} \left[ \left( \frac{\partial u}{\partial t} \right)^2 + \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \right)^2 \right] dx = 2 \int_{D_\tau^+} \square u \frac{\partial u}{\partial t} dx dt, \quad \tau \leq T/2. \quad (2.10)$$

Assuming  $w(\delta) = \int_{\Omega_\delta} \left[ \left( \frac{\partial u}{\partial t} \right)^2 + \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \right)^2 \right] dx$ , and using inequality  $2 \square u \frac{\partial u}{\partial t} \leq \varepsilon \left( \frac{\partial u}{\partial t} \right)^2 + \frac{1}{\varepsilon} |\square u|^2$ , which is valid for any positive  $\varepsilon$ , from (2.10) we obtain

$$w(\delta) \leq \varepsilon \int_0^\delta w(\sigma) d\sigma + \frac{1}{\varepsilon} \|\square\|_{L_2(D_\delta^+)}^2, \quad 0 < \delta \leq T/2. \quad (2.11)$$

From (2.11), taking into account that value  $\|\square\|_{L_2(D_\delta^+)}^2$  as a function of  $\delta$  is non-decreasing, in view of Gronwall's lemma [11, p. 13] it follows that

$$w(\delta) \leq \frac{1}{\varepsilon} \|\square\|_{L_2(D_\delta^+)}^2 \exp \delta \varepsilon.$$

Hence, taking into account the fact that  $\inf_{\varepsilon > 0} \frac{1}{\varepsilon} \exp \delta \varepsilon = e\delta$  and it is reached at  $\varepsilon = \frac{1}{\delta}$ , we obtain

$$w(\delta) \leq e\delta \|\square\|_{L_2(D_\delta^+)}^2, \quad 0 < \delta \leq T/2.$$

From (2), in turn, it follows that

$$\int_{D_{T/2}^+} \left[ \left( \frac{\partial u}{\partial t} \right)^2 + \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \right)^2 \right] dx dt = \int_0^{T/2} w(\delta) d\delta \leq \frac{e}{8} T^2 \|\square u\|_{L_2(D_{T/2}^+)}^2. \quad (2.12)$$

Using the equalities  $u|_{S_{T/2}} = 0$  and  $u(x, t) = \int_{|x|}^t \frac{\partial u(x, \tau)}{\partial \tau} d\tau$ ,  $(x, t) \in \overline{D}_{T/2}^+$ , which are valid for any function  $u \in C^{2,0}(\overline{D}_T, \partial D_T)$ , by standard reasoning [24, p. 63] we easily obtain

$$\int_{D_{T/2}^+} u^2(x, t) dx dt \leq \frac{1}{4} T^2 \int_{D_{T/2}^+} \left( \frac{\partial u}{\partial t} \right)^2 dx dt. \quad (2.13)$$

By virtue of (2.12) and (2.13), we have

$$\begin{aligned} \|u\|_{\dot{W}_{2,\square}^1(D_{T/2}^+)}^2 &= \int_{D_{T/2}^+} \left[ u^2 + \left( \frac{\partial u}{\partial t} \right)^2 + \sum_{i=1}^n \left( \frac{\partial u}{\partial x_i} \right)^2 + (\square u)^2 \right] dx dt \\ &\leq \left( 1 + \frac{e}{8} T^2 + \frac{e}{32} T^4 \right) \|\square\|_{L_2(D_{T/2}^+)}^2, \end{aligned}$$

whence it follows the first inequality of (2.5) with constant  $c^2 = 1 + \frac{e}{8} T^2 + \frac{e}{32} T^4$ . The proof is complete.  $\square$

**Lemma 2.2.** *Assume  $F \in L_2(D_T)$ ,  $0 < \alpha < 1$ , and in the case when  $\alpha > 1$  additionally require that  $\lambda < 0$ . Then for a weak generalized solution  $u \in \dot{W}_{2,\square}^1(D_T)$  of (1.1)-(1.2) in the case with nonlinearity of form (2.1); i.e., problem (2.2)-(1.2) in the sense of integral equality (2.3) with  $|u|^\alpha \in L_2(D_T)$ , it is valid a priori estimate*

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)} \leq c_1 \|F\|_{L_2(D_T)} + c_2 \quad (2.14)$$

with non-negative constants  $c_i(T, \alpha, \lambda)$ ,  $i = 1, 2$ , which do not depend on  $u, F$  and  $c_1 > 0$ .

*Proof.* First let  $\alpha > 1$  and  $\lambda < 0$ . Assuming in (2.3) that  $\phi = u \in \dot{W}_{2,\square}^1(D_T)$  and taking into account (1.4), for any  $\varepsilon > 0$  we have

$$\begin{aligned} \|\square u\|_{L_2(D_T)}^2 &= \int_{D_T} (\square u)^2 dx dt \\ &= \lambda \int_{D_T} |u|^{\alpha+1} dx dt + \int_{D_T} Fu dx dt \\ &\leq \int_{D_T} Fu dx dt \\ &\leq \frac{1}{4\varepsilon} \int_{D_T} F^2 dx dt + \varepsilon \|u\|_{L_2(D_T)}^2 \\ &\leq \frac{1}{4\varepsilon} \|F\|_{L_2(D_T)}^2 + \varepsilon \|u\|_{\dot{W}_{2,\square}^1(D_T)}^2. \end{aligned} \quad (2.15)$$

Due to (2.4) and the above inequality we have

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 \leq c^2 \|\square u\|_{L_2(D_T)}^2 \leq \frac{c^2}{4\varepsilon} \|F\|_{L_2(D_T)}^2 + c^2 \varepsilon \|u\|_{\dot{W}_{2,\square}^1(D_T)}^2,$$

from which for  $\varepsilon = \frac{1}{2c^2} < \frac{1}{c^2}$ , we obtain

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 \leq \frac{c^2}{4\varepsilon(1 - \varepsilon c^2)} \|F\|_{L_2(D_T)}^2 = c^4 \|F\|_{L_2(D_T)}^2.$$

From this inequality in the case  $\alpha > 1$  and  $\lambda < 0$  follows inequality (2.14) with  $c_1 = c^2$  and  $c_2 = 0$ .

Now let  $0 < \alpha < 1$ . Using the known inequality

$$ab \leq \frac{\varepsilon a^p}{p} + \frac{b^q}{q\varepsilon^{q-1}}$$

with parameter  $\varepsilon > 0$  for  $a = |u|^{\alpha+1}$ ,  $b = 1$ ,  $p = \frac{2}{\alpha+1} > 1$ ,  $q = \frac{2}{1-\alpha}$ ,  $\frac{1}{p} + \frac{1}{q} = 1$ , in the same way as for inequality (2.15), we have

$$\begin{aligned}
& \|\square u\|_{L_2(D_T)}^2 \\
&= \int_{D_T} (\square u)^2 dx dt \\
&= \lambda \int_{D_T} |u|^{\alpha+1} dx dt + \int_{D_T} Fu dx dt \\
&\leq |\lambda| \int_{D_T} \left[ \varepsilon \frac{1+\alpha}{2} |u|^2 + \frac{1-\alpha}{2\varepsilon^{q-1}} \right] dx dt + \frac{1}{4\varepsilon} \int_{D_T} F^2 dx dt + \varepsilon \int_{D_T} u^2 dx dt \\
&= \frac{1}{4\varepsilon} \|F\|_{L_2(D_T)}^2 + \varepsilon (|\lambda| \frac{1+\alpha}{2} + 1) \|u\|_{L_2(D_T)}^2 + |\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T.
\end{aligned} \tag{2.16}$$

In view of (1.4) and (2.4) it follows from (2.16) that

$$\begin{aligned}
& \|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 \\
&\leq c^2 \|\square u\|_{L_2(D_T)}^2 \\
&\leq \frac{c^2}{4\varepsilon} \|F\|_{L_2(D_T)}^2 + \varepsilon c^2 (|\lambda| \frac{1+\alpha}{2} + 1) \|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 + c^2 |\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T,
\end{aligned}$$

where  $q = \frac{2}{1-\alpha}$ ; whence for  $\varepsilon = \frac{1}{2} c^{-2} (|\lambda| \frac{1+\alpha}{2} + 1)^{-1}$ ,

$$\begin{aligned}
& \|u\|_{\dot{W}_{2,\square}^1(D_T)}^2 \\
&\leq [1 - \varepsilon c^2 (|\lambda| \frac{1+\alpha}{2} + 1)]^{-1} \left( \frac{c^2}{4\varepsilon} \|F\|_{L_2(D_T)}^2 + c^2 |\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T \right) \\
&= c^4 (|\lambda| \frac{1+\alpha}{2} + 1) \|F\|_{L_2(D_T)}^2 + 2c^2 |\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T.
\end{aligned} \tag{2.17}$$

From (2.17), in the case when  $0 < \alpha < 1$ , follows inequality (2.14) with  $c_1 = c^2 (|\lambda| \frac{1+\alpha}{2} + 1)^{1/2}$  and  $c_2 = c(2|\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T)^{1/2}$ , where  $q = \frac{2}{1-\alpha}$ . The proof is complete.  $\square$

**Remark 2.3.** From the proof of Lemma 2.2 it follows that in estimate (2.14) the constants  $c_1$  and  $c_2$  are equal:

$$\alpha > 1, \quad \lambda < 0: \quad c_1 = c^2, \quad c_2 = 0; \tag{2.18}$$

$$0 < \alpha < 1, \quad -\infty < \lambda < +\infty:$$

$$c_1 = c^2 (|\lambda| \frac{1+\alpha}{2} + 1)^{1/2}, \quad c_2 = c(2|\lambda| \frac{1-\alpha}{2\varepsilon^{q-1}} \text{meas } D_T)^{\frac{1}{2}}, \tag{2.19}$$

where constant  $c = (1 + \frac{\varepsilon}{2} T^2 + \frac{\varepsilon}{2} T^4)^{1/2}$  is taken from estimate (2.4), and  $q = \frac{2}{1-\alpha}$ .

**Remark 2.4.** Below, we will consider a linear problem appropriate for (1.1)-(1.2); i.e., when  $\lambda = 0$ . In this case for  $F \in L_2(D_T)$  it is analogously introduced a concept of the weak generalized solution  $u \in \dot{W}_{2,\square}^1(D_T)$  of this problem, when

$$(u, \phi)_{\square} := \int_{D_T} \square u \square \phi dx dt = \int_{D_T} F \phi dx dt \quad \forall \phi \in \dot{W}_{2,\square}^1(D_T). \tag{2.20}$$

**Remark 2.5.** In view of (1.4) and (2.4), taking into account that

$$\begin{aligned} |(\square u, \square \phi)_{L_2(D_T)}| &= \left| \int_{D_T} \square u \square \phi \, dx \, dt \right| \\ &\leq \|\square u\|_{L_2(D_T)} \|\square \phi\|_{L_2(D_T)} \\ &\leq \|\square u\|_{\dot{W}_{2,\square}^1(D_T)} \|\square \phi\|_{\dot{W}_{2,\square}^1(D_T)}, \end{aligned}$$

the bilinear form

$$(u, \phi)_{\square} := \int_{D_T} \square u \square \phi \, dx \, dt$$

in (2.20) can be considered as a scalar product in the Hilbert space  $\dot{W}_{2,\square}^1(D_T)$ . Therefore, since for  $F \in L_2(D_T)$

$$\left| \int_{D_T} F \phi \, dx \, dt \right| \leq \|F\|_{L_2(D_T)} \|\phi\|_{L_2(D_T)} \leq \|F\|_{L_2(D_T)} \|\phi\|_{\dot{W}_{2,\square}^1(D_T)},$$

then due to the Riesz theorem [7, p. 83] there is unique function  $u$  in the space  $\dot{W}_{2,\square}^1(D_T)$ , which satisfies equality (2.20) for any  $\phi \in \dot{W}_{2,\square}^1(D_T)$  and for the norm of which it is valid estimate

$$\|u\|_{\dot{W}_{2,\square}^1(D_T)} \leq \|F\|_{L_2(D_T)}. \quad (2.21)$$

Thus, introducing notation  $u = L_0^{-1}F$ , we obtain that to the linear problem appropriate to (1.1)-(1.2); i.e., when  $\lambda = 0$ , corresponds the linear, bounded operator

$$L_0^{-1} : L_2(D_T) \rightarrow \dot{W}_{2,\square}^1(D_T),$$

for the norm of which, by (2.21), it is valid the estimate

$$\|L_0^{-1}\|_{L_2(D_T) \rightarrow \dot{W}_{2,\square}^1(D_T)} \leq \|F\|_{L_2(D_T)}. \quad (2.22)$$

Taking into account Definition 1.1 and Remark 2.5, Equality (2.3) and Problem (2.2)-(1.2) can be rewritten in the equivalent form

$$u = L_0^{-1}[\lambda|u|^\alpha \operatorname{sgn} u + F] \quad (2.23)$$

in the Hilbert space  $\dot{W}_{2,\square}^1(D_T)$ .

**Remark 2.6.** The embedding operator  $I : \dot{W}_2^1(D_T) \rightarrow L_q(D_T)$  is a linear continuous compact operator for  $1 < q < \frac{2(n+1)}{n-1}$ , when  $n \geq 2$  [24, p. 81]. At the same time the operator of Nemytskii  $N : L_q(D_T) \rightarrow L_2(D_T)$ , which acts according to the formula  $Nu = \lambda|u|^\alpha \operatorname{sgn} u$ ,  $\alpha > 1$ , is continuous and bounded for  $q \geq 2\alpha$  [22, p. 349], [23, pp. 66, 67]. Thus, if  $1 < \alpha < \frac{n+1}{n-1}$ , then there exists such number  $q$ , that  $1 < 2\alpha \leq q < \frac{2(n+1)}{n-1}$  and hence the operator

$$N_1 = NI : \dot{W}_2^1(D_T) \rightarrow L_2(D_T) \quad (2.24)$$

is continuous and compact operator. In this case since  $u \in \dot{W}_2^1(D_T)$  then it is clear that  $f(u) = |u|^\alpha \operatorname{sgn} u \in L_2(D_T)$ . Further, since in view of (1.4) the space  $\dot{W}_{2,\square}^1(D_T)$  is continuously embedded in the space  $\dot{W}_2^1(D_T)$ , then taking into account (2.24) the operator

$$N_2 = NII_1 : \dot{W}_{2,\square}^1(D_T) \rightarrow L_2(D_T), \quad (2.25)$$

where  $I_1 : \dot{W}_{2,\square}^1(D_T) \rightarrow \dot{W}_2^1(D_T)$  is the embedding operator, continuous and compact for  $1 < \alpha < \frac{n+1}{n-1}$ . For  $0 < \alpha < 1$  operator (2.25) is also continuous and

compact, since according to the Rellich theorem [24, p. 64] the space  $\mathring{W}_2^1(D_T)$  is continuously and compactly embedded into  $L_2(D_T)$ , and the space  $L_2(D_T)$ , in turn, is continuously embedded into  $L_p(D_T)$  for  $p < 2$ .

Let us rewrite equation (2.23) in the form

$$u = Au := L_0^{-1}(N_2u + F), \quad (2.26)$$

where the operator  $N_2 : \mathring{W}_{2,\square}^1(D_T) \rightarrow L_2(D_T)$ , for  $0 < \alpha < \frac{n+1}{n-1}$ ,  $\alpha \neq 1$ , is continuous and compact in view of the Remark 2.6. Then taking into account (2.22) operator  $A : \mathring{W}_{2,\square}^1(D_T) \rightarrow \mathring{W}_{2,\square}^1(D_T)$  in (2.26) is also continuous and compact. At the same time according to a priori estimate (2.14) of the Lemma 2.2, in which the constants  $c_1$  and  $c_2$  are given by equalities (2.18) and (2.19), for any parameter  $\tau \in [0, 1]$  and for any solution  $u \in \mathring{W}_{2,\square}^1(D_T)$  of equation  $u = \tau Au$  with this parameter it is valid a priori estimation (2.14) with constants  $c_1 > 0$  and  $c_2 \geq 0$ , not depending on  $u$ ,  $\tau$  and  $F$ . Therefore, according to the Lere-Schauder theorem [31, p. 375] equation (2.26), and consequently problem (2.2)-(1.2) has at least one weak generalized solution  $u$  in the space  $\mathring{W}_{2,\square}^1(D_T)$ . This is summarized in the following result.

**Theorem 2.7.** *Let  $0 < \alpha < \frac{n+1}{n-1}$ ,  $\alpha \neq 1$ ,  $\lambda \neq 0$  and  $\lambda < 0$  when  $\alpha > 1$ . Then for any  $F \in L_2(D_T)$  problem (2.2)-(1.2) has at least one weak generalized solution  $u \in \mathring{W}_{2,\square}^1(D_T)$ .*

### 3. UNIQUENESS OF SOLUTION FOR (1.1)-(1.2) WHEN $f(u) = |u|^\alpha \operatorname{sgn} u$

Let  $F \in L_2(D_T)$ , and  $u_1, u_2$  be two weak generalized solutions of (2.2)-(1.2) in the space  $\mathring{W}_{2,\square}^1(D_T)$ . According to (2.3),

$$\int_{D_T} \square u_i \square \phi \, dx \, dt = \lambda \int_{D_T} \phi |u_i|^\alpha \operatorname{sgn} u_i \, dx \, dt + \int_{D_T} F \phi \, dx \, dt \quad \forall \phi \in \mathring{W}_{2,\square}^1(D_T) \quad (3.1)$$

and  $|u_i|^\alpha \in L_2(D_T)$ ,  $i = 1, 2$ . For the difference  $v = u_2 - u_1$  from (3.1) it follows that

$$\int_{D_T} \square v \square \phi \, dx \, dt = \lambda \int_{D_T} \phi (|u_2|^\alpha \operatorname{sgn} u_2 - |u_1|^\alpha \operatorname{sgn} u_1) \, dx \, dt \quad \forall \phi \in \mathring{W}_{2,\square}^1(D_T). \quad (3.2)$$

Assuming  $\phi = v \in \mathring{W}_{2,\square}^1(D_T)$  in the above equality, we obtain

$$\int_{D_T} (\square v)^2 \, dx \, dt = \lambda \int_{D_T} (|u_2|^\alpha \operatorname{sgn} u_2 - |u_1|^\alpha \operatorname{sgn} u_1)(u_2 - u_1) \, dx \, dt. \quad (3.3)$$

Let us note that for the finite values of  $u_1$  and  $u_2$  with  $\alpha > 0$  it is valid the inequality

$$(|u_2|^\alpha \operatorname{sgn} u_2 - |u_1|^\alpha \operatorname{sgn} u_1)(u_2 - u_1) \geq 0. \quad (3.4)$$

From (3.3) and inequality (3.4), which is true for almost all points  $(x, t) \in D_T$  with  $u_i \in \mathring{W}_{2,\square}^1(D_T)$ ,  $i = 1, 2$ , in the case when  $\alpha > 0$  and  $\lambda < 0$  it follows that

$$\int_{D_T} (\square v)^2 \, dx \, dt \leq 0,$$

whence, due to (2.4), we obtain  $v = 0$ ; i.e.  $u_1 = u_2$ . This result is summarized in the next theorem.



**Theorem 3.1.** *Let  $\alpha > 0$ ,  $\alpha \neq 1$  and  $\lambda < 0$ . Then for any  $F \in L_2(D_T)$ , Problem (2.2)-(1.2) cannot have more than one generalized solution in  $\dot{W}_{2,\square}^1(D_T)$ .*

The following result follows from Theorems 2.7 and 3.1.

**Theorem 3.2.** *Let  $0 < \alpha < \frac{n+1}{n-1}$ ,  $\alpha \neq 1$  and  $\lambda < 0$ . Then for any  $F \in L_2(D_T)$ , Problem (2.2)-(1.2) has an unique weak generalized solution  $u \in \dot{W}_{2,\square}^1(D_T)$ .*

#### 4. NON-SOLVABILITY OF (1.1)-(1.2) WHEN $f(u) = |u|^\alpha$

Now assume that in (1.1), and therefore in (1.3), that  $f(u) = |u|^\alpha$ ,  $\alpha > 1$ .

**Theorem 4.1.** *Let  $F^0 \in L_2(D_T)$ ,  $\|F^0\|_{L_2(D_T)} \neq 0$ ,  $F^0 \geq 0$ , and  $F = \mu F^0$ ,  $\mu$  is a positive constant. Then when  $f(u) = |u|^\alpha$  with  $\alpha > 1$  and  $\lambda > 0$ , there exists a number  $\mu_0 = \mu_0(F^0, \lambda, \alpha) > 0$  such that for  $\mu > \mu_0$ , problem (1.1)-(1.2) can not have a weak generalized solution in the space  $\dot{W}_{2,\square}^1(D_T)$ .*

*Proof.* Let us assume that there is a solution  $u \in \dot{W}_{2,\square}^1(D_T)$  of problem (1.1)-(1.2) exists for any fixed  $\mu > 0$ . Then (1.5) takes the form

$$\int_{D_T} \square u \square \phi \, dx \, dt = \lambda \int_{D_T} |u|^\alpha \phi \, dx \, dt + \mu \int_{D_T} F^0 \phi \, dx \, dt \quad \forall \phi \in \dot{W}_{2,\square}^1(D_T). \quad (4.1)$$

It is easy to verify that

$$\int_{D_T} \square u \square \phi \, dx \, dt = \int_{D_T} u \square^2 \phi \, dx \, dt \quad \forall \phi \in \dot{C}^4(\overline{D}_T, \partial D_T), \quad (4.2)$$

where  $\dot{C}^4(\overline{D}_T, \partial D_T) = \{u \in C^4(\overline{D}_T) : u|_{\partial D_T} = 0\} \subset \dot{W}_{2,\square}^1(D_T)$ . Indeed, since  $u \in \dot{W}_{2,\square}^1(D_T)$ , and the space  $\dot{C}^2(\overline{D}_T, \partial D_T)$  is dense in  $\dot{W}_{2,\square}^1(D_T)$ , there exists such sequence  $u_k \in \dot{C}^2(\overline{D}_k, \partial D_k)$  that

$$\lim_{k \rightarrow \infty} \|u_k - u\|_{\dot{W}_{2,\square}^1(D_T)} = 0. \quad (4.3)$$

Taking into account that

$$\int_{D_T} \square u_k \square \phi \, dx \, dt = \int_{\partial D_T} \frac{\partial u_k}{\partial N} \square \phi \, ds - \int_{\partial D_T} u_k \frac{\partial}{\partial N} \square \phi \, ds + \int_{D_T} u_k \square^2 \phi \, dx \, dt, \quad (4.4)$$

where the derivative on the conormal  $\frac{\partial}{\partial N} = \gamma_{n+1} \frac{\partial}{\partial t} - \sum_{i=1}^n \gamma_i \frac{\partial}{\partial x_i}$  is an inner differential operator on characteristic manifold  $\partial D_T$ , and, therefore  $\frac{\partial u_k}{\partial N}|_{\partial D_T} = 0$ , since  $u_k|_{\partial D_T} = 0$ , then from (4.4) we obtain

$$\int_{D_T} \square u_k \square \phi \, dx \, dt = \int_{D_T} u_k \square^2 \phi \, dx \, dt, \quad (4.5)$$

where  $\gamma = (\gamma_1, \dots, \gamma_n, \gamma_{n+1})$  is the unit vector of outer normal relative to  $\partial D_T$ . Passing in (4.5) to the limit with  $k \rightarrow \infty$ , in view of (1.4) and (4.3), we obtain (4.2).

Taking into account (4.2) let us rewrite equality (4.1) in the form

$$\lambda \int_{D_T} |u|^\alpha \phi \, dx \, dt = \int_{D_T} u \square^2 \phi \, dx \, dt - \mu \int_{D_T} F^0 \phi \, dx \, dt \quad \forall \phi \in \dot{C}^4(\overline{D}_T, \partial D_T). \quad (4.6)$$

Below we use the method of test functions [22, p. 10-12]. Let us select such a test function  $\phi \in \mathring{C}^4(\overline{D_T}, \partial D_T)$ , that  $\phi|_{D_T} > 0$ . If in Young's inequality with parameter  $\varepsilon > 0$

$$ab \leq \frac{\varepsilon}{\alpha} a^\alpha + \frac{1}{\alpha' \varepsilon^{\alpha'-1}} b^{\alpha'}, \quad a, b \geq 0, \quad \alpha' = \frac{\alpha}{\alpha - 1}$$

we take  $a = |u|\phi^{1/\alpha}$ ,  $b = \frac{|\square^2 \phi|}{\phi^{1/\alpha}}$ , then due to the fact that  $\frac{\alpha'}{\alpha} = \alpha' - 1$ , we have

$$|u \square^2 \phi| = |u| \phi^{1/\alpha} \frac{|\square^2 \phi|}{\phi^{1/\alpha}} \leq \frac{\varepsilon}{\alpha} |u|^\alpha \phi + \frac{1}{\alpha' \varepsilon^{\alpha'-1}} \frac{|\square^2 \phi|^{\alpha'}}{\phi^{\alpha'-1}}. \quad (4.7)$$

By (4.7) and (4.6) we have the inequality

$$\left(\lambda - \frac{\varepsilon}{\alpha}\right) \int_{D_T} |u|^\alpha \phi \, dx \, dt \leq \frac{1}{\alpha' \varepsilon^{\alpha'-1}} \int_{D_T} \frac{|\square^2 \phi|^{\alpha'}}{\phi^{\alpha'-1}} \, dx \, dt - \mu \int_{D_T} F^0 \phi \, dx \, dt;$$

whence for  $\varepsilon < \lambda \alpha$  we obtain

$$\int_{D_T} |u|^\alpha \phi \, dx \, dt \leq \frac{\alpha}{(\lambda \alpha - \varepsilon) \alpha' \varepsilon^{\alpha'-1}} \int_{D_T} \frac{|\square^2 \phi|^{\alpha'}}{\phi^{\alpha'-1}} \, dx \, dt - \frac{\alpha \mu}{\lambda \alpha - \varepsilon} \int_{D_T} F^0 \phi \, dx \, dt. \quad (4.8)$$

Taking into account the equalities  $\alpha' = \frac{\alpha}{\alpha-1}$ ,  $\alpha = \frac{\alpha'}{\alpha'-1}$ , and

$$\min_{0 < \varepsilon < \lambda \alpha} \frac{\alpha}{(\lambda \alpha - \varepsilon) \alpha' \varepsilon^{\alpha'-1}} = \frac{1}{\lambda^{\alpha'}},$$

which is reached at  $\varepsilon = \lambda$ , it follows from (4.8) that

$$\int_{D_T} |u|^\alpha \phi \, dx \, dt \leq \frac{1}{\lambda^{\alpha'}} \int_{D_T} \frac{|\square^2 \phi|^{\alpha'}}{\phi^{\alpha'-1}} \, dx \, dt - \frac{\alpha' \mu}{\lambda} \int_{D_T} F^0 \phi \, dx \, dt.$$

Let us note that is not difficult to the existence of test function  $\phi$ , such that

$$\phi \in \mathring{C}^4(\overline{D_T}, \partial D_T), \quad \phi|_{D_T} > 0, \quad \kappa = \int_{D_T} \frac{|\square^2 \phi|^{\alpha'}}{\phi^{\alpha'-1}} \, dx \, dt < +\infty. \quad (4.9)$$

Indeed, it is easy to verify that the function

$$\phi(x, t) = [(t^2 - |x|^2)((T - t)^2 - |x|^2)]^m$$

for sufficiently large positive  $m$  satisfies conditions (4.9).

According to the conditions in this theorem,  $F^0 \in L_2(D_T)$ ,  $\|F^0\|_{L_2(D_T)} \neq 0$ ,  $F^0 \geq 0$ , and  $\text{meas } D_T < +\infty$ . Then due to the fact that  $\phi|_{D_T} > 0$  we have

$$0 < \kappa_1 = \int_{D_T} F^0 \phi \, dx \, dt < +\infty. \quad (4.10)$$

Let us denote by  $g(\mu)$  the right side of inequality (4), which is a linear function with respect to  $\mu$ , then in view of (4.9) and (4.10) we have

$$g(\mu) < 0 \text{ for } \mu > \mu_0 \quad \text{and} \quad g(\mu) > 0 \text{ for } \mu < \mu_0, \quad (4.11)$$

where

$$g(\mu) = \frac{\kappa_0}{\lambda^{\alpha'}} - \frac{\alpha' \mu}{\lambda} \kappa_1, \quad \mu_0 = \frac{\lambda}{\alpha' \lambda^{\alpha'}} \frac{\kappa_0}{\kappa_1} > 0.$$

According to (4.11) with  $\mu > \mu_0$  the right side of inequality (4) is negative, while the left side is non-negative. This contradiction completes the proof.  $\square$

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